June 12, Week 2

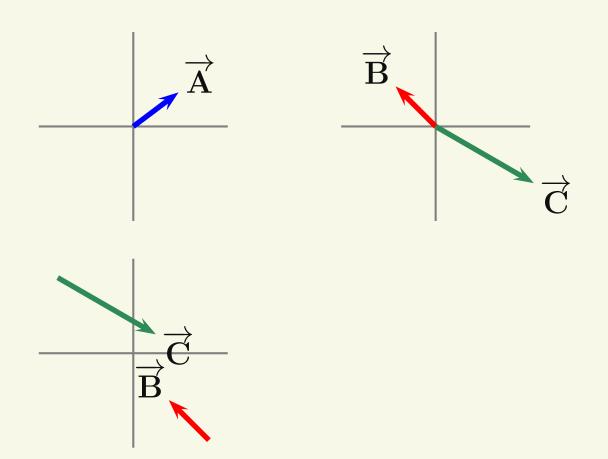
Today: Chapter 3, Vectors

Homework #2 due tomorrow

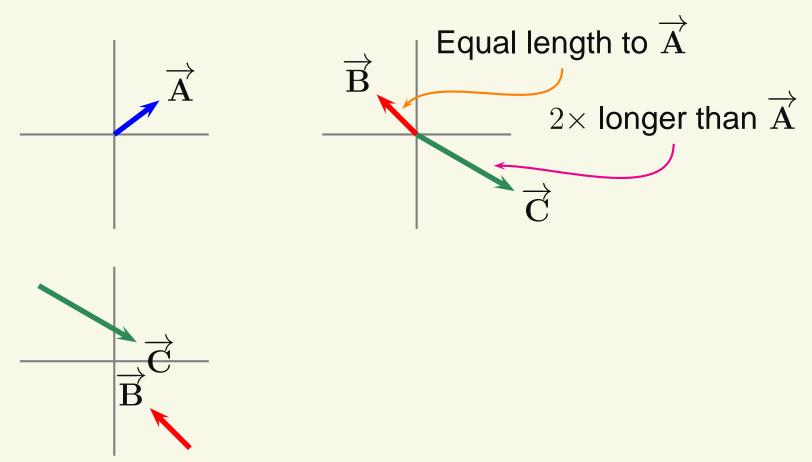
No reading quiz for Monday

Please register your clicker. (There are 2 students without registered clickers.)

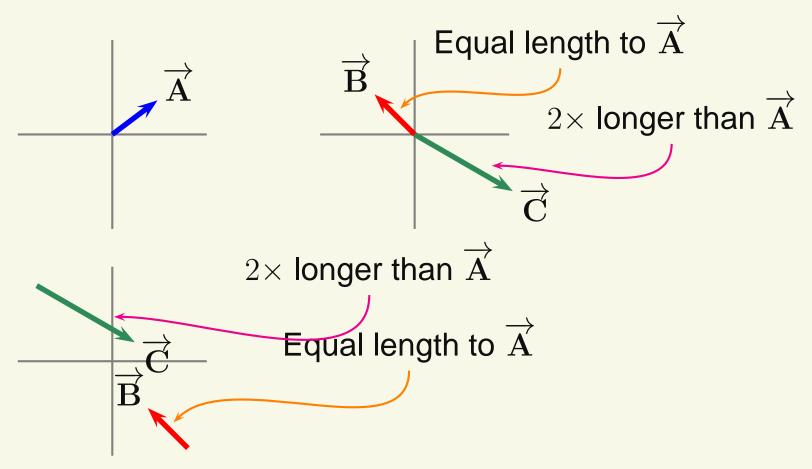
If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



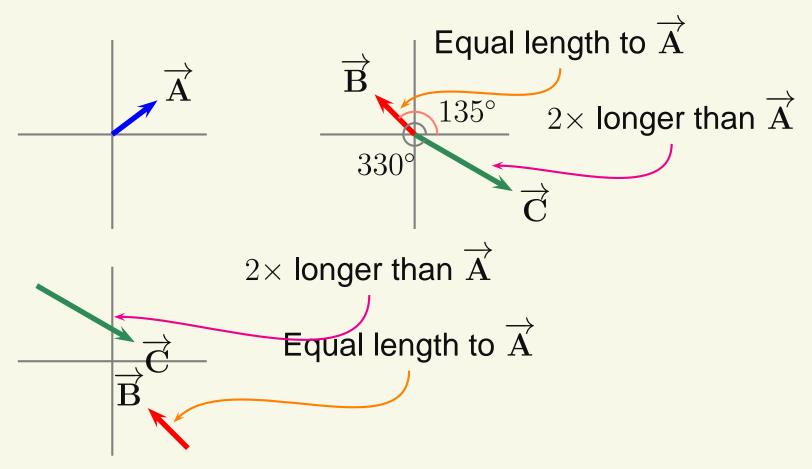
If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



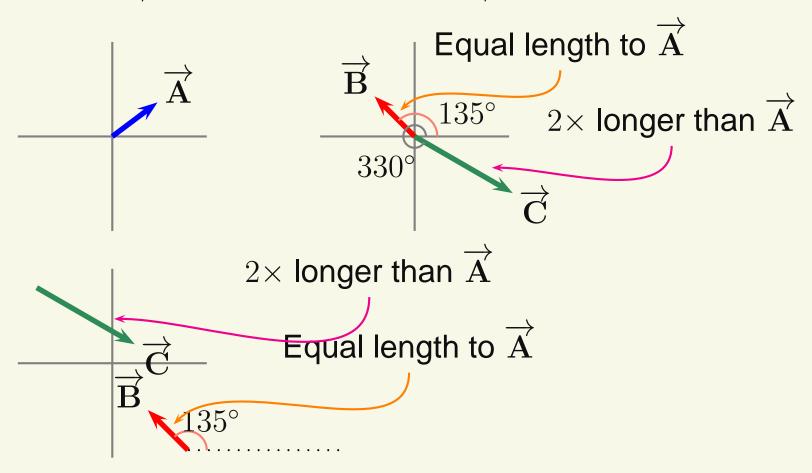
If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



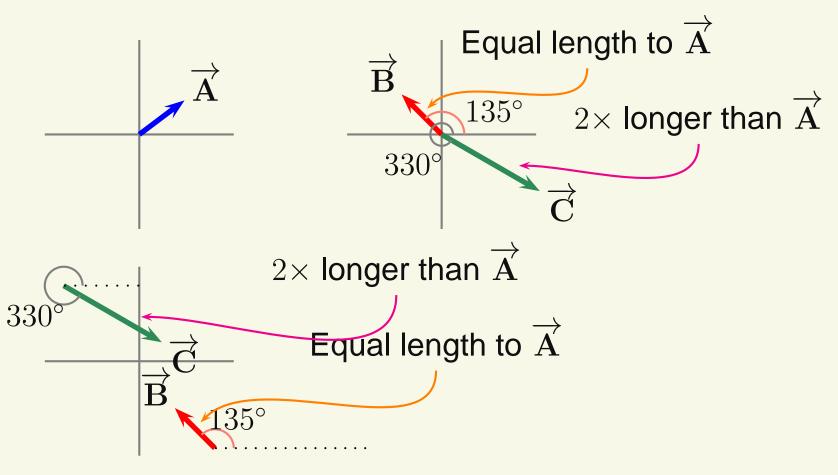
If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



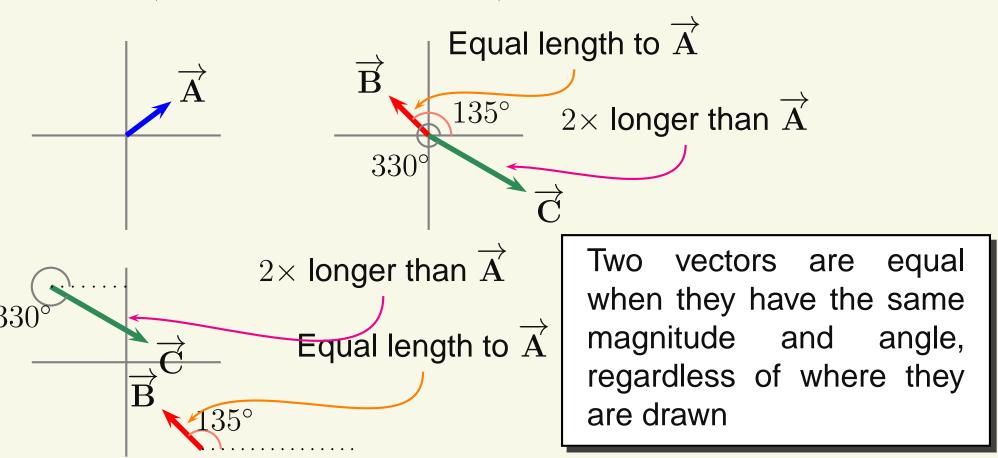
If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



If $\overrightarrow{\mathbf{A}} = 5\,m/s$ at 37° , which of the following drawing correctly shows $\overrightarrow{\mathbf{B}} = 5\,m/s$ at 135° and $\overrightarrow{\mathbf{C}} = 10\,m/s$ at 330° ?



Multiplying a vector by a scalar changes the magnitude but not the direction of a vector.

Example: $\overrightarrow{\mathbf{A}} = 5 \, m/s$ at 37° , $3\overrightarrow{\mathbf{A}} =$

Multiplying a vector by a scalar changes the magnitude but not the direction of a vector.

Example: $\overrightarrow{\mathbf{A}} = 5 \, m/s$ at 37° , $3\overrightarrow{\mathbf{A}} = 15 \, m/s$ at 37°

Multiplying a vector by a scalar changes the magnitude but not the direction of a vector.

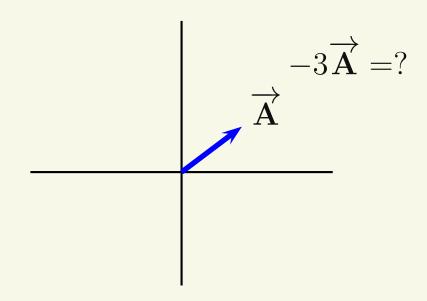
Example:
$$\overrightarrow{\mathbf{A}} = 5 \, m/s$$
 at 37° , $3\overrightarrow{\mathbf{A}} = 15 \, m/s$ at 37°

One "exception": Negative numbers change magnitude and flip direction by 180° .

Multiplying a vector by a scalar changes the magnitude but not the direction of a vector.

Example:
$$\overrightarrow{\mathbf{A}} = 5 \, m/s$$
 at 37° , $3\overrightarrow{\mathbf{A}} = 15 \, m/s$ at 37°

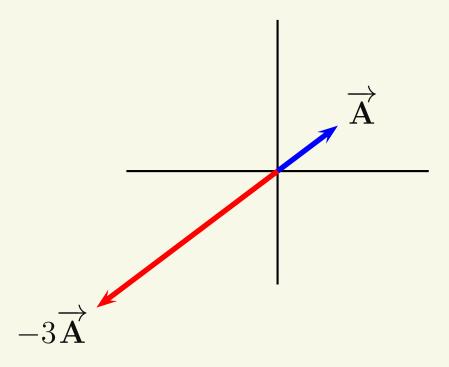
One "exception": Negative numbers change magnitude and flip direction by 180° .



Multiplying a vector by a scalar changes the magnitude but not the direction of a vector.

Example:
$$\overrightarrow{\mathbf{A}} = 5 \, m/s$$
 at 37° , $3\overrightarrow{\mathbf{A}} = 15 \, m/s$ at 37°

One "exception": Negative numbers change magnitude and flip direction by 180° .

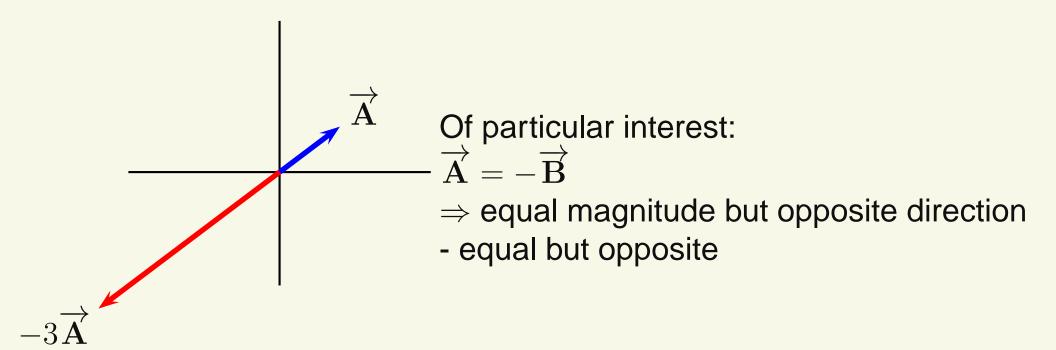


Vectors

Multiplying a vector by a scalar changes the magnitude but not the direction of a vector.

Example:
$$\overrightarrow{\mathbf{A}} = 5 \, m/s$$
 at 37° , $3\overrightarrow{\mathbf{A}} = 15 \, m/s$ at 37°

One "exception": Negative numbers change magnitude and flip direction by 180° .



Vectors

<u>Vector Addition</u> - The net result of two or more vectors, *i.e.*, taking direction into account while adding.

<u>Vector Addition</u> - The net result of two or more vectors, *i.e.*, taking direction into account while adding.

There are two methods of adding vectors - the graphical and component methods.

<u>Vector Addition</u> - The net result of two or more vectors, *i.e.*, taking direction into account while adding.

There are two methods of adding vectors - the graphical and component methods.

Graphical Addition - Drawing pictures and placing the vectors, "tip-to-tail" in order to determine the vector sum.

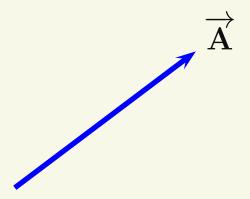
<u>Vector Addition</u> - The net result of two or more vectors, *i.e.*, taking direction into account while adding.

There are two methods of adding vectors - the graphical and component methods.

Graphical Addition - Drawing pictures and placing the vectors, "tip-to-tail" in order to determine the vector sum.

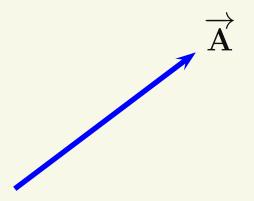
Component Addition - Uses trigonometry to calculate the vector sum.

Add the following vectors.





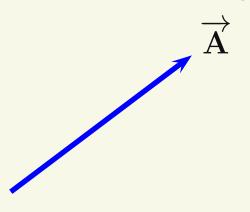
Add the following vectors.



Vectors can be drawn at any point as long as the magnitude and direction don't change

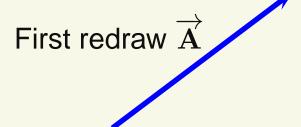


Add the following vectors.

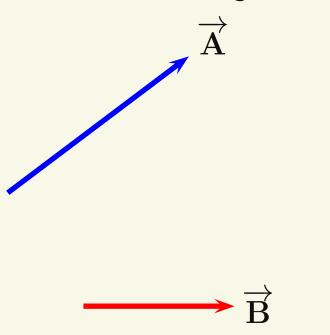


Vectors can be drawn at any point as long as the magnitude and direction don't change

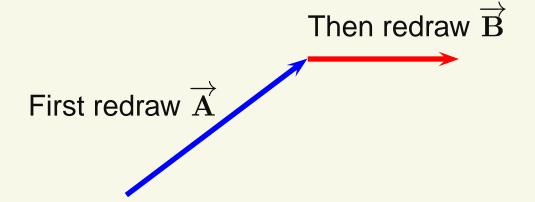




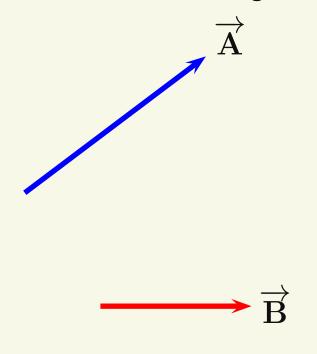
Add the following vectors.



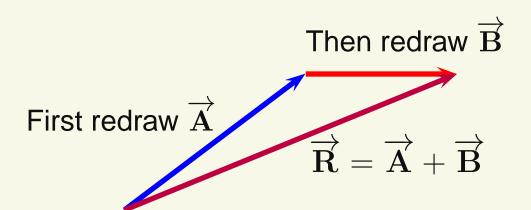
Vectors can be drawn at any point as long as the magnitude and direction don't change



Add the following vectors.

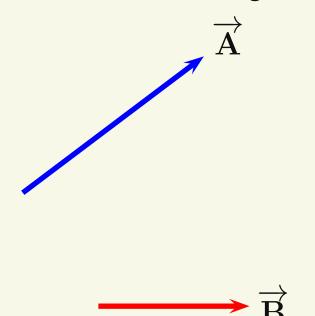


Vectors can be drawn at any point as long as the magnitude and direction don't change

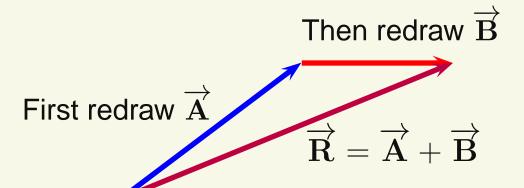


The vector sum or resultant, $\overrightarrow{\mathbf{R}}$, goes from the remaining tail to tip.

Add the following vectors.



Vectors can be drawn at any point as long as the magnitude and direction don't change



A carefully drawn picture can give magnitude and direction of $\overrightarrow{\mathbf{R}}$. Simply use a ruler and protractor

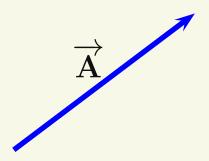
The vector sum or resultant, $\overrightarrow{\mathbf{R}}$, goes from the remaining tail to tip.

You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$

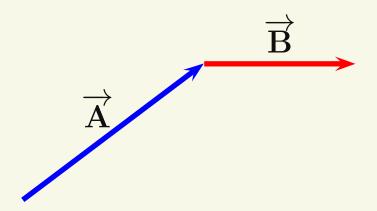
You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$



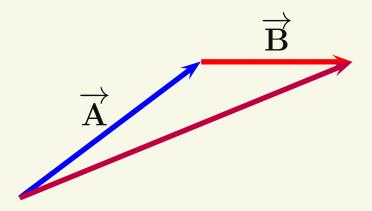
You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$



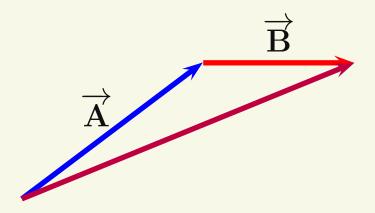
You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$



You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$

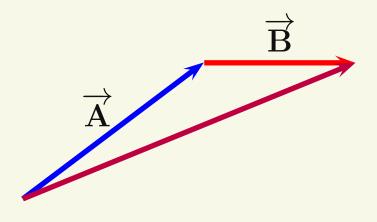


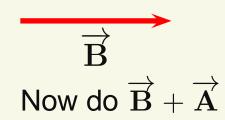
First do
$$\overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}}$$

Now do
$$\overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$

You can add vectors in either order and the answer is the same!

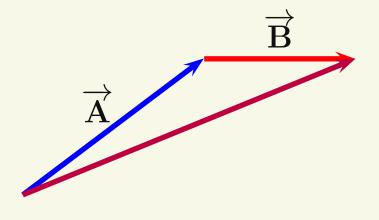
$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$



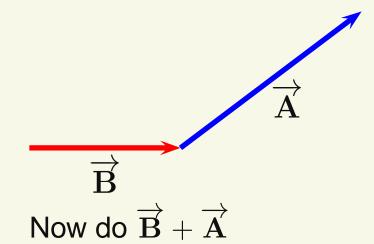


You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$

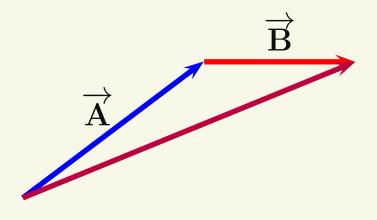


First do $\overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}}$

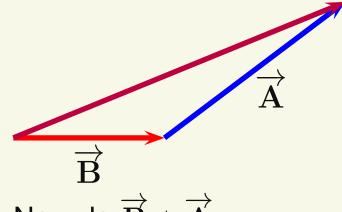


You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$

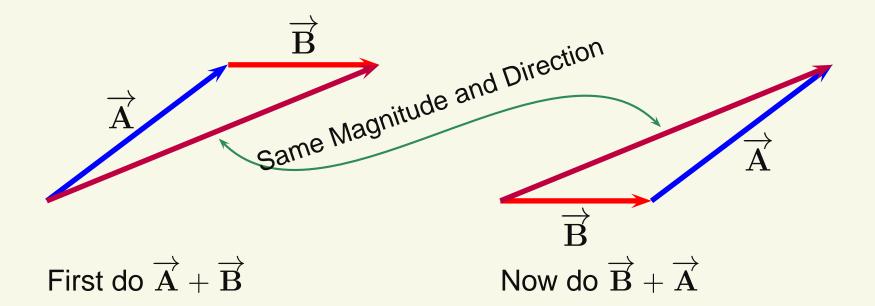


First do $\overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}}$



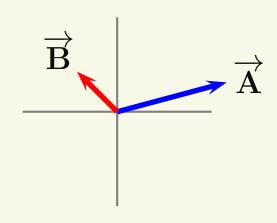
You can add vectors in either order and the answer is the same!

$$\overrightarrow{\mathbf{R}} = \overrightarrow{\mathbf{A}} + \overrightarrow{\mathbf{B}} = \overrightarrow{\mathbf{B}} + \overrightarrow{\mathbf{A}}$$



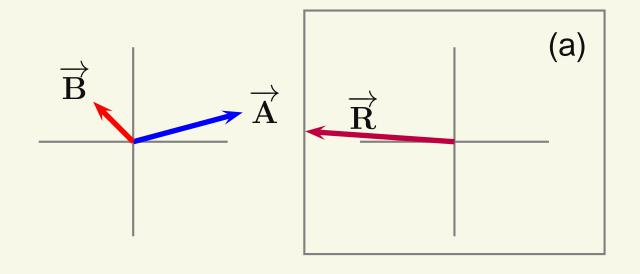
Vector Addition Exercise

For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R}=\overrightarrow{A}+\overrightarrow{B}$?



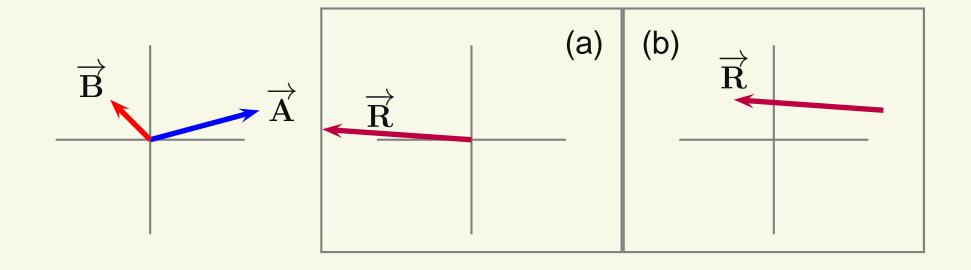
Vector Addition Exercise

For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R} = \overrightarrow{A} + \overrightarrow{B}$?

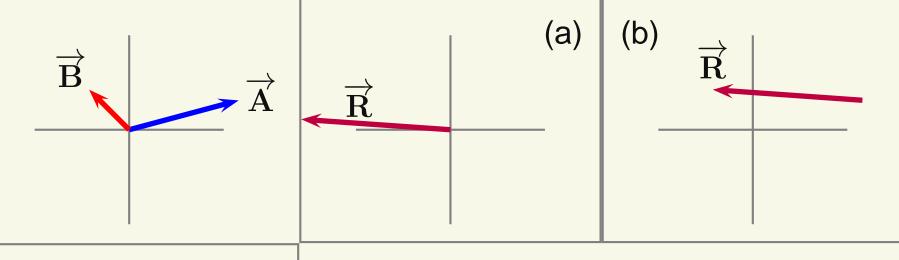


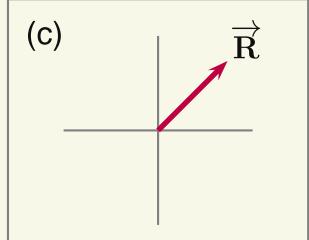
Vector Addition Exercise

For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R}=\overrightarrow{A}+\overrightarrow{B}$?

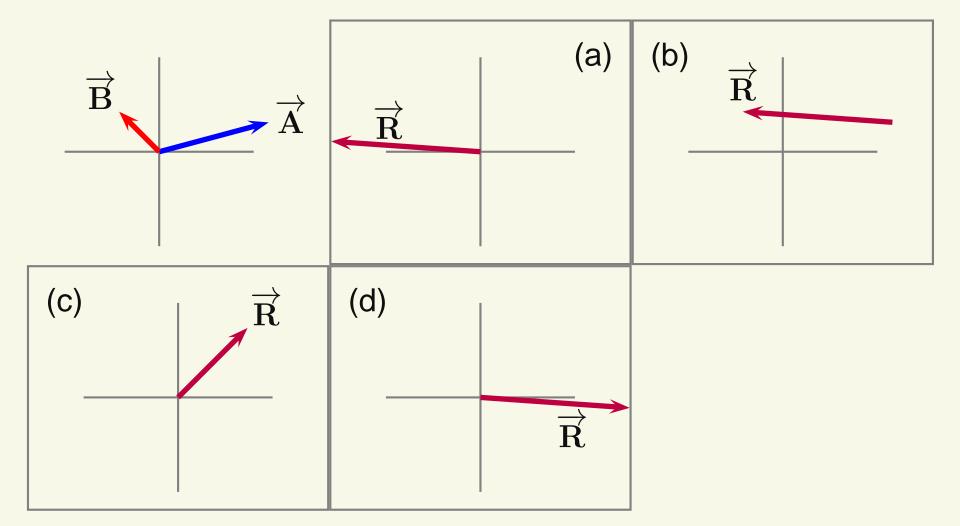


For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R}=\overrightarrow{A}+\overrightarrow{B}$?

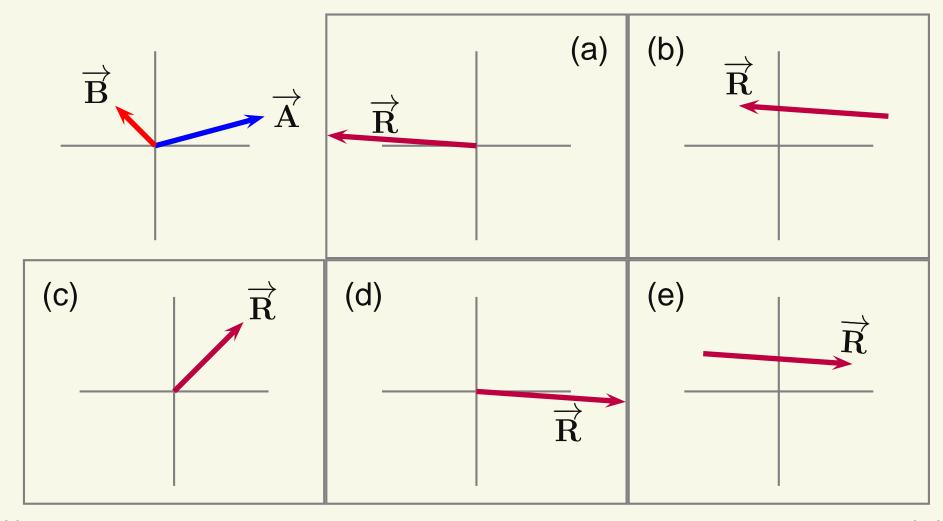




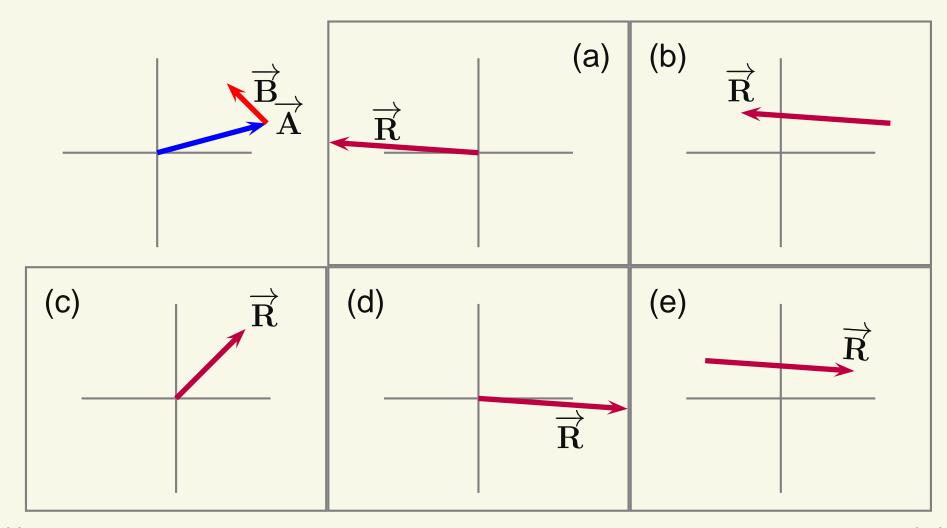
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R} = \overrightarrow{A} + \overrightarrow{B}$?



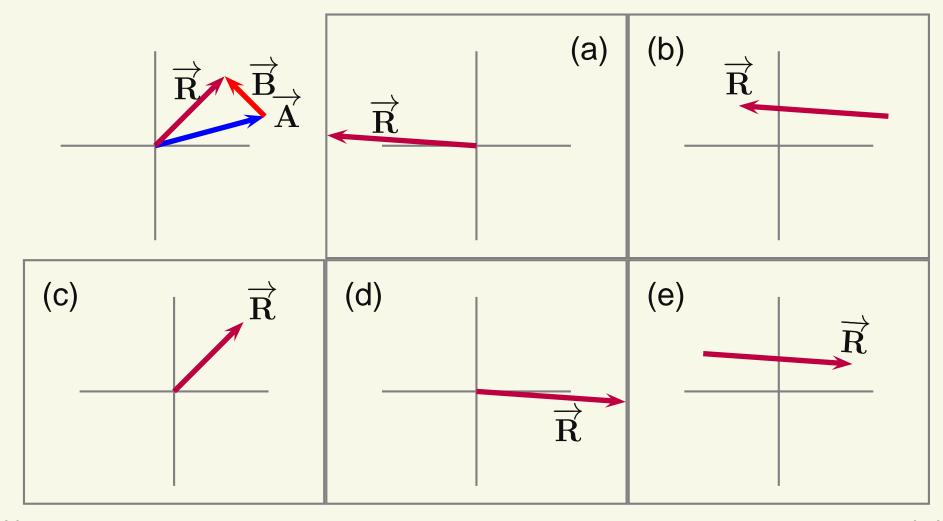
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R}=\overrightarrow{A}+\overrightarrow{B}$?



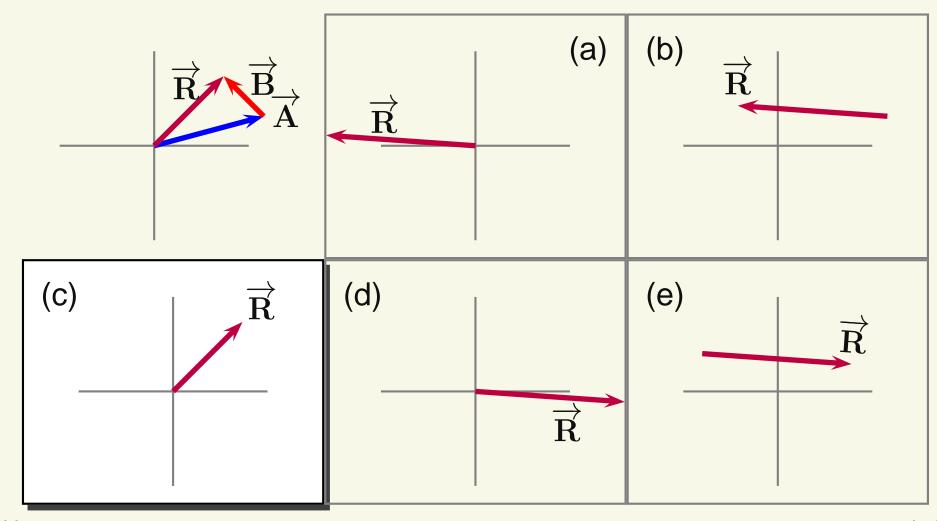
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R} = \overrightarrow{A} + \overrightarrow{B}$?



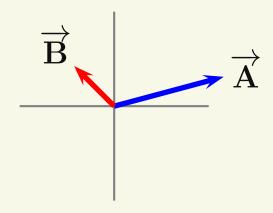
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R} = \overrightarrow{A} + \overrightarrow{B}$?



For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{R} , where $\overrightarrow{R} = \overrightarrow{A} + \overrightarrow{B}$?

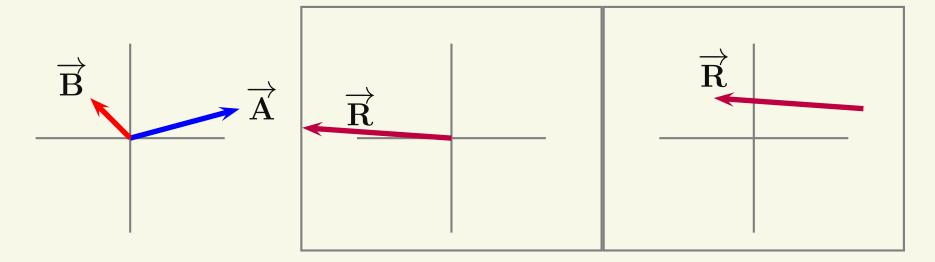


The previous example contained two vector subtractions.

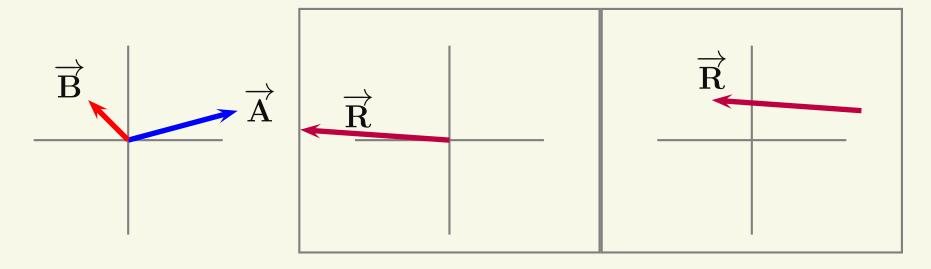


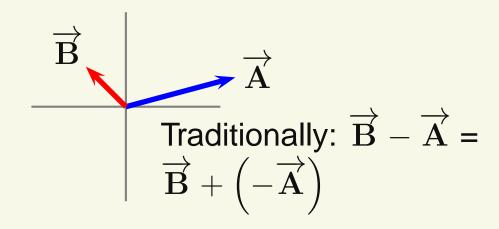
The previous example contained two vector subtractions.

These are both $\overrightarrow{\mathbf{B}} - \overrightarrow{\mathbf{A}}$

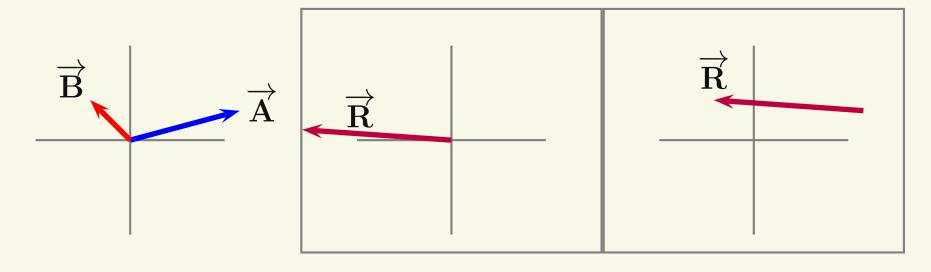


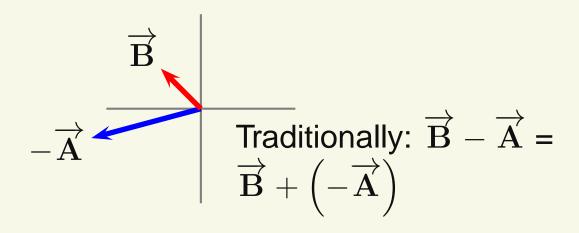
The previous example contained two vector subtractions.



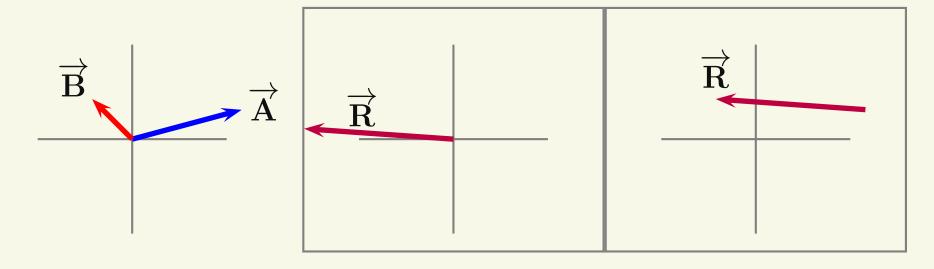


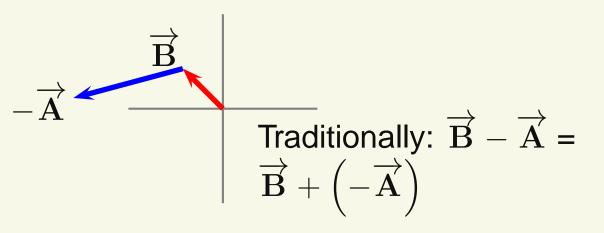
The previous example contained two vector subtractions.



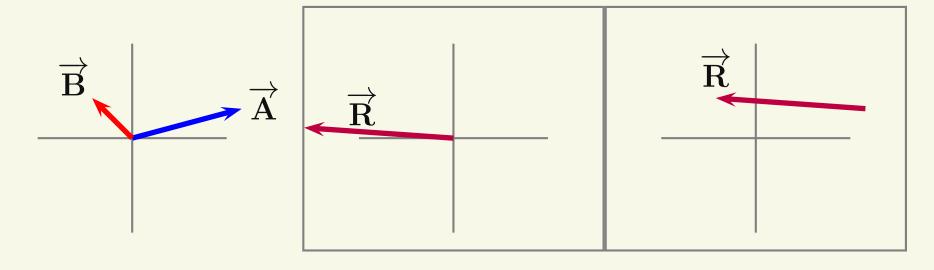


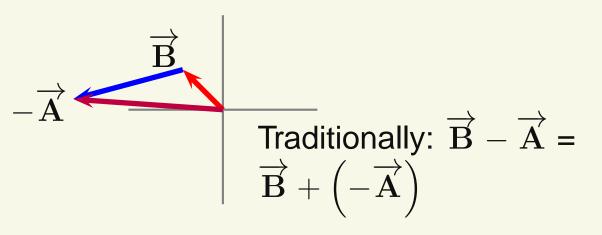
The previous example contained two vector subtractions.



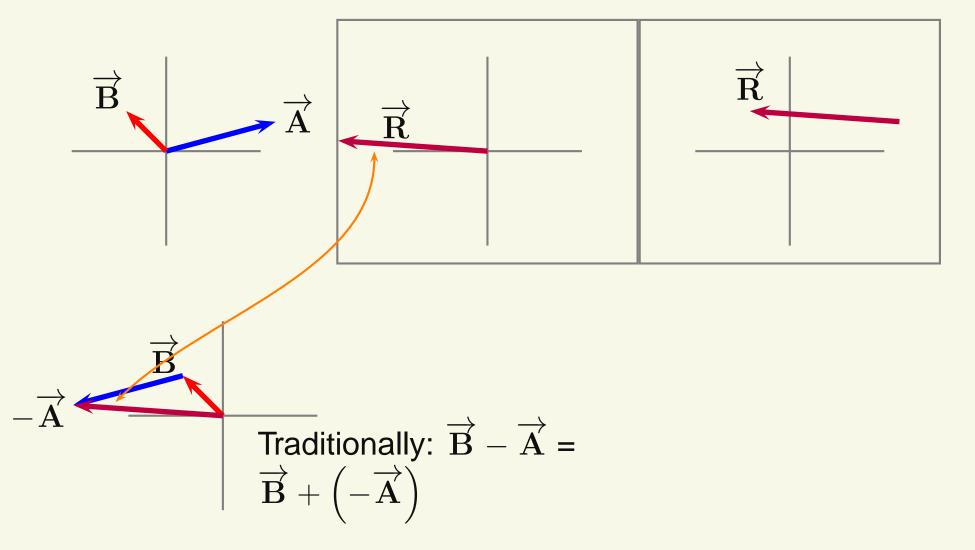


The previous example contained two vector subtractions.

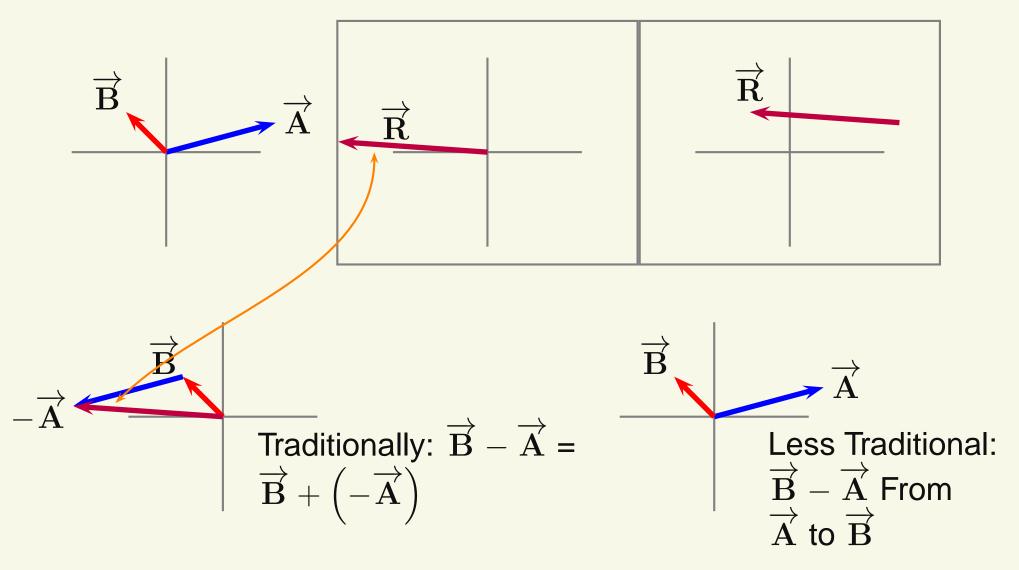




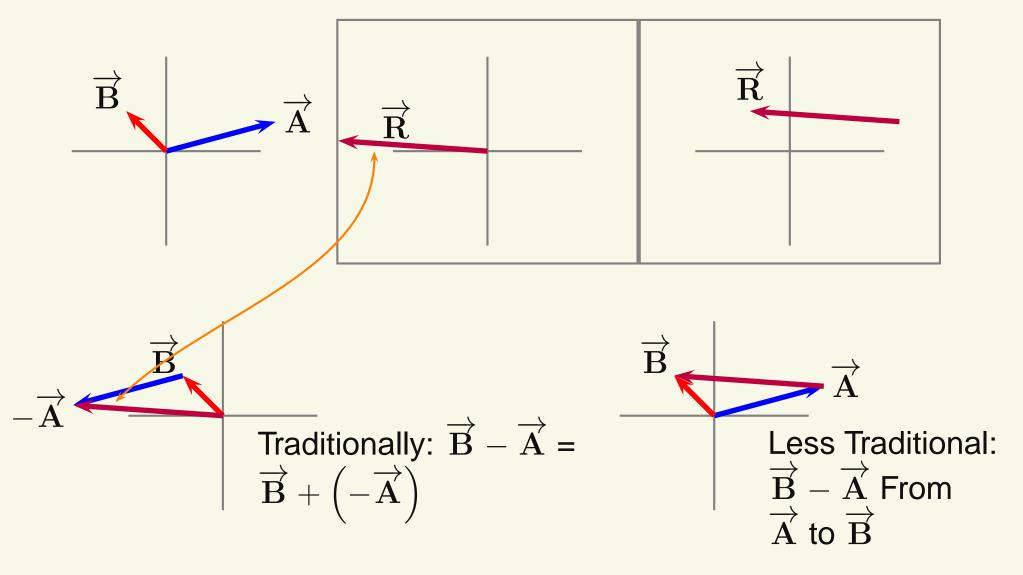
The previous example contained two vector subtractions.



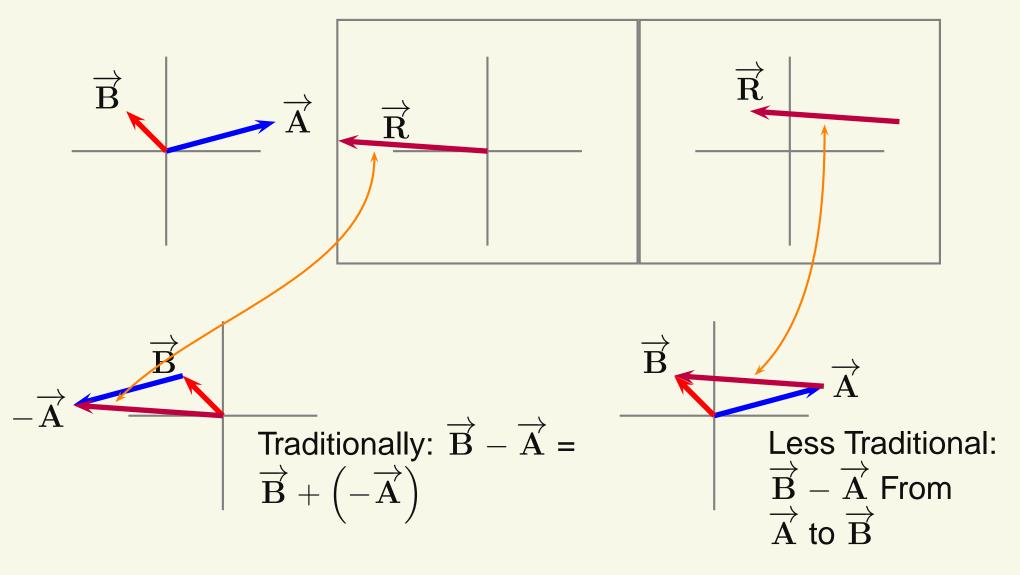
The previous example contained two vector subtractions.



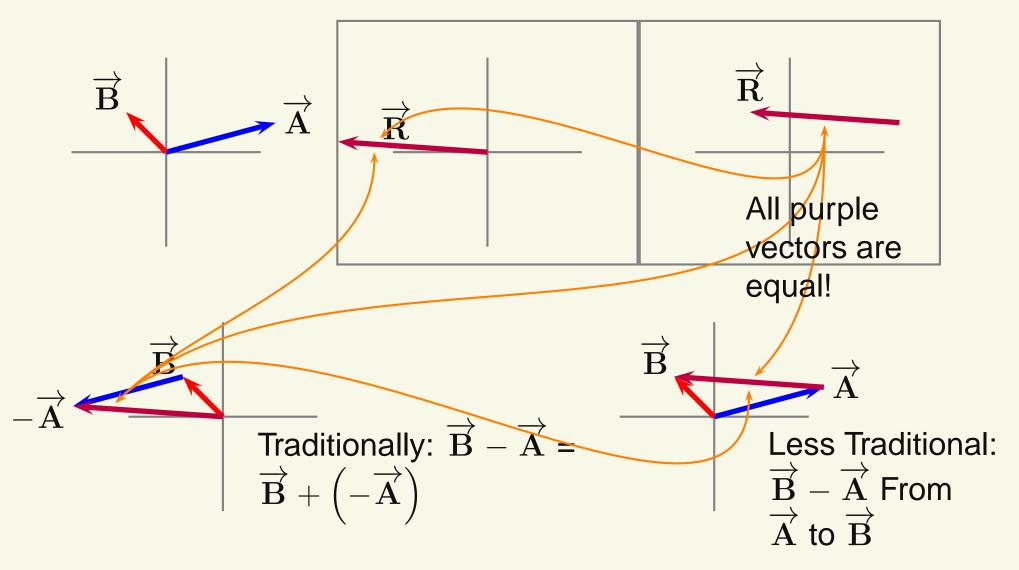
The previous example contained two vector subtractions.



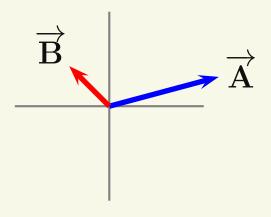
The previous example contained two vector subtractions.



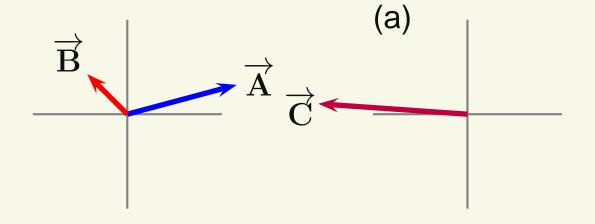
The previous example contained two vector subtractions.



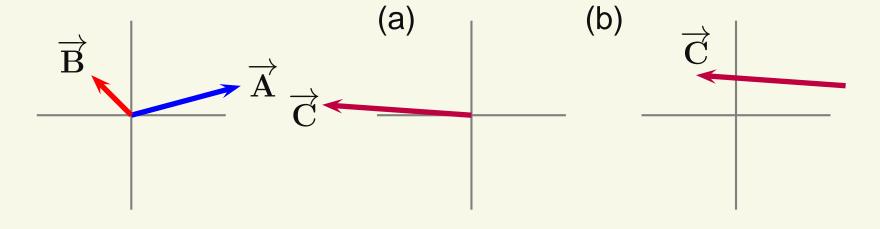
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



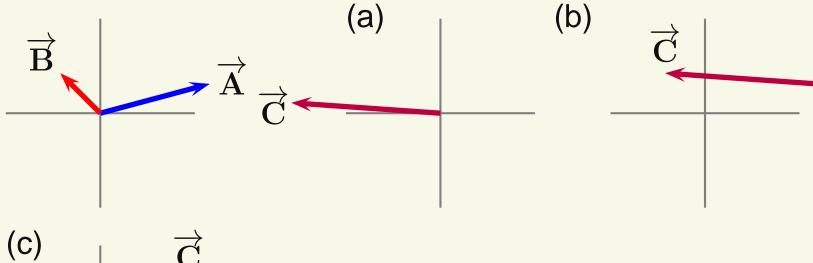
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?

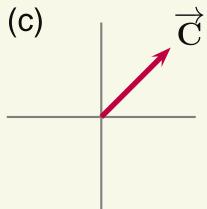


For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?

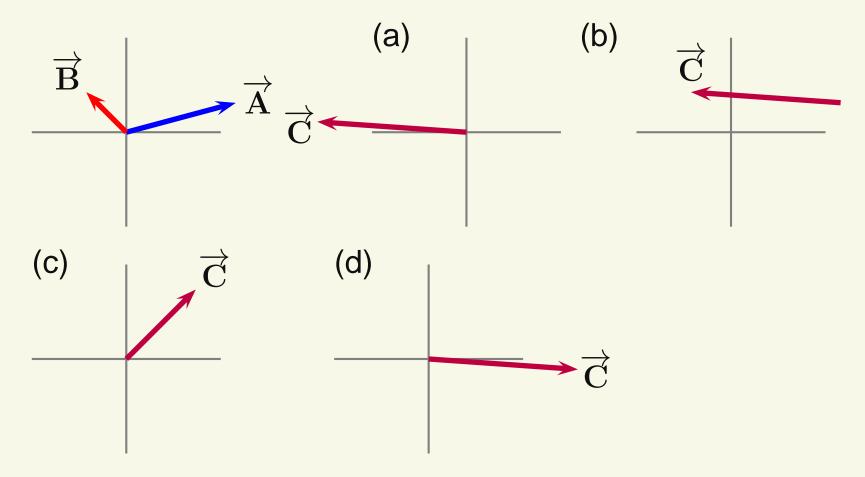


For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?

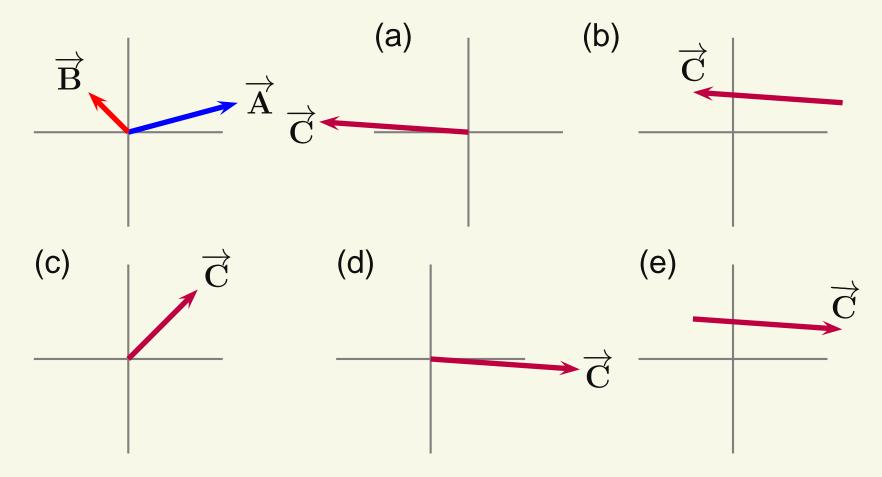




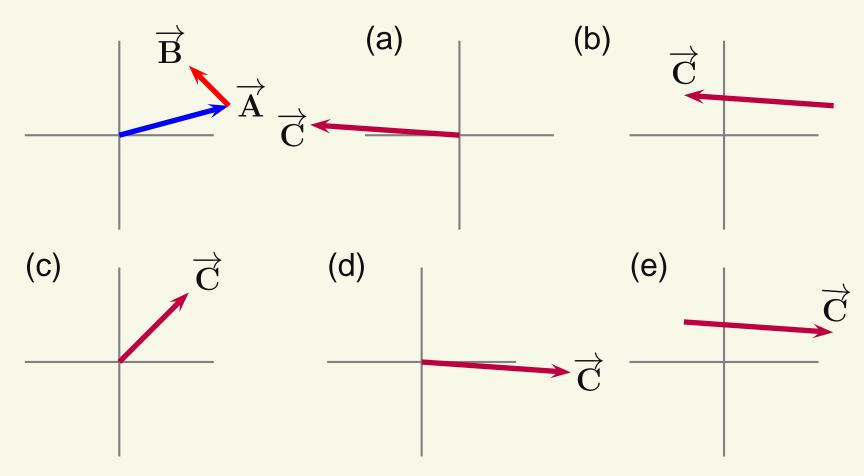
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



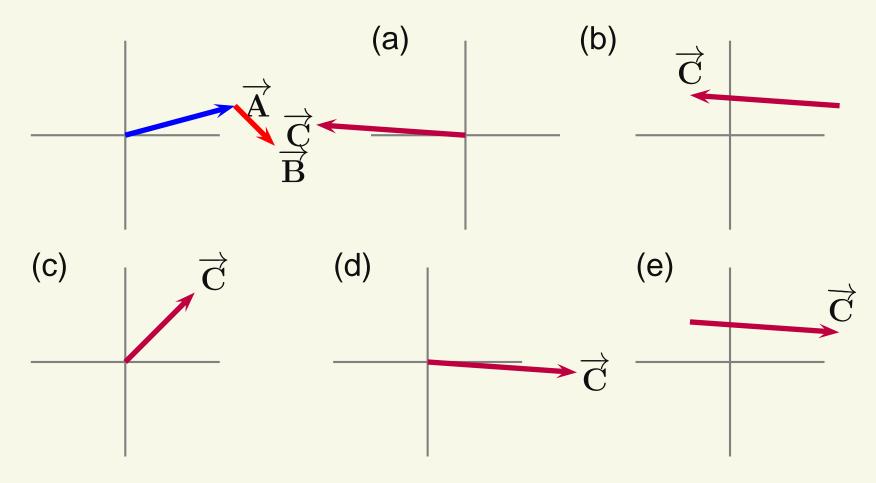
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



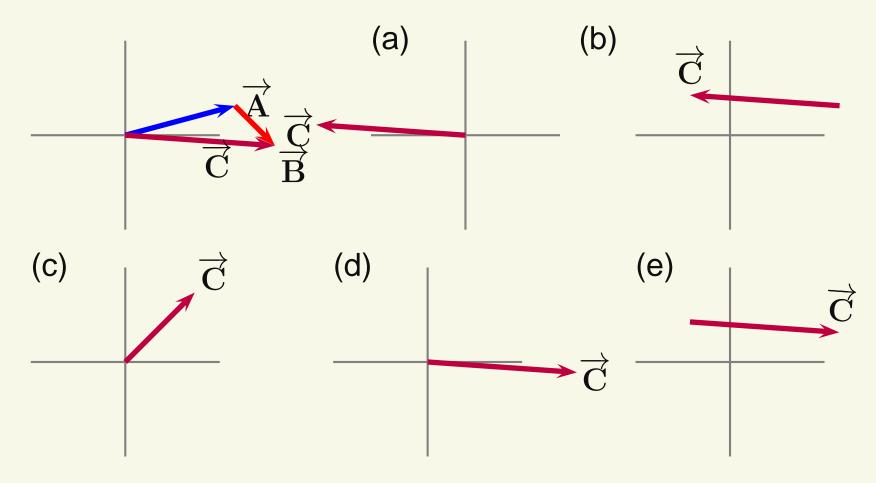
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



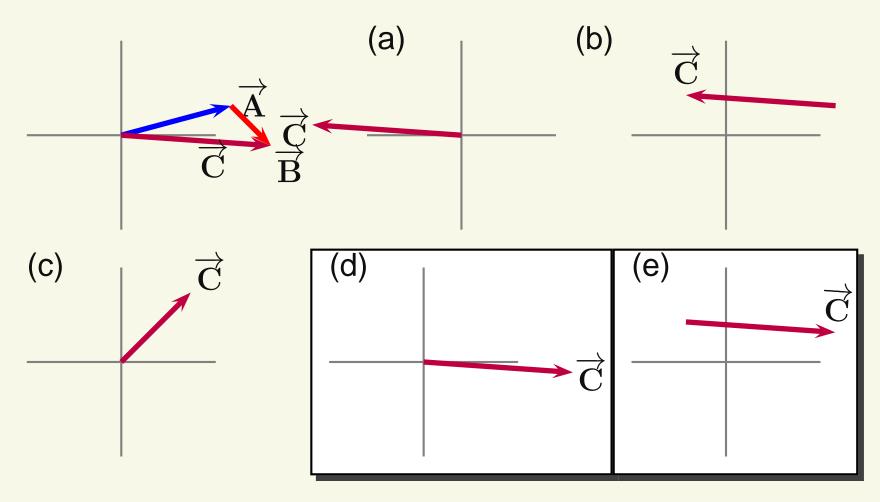
For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



For the vectors \overrightarrow{A} and \overrightarrow{B} , which of the following correctly shows \overrightarrow{C} , where $\overrightarrow{C}=\overrightarrow{A}-\overrightarrow{B}$?



Physics uses many vector subtractions.

Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

Physics uses many vector subtractions.

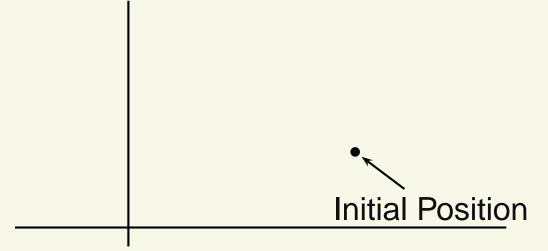
The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

 $\Rightarrow \overrightarrow{\Delta \mathbf{r}}$ points from $\overrightarrow{\mathbf{r}}_i$ to $\overrightarrow{\mathbf{r}}_f$.

Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

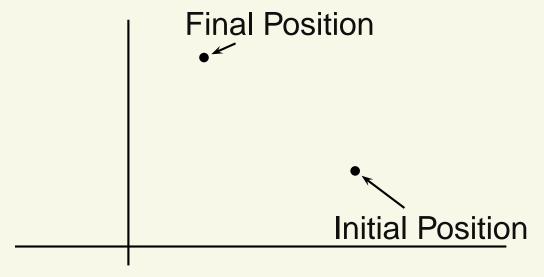
$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

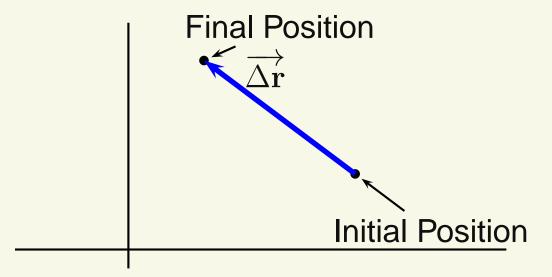
$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

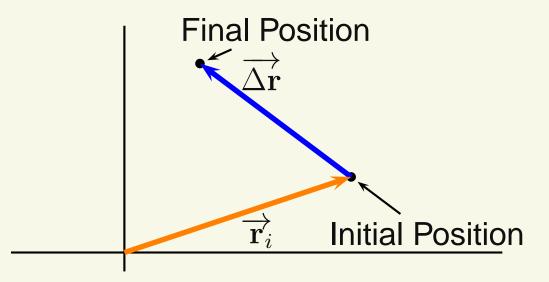
$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

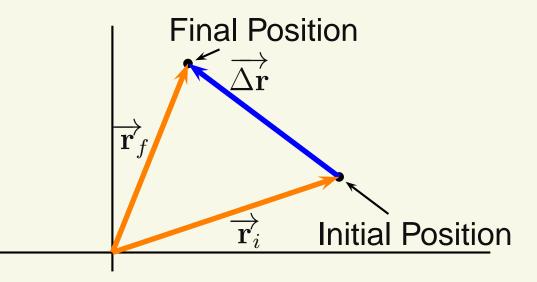
$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

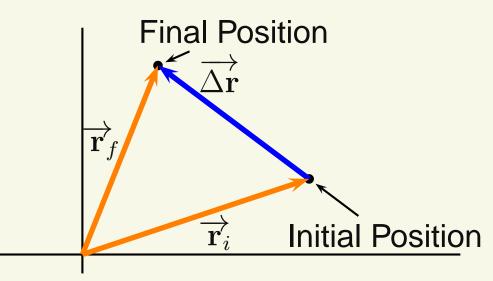
 $\Rightarrow \overrightarrow{\Delta r}$ points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



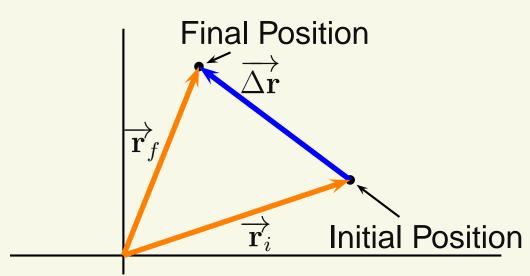
Position vectors are from the origin.

The Position and Velocity Vectors

Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Position vectors are from the origin.

The average velocity vector is parallel to $\overrightarrow{\Delta \mathbf{r}}$ since $\overrightarrow{\mathbf{v}}_{av} = \frac{\overrightarrow{\Delta \mathbf{r}}}{\Delta t}$

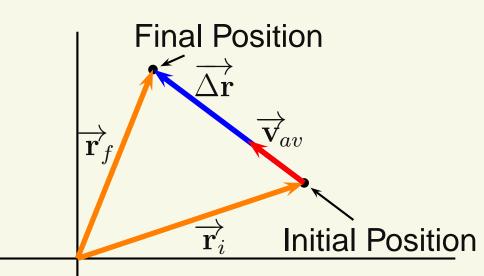
(Textbook is not careful here and just calls it the velocity!)

The Position and Velocity Vectors

Physics uses many vector subtractions.

The displacement vector $\overrightarrow{\Delta \mathbf{r}} = \overrightarrow{\mathbf{r}}_f - \overrightarrow{\mathbf{r}}_i$ is a vector subtraction.

$$\Rightarrow \overrightarrow{\Delta r}$$
 points from \overrightarrow{r}_i to \overrightarrow{r}_f .



Position vectors are from the origin.

The average velocity vector is parallel to $\overrightarrow{\Delta \mathbf{r}}$ since $\overrightarrow{\mathbf{v}}_{av} = \frac{\overrightarrow{\Delta \mathbf{r}}}{\Delta t}$

(Textbook is not careful here and just calls it the velocity!)

Acceleration is the rate at which the *velocity* changes

Acceleration is the rate at which the *velocity* changes

A change in speed *OR* direction means an object is accelerating

Acceleration is the rate at which the *velocity* changes

A change in speed *OR* direction means an object is accelerating

The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$

Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$

1•

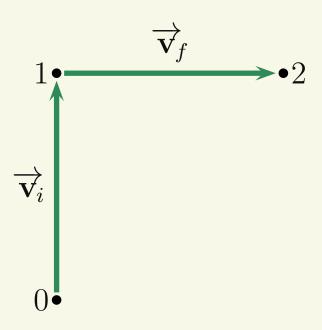
•2

 $0 \bullet$

Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$

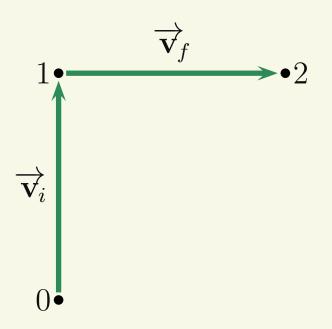


Vectors

Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

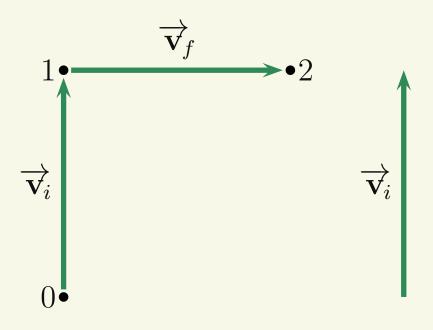
The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$



Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

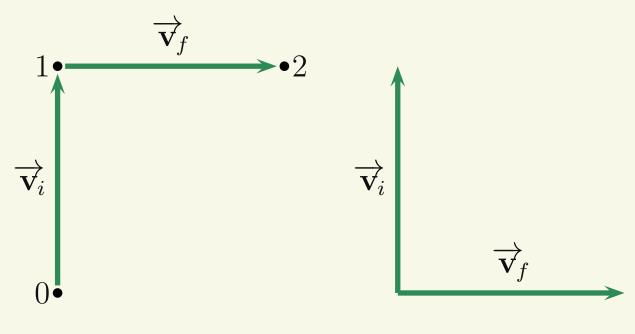
The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$



Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

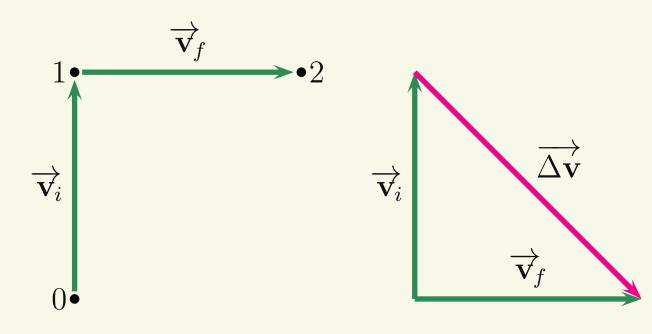
The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$



Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

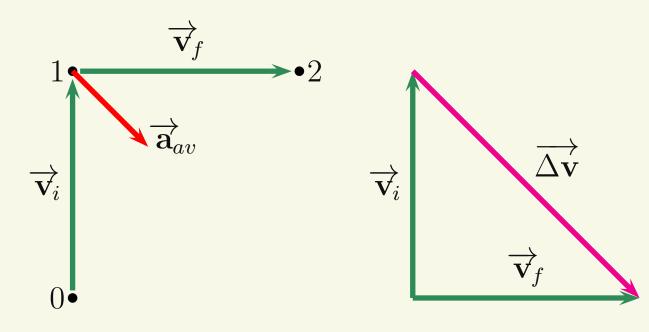
The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$



Acceleration is the rate at which the velocity changes

A change in speed *OR* direction means an object is accelerating

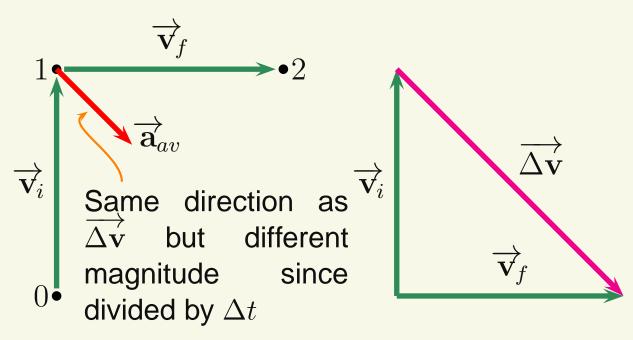
The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$



Acceleration is the rate at which the *velocity* changes

A change in speed *OR* direction means an object is accelerating

The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same direction as $\overrightarrow{\Delta \mathbf{v}}$

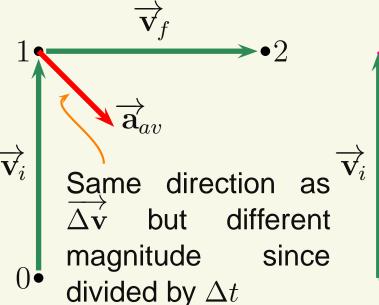


Acceleration is the rate at which the velocity changes

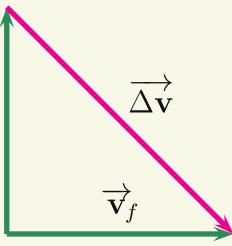
A change in speed *OR* direction means an object is accelerating

The average acceleration vector: $\overrightarrow{\mathbf{a}}_{av} = \frac{\overrightarrow{\Delta \mathbf{v}}}{\Delta t} \Rightarrow \overrightarrow{\mathbf{a}}_{av}$ in same

direction as $\overrightarrow{\Delta \mathbf{v}}$



Acceleration can be in a completely different direction than the motion

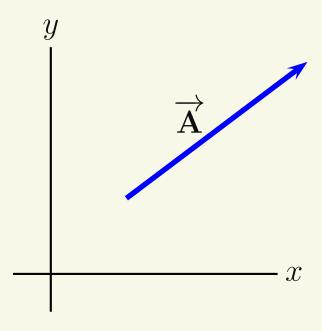


From now on, we'll use the familiar Cartesian coordinate system, (x,y).

The components of a vector are the "pieces" of the vector parallel to the x and y axes.

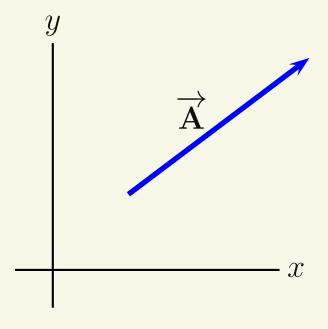
From now on, we'll use the familiar Cartesian coordinate system, (x,y).

The <u>components</u> of a vector are the "pieces" of the vector parallel to the x and y axes.



From now on, we'll use the familiar Cartesian coordinate system, (x,y).

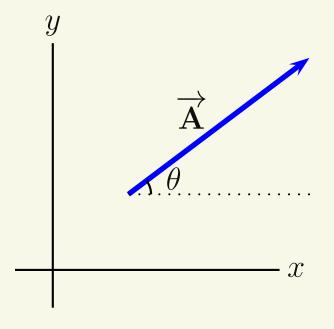
The <u>components</u> of a vector are the "pieces" of the vector parallel to the x and y axes.



Mathematically, the components are the horizontal and vertical lengths from tip to tail.

From now on, we'll use the familiar Cartesian coordinate system, (x,y).

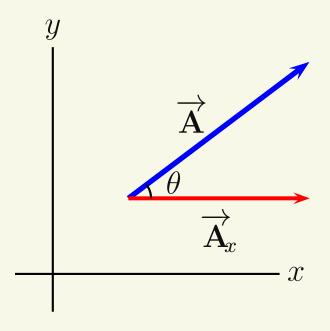
The components of a vector are the "pieces" of the vector parallel to the x and y axes.



Mathematically, the components are the horizontal and vertical lengths from tip to tail.

From now on, we'll use the familiar Cartesian coordinate system, (x,y).

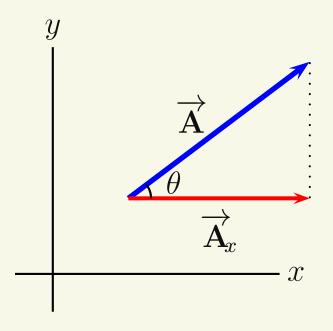
The <u>components</u> of a vector are the "pieces" of the vector parallel to the x and y axes.



Mathematically, the components are the horizontal and vertical lengths from tip to tail.

From now on, we'll use the familiar Cartesian coordinate system, (x,y).

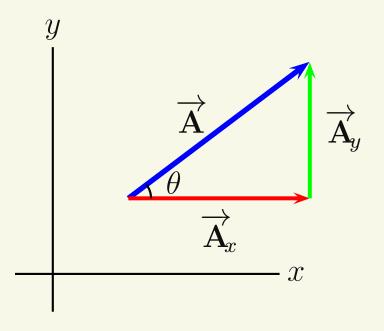
The components of a vector are the "pieces" of the vector parallel to the x and y axes.



Mathematically, the components are the horizontal and vertical lengths from tip to tail.

From now on, we'll use the familiar Cartesian coordinate system, (x,y).

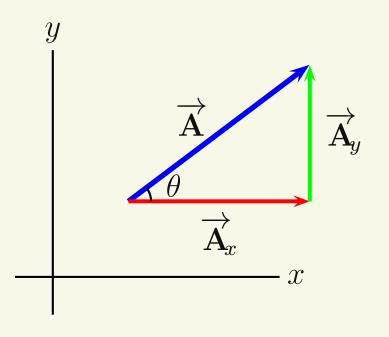
The <u>components</u> of a vector are the "pieces" of the vector parallel to the x and y axes.



Mathematically, the components are the horizontal and vertical lengths from tip to tail.

From now on, we'll use the familiar Cartesian coordinate system, (x,y).

The components of a vector are the "pieces" of the vector parallel to the x and y axes.

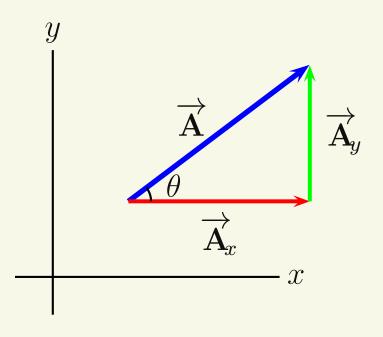


Mathematically, the components are the horizontal and vertical lengths from tip to tail.

 $\overrightarrow{\mathbf{A}}_{\!x}, \overrightarrow{\mathbf{A}}_{\!y}$ are the vector components.

From now on, we'll use the familiar Cartesian coordinate system, (x,y).

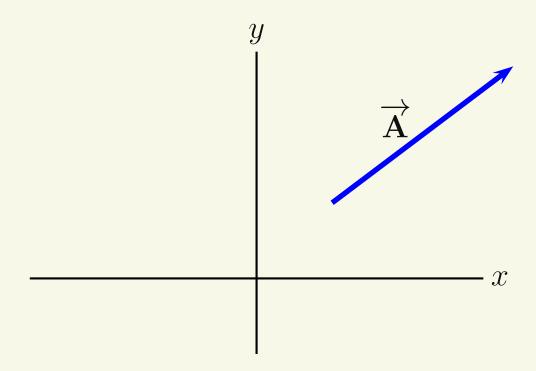
The components of a vector are the "pieces" of the vector parallel to the x and y axes.

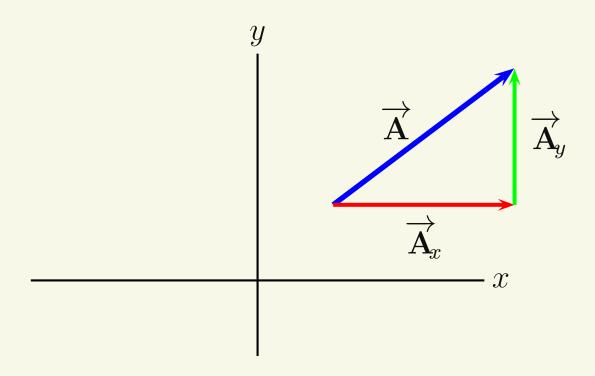


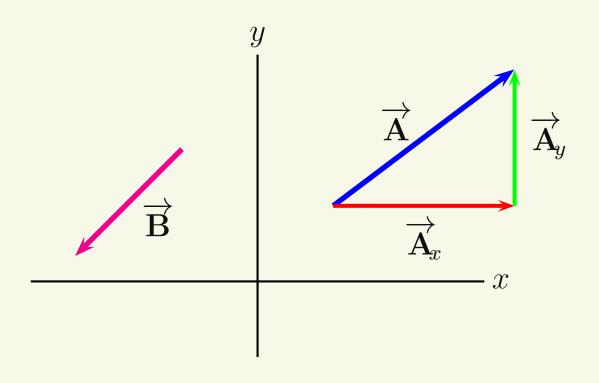
Mathematically, the components are the horizontal and vertical lengths from tip to tail.

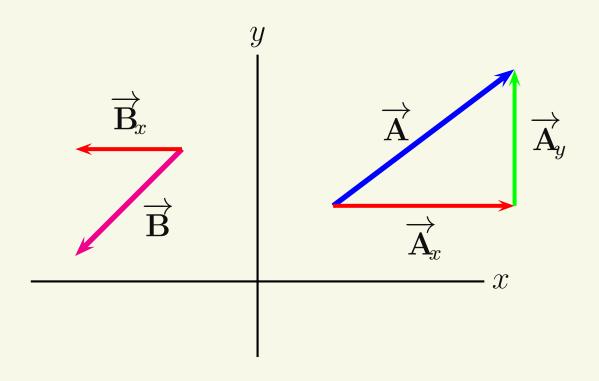
 $\overrightarrow{\mathbf{A}}_{\!\!x}, \overrightarrow{\mathbf{A}}_{\!\!y}$ are the vector components.

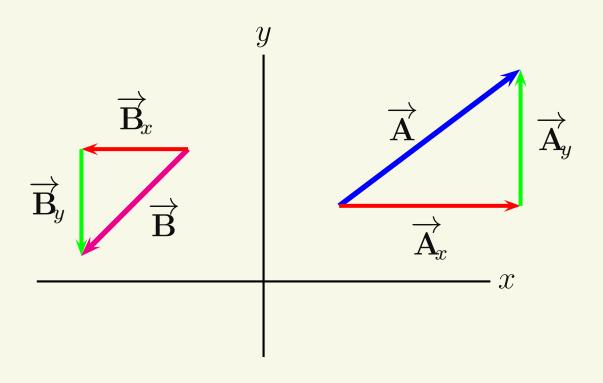
The components and the original vector are related by vector addition: $\overrightarrow{\mathbf{A}}_x + \overrightarrow{\mathbf{A}}_y = \overrightarrow{\mathbf{A}}$.

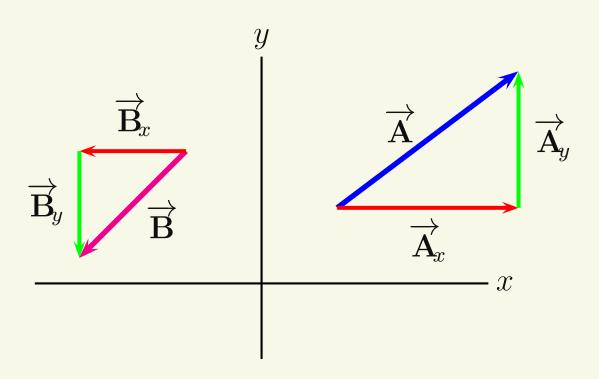




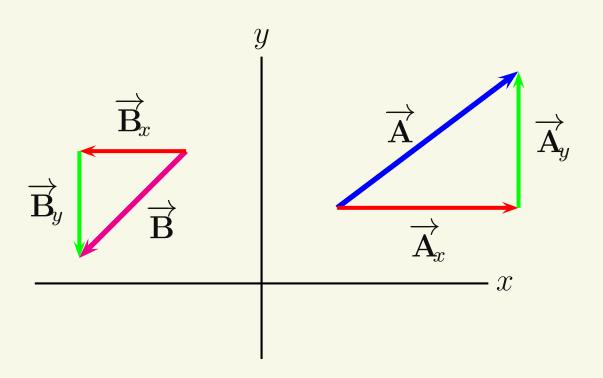








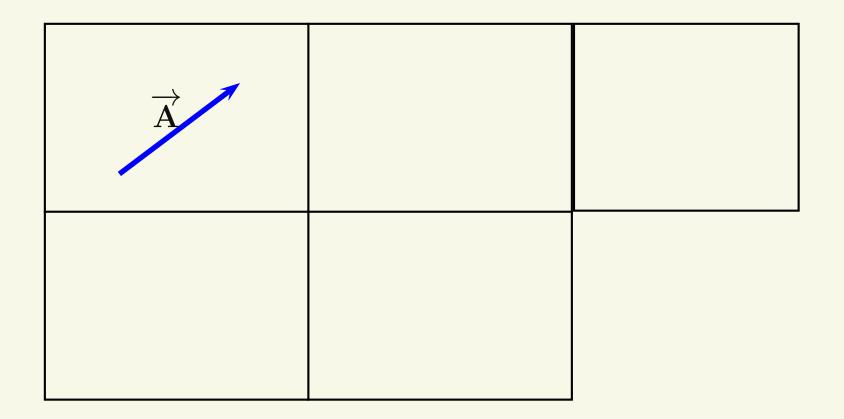
 $\overrightarrow{\mathbf{A}}_{x}, \overrightarrow{\mathbf{A}}_{y}, \overrightarrow{\mathbf{B}}_{x}, \overrightarrow{\mathbf{B}}_{y} = \text{Vector Components}$



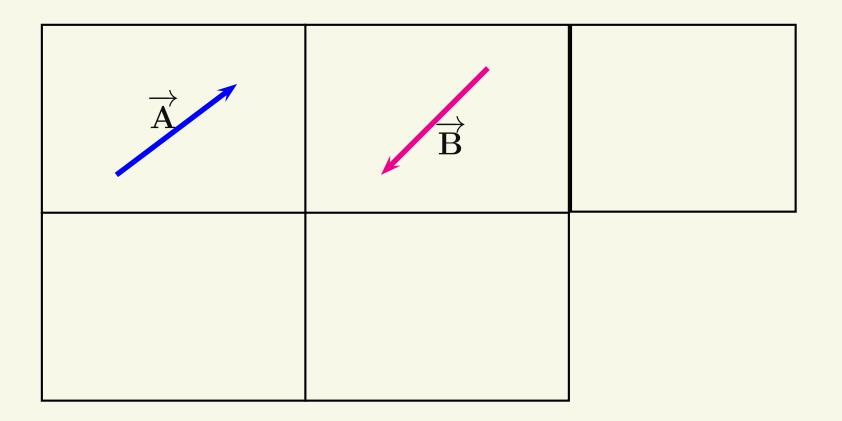
 $\overrightarrow{A}_x, \overrightarrow{A}_y, \overrightarrow{B}_x, \overrightarrow{B}_y = \text{Vector Components}$ $A_x, A_y, B_x, B_y \text{ and their signs } = \text{Scalar Components}$

Which of the following vectors has negative x and positive y scalar components?

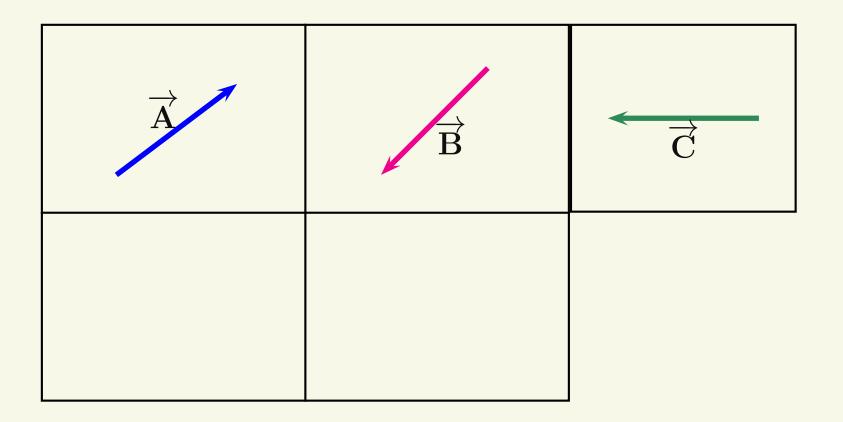
Which of the following vectors has negative x and positive y scalar components?



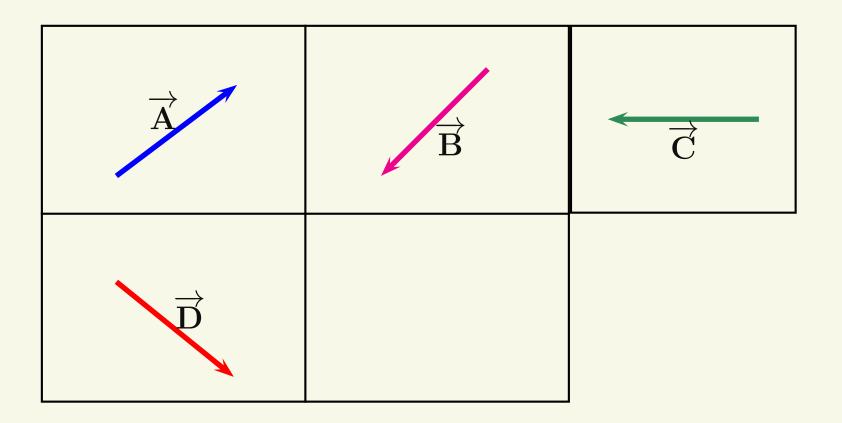
Which of the following vectors has negative \boldsymbol{x} and positive \boldsymbol{y} scalar components?



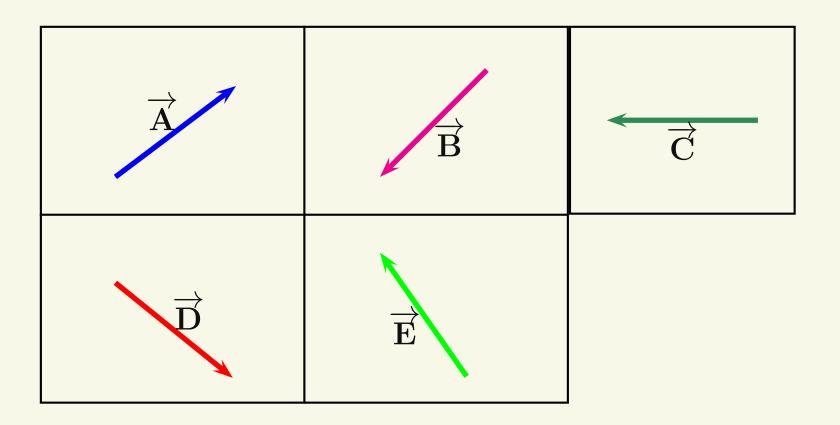
Which of the following vectors has negative x and positive y scalar components?



Which of the following vectors has negative x and positive y scalar components?

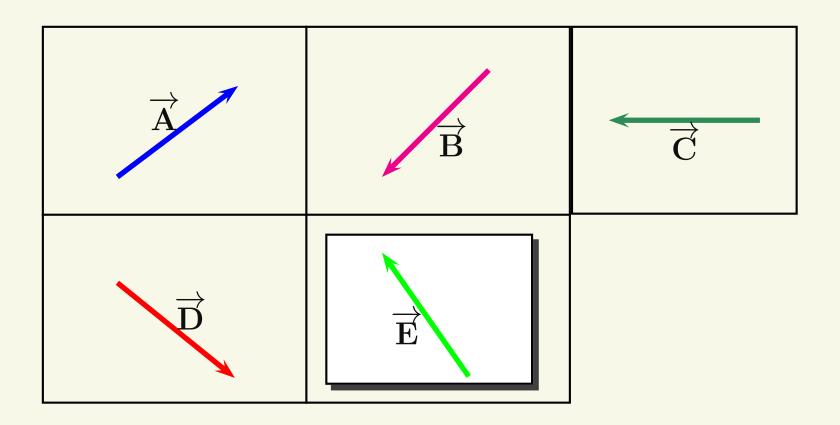


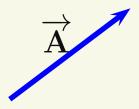
Which of the following vectors has negative x and positive y scalar components?

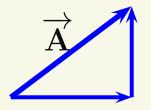


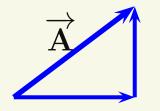
Scalar Component Exercise

Which of the following vectors has negative x and positive y scalar components?

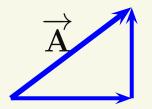




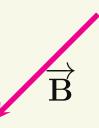


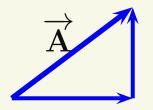


 A_x positive A_y positive

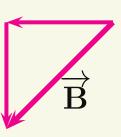


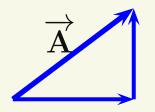
 A_x positive A_y positive



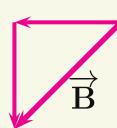


 A_x positive A_y positive





 A_x positive A_y positive

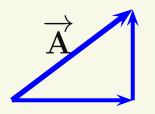


 B_x negative B_y negative

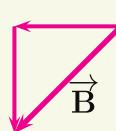




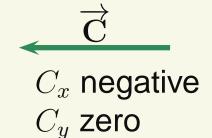
12th June 2014 **Vectors**

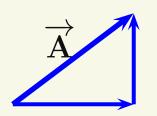


 A_x positive A_y positive

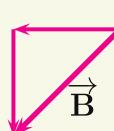


 B_x negative B_y negative

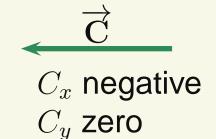


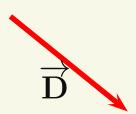


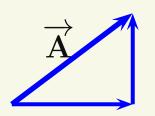
 A_x positive A_y positive



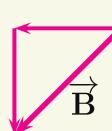
 B_x negative B_y negative



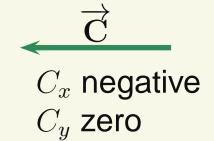


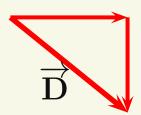


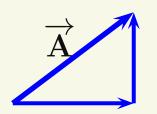
 A_x positive A_y positive



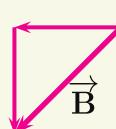
 B_x negative B_y negative



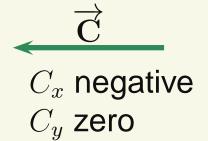


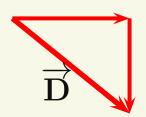


 A_x positive A_y positive

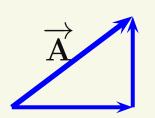


 B_x negative B_y negative

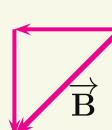




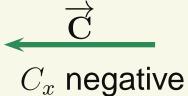
 D_x positive D_y negative



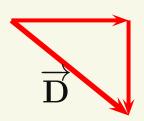
 A_x positive A_y positive



 B_x negative B_y negative

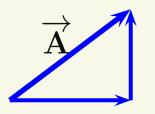


 C_y zero

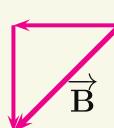


 D_x positive D_y negative





 A_x positive A_y positive

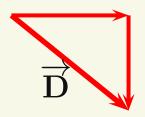


 B_x negative B_y negative

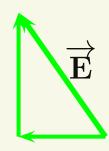


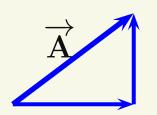
 C_x negative

 C_y zero

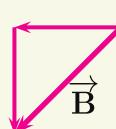


 D_x positive D_y negative

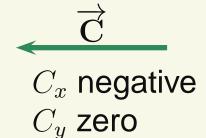


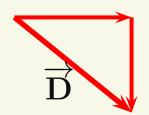


 A_x positive A_y positive

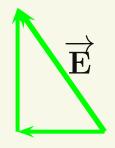


 B_x negative B_y negative





 D_x positive D_y negative



 E_x negative E_y positive

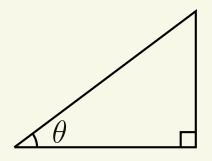
The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.

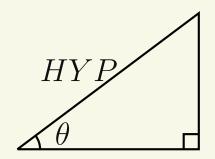
The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.



The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

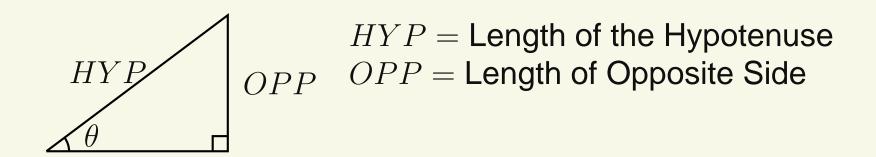
Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.



HYP =Length of the Hypotenuse

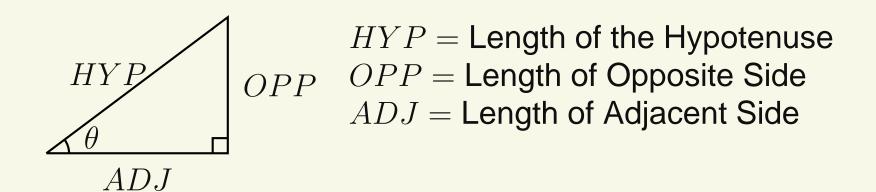
The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.



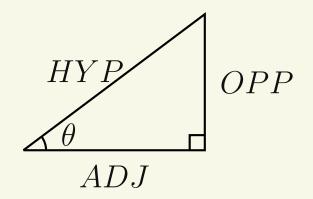
The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.



The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.



 $\begin{array}{cc} HYP = \text{Length of the Hypotenuse} \\ OPP & OPP = \text{Length of Opposite Side} \\ ADJ = \text{Length of Adjacent Side} \end{array}$

Sine Function:
$$\sin \theta = \frac{OPP}{HYP}$$

The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.

$$\begin{array}{c|cccc} & HYP \\ OPP & OPP \\ ADJ & \end{array}$$

 $HYP = Length \ of the Hypotenuse$ $OPP = Length \ of Opposite Side$ $ADJ = Length \ of Adjacent Side$

Sine Function:
$$\sin \theta = \frac{OPP}{HYP}$$

Cosine Function:
$$\cos \theta = \frac{ADJ}{HYP}$$

Vectors

The scalar components' numerical values are found using trigonometry since the magnitude and the scalar components always form a right triangle.

Trigonometry - The mathematics of right (90°) triangles. Uses the fact that the ratio of the lengths of the sides of right triangle is always the same for the same angle.

$$HYP = OPP = OPP = ADJ = ADJ$$

 $HYP = Length \ of the Hypotenuse$ $OPP = Length \ of Opposite Side$ $ADJ = Length \ of Adjacent Side$

Sine Function:
$$\sin \theta = \frac{OPP}{HYP}$$

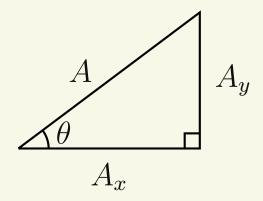
Cosine Function:
$$\cos \theta = \frac{ADJ}{HYP}$$

Tangent Function:
$$\tan \theta = \frac{OPP}{ADJ}$$

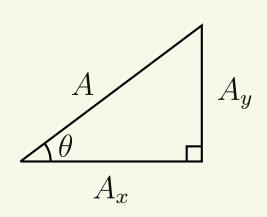
Vectors

In physics, the sides of the right triangle are the scalar components.

In physics, the sides of the right triangle are the scalar components.

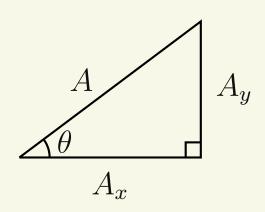


In physics, the sides of the right triangle are the scalar components.



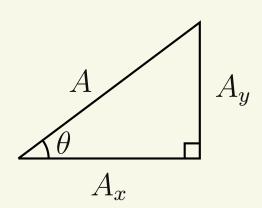
$$\cos\theta = \frac{A_x}{A}$$

In physics, the sides of the right triangle are the scalar components.



$$\cos \theta = \frac{A_x}{A} \quad \Rightarrow \quad \boxed{A_x = A \cos \theta}$$

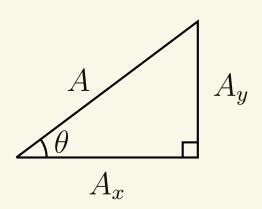
In physics, the sides of the right triangle are the scalar components.



$$\cos \theta = \frac{A_x}{A} \quad \Rightarrow \quad \boxed{A_x = A \cos \theta}$$

$$\sin\theta = \frac{A_y}{A}$$

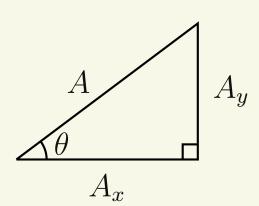
In physics, the sides of the right triangle are the scalar components.



$$\cos \theta = \frac{A_x}{A} \quad \Rightarrow \quad \boxed{A_x = A \cos \theta}$$

$$\sin \theta = \frac{A_y}{A} \quad \Rightarrow \quad \boxed{A_y = A \sin \theta}$$

In physics, the sides of the right triangle are the scalar components.



$$\cos \theta = \frac{A_x}{A} \quad \Rightarrow \quad \boxed{A_x = A \cos \theta}$$

$$\cos \theta = \frac{A_x}{A} \implies A_x = A \cos \theta$$

$$\sin \theta = \frac{A_y}{A} \implies A_y = A \sin \theta$$

Only guaranteed to work for the standard angle

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 \, m$ at 110° .

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 \, m$ at 110° .

(a)
$$x = 1.71 \, m, y = 4.7 \, m$$

Vectors

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 m$ at 110° .

(a)
$$x = 1.71 \, m, y = 4.7 \, m$$

(b)
$$x = 1.71 \, m, y = -4.7 \, m$$

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 m$ at 110° .

(a)
$$x = 1.71 \, m, y = 4.7 \, m$$

(b)
$$x = 1.71 \, m, y = -4.7 \, m$$

(c)
$$x = -1.71 \, m, y = 4.7 \, m$$

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 m$ at 110° .

(a)
$$x = 1.71 \, m, y = 4.7 \, m$$

(b)
$$x = 1.71 \, m, y = -4.7 \, m$$

(c)
$$x = -1.71 \, m, y = 4.7 \, m$$

(d)
$$x = -1.71 \, m, y = -4.7 \, m$$

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 m$ at 110° .

(a)
$$x = 1.71 \, m, y = 4.7 \, m$$

(b)
$$x = 1.71 \, m, y = -4.7 \, m$$

(c)
$$x = -1.71 \, m, y = 4.7 \, m$$

(d)
$$x = -1.71 \, m, y = -4.7 \, m$$

(e) Intentionally left blank.

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 m$ at 110° .

(a)
$$x = 1.71 \, m, y = 4.7 \, m$$

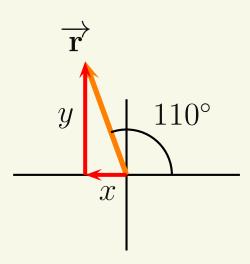
(b)
$$x = 1.71 \, m, y = -4.7 \, m$$

(c)
$$x = -1.71 \, m, y = 4.7 \, m$$

(d)
$$x = -1.71 \, m, y = -4.7 \, m$$

(e) Intentionally left blank.

Find the components of the vector $\overrightarrow{\mathbf{r}} = 5 m$ at 110° .



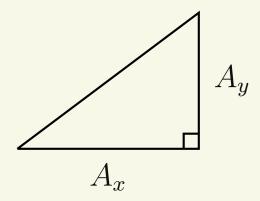
(c)
$$x = -1.71 \, m, y = 4.7 \, m$$

Using the standard angle automatically gives correct signs:

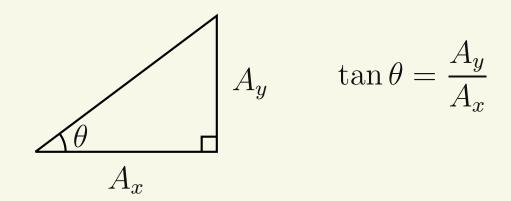
$$x = (5 m) \cos 110^{\circ} = -1.71 m$$

 $y = (5 m) \sin 110^{\circ} = 4.7 m$

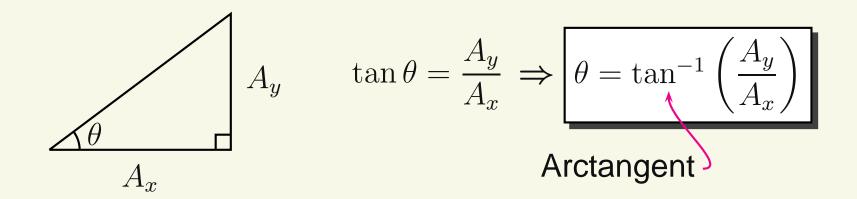
To find the magnitude and the angle *from* the components:



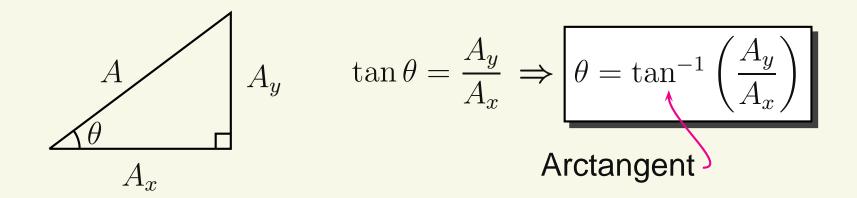
To find the magnitude and the angle *from* the components:



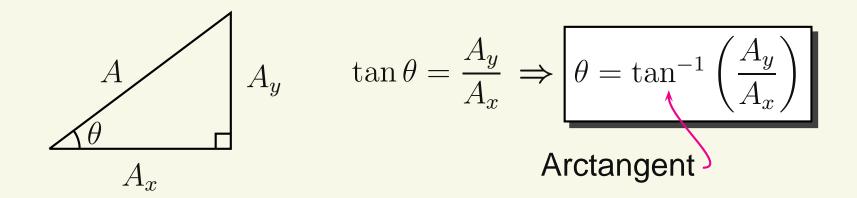
To find the magnitude and the angle *from* the components:



To find the magnitude and the angle *from* the components:

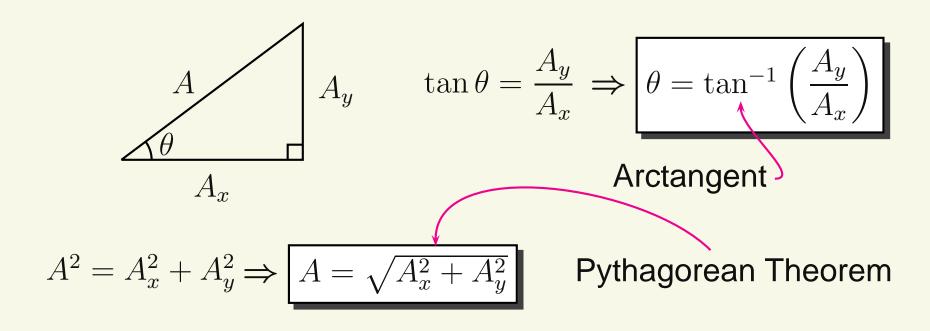


To find the magnitude and the angle *from* the components:

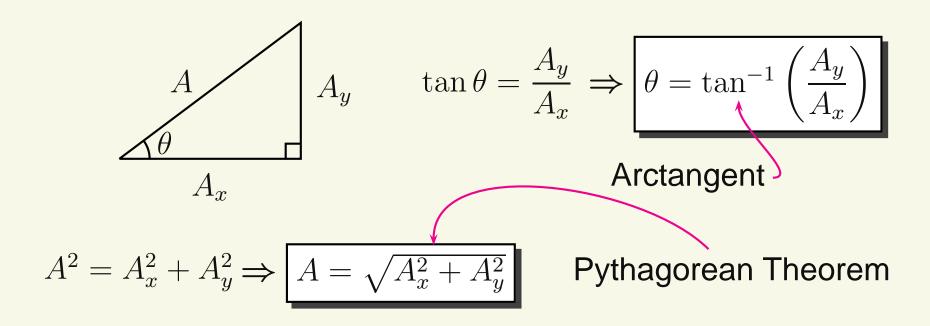


$$A^2 = A_x^2 + A_y^2$$

To find the magnitude and the angle *from* the components:



To find the magnitude and the angle *from* the components:



Example: Find the magnitude and direction for the vector with components $A_x = 1 m$ and $A_y = 1 m$.