## Notes for the standard central, single mass metric in Kruskal coordinates

I. Relation to Schwarzschild coordinates

One originally relates the Kruskal coordinates to the Schwarzschild coordinates in the following way:

$$
\left.\begin{array}{rl}
u= & \sqrt{r / 2 m-1} e^{r / 4 m} \cosh (t / 4 m), \\
v= & \sqrt{r / 2 m-1} e^{r / 4 m} \sinh (t / 4 m), \tag{1.1}
\end{array}\right\}, \quad r \geq 2 m,
$$



As it turns out, when one creates the manifold described above where we label the quadrant where $r \geq 2 m$ as quadrant I-below-and label the quadrant where $r \leq 2 m$ as quadrant II, the manifold that results is incomplete. To complete it we must append an additional copy of it, where $u$ and $v$ are given as the negatives of the expressions above. We refer to the copy of the two original quadrants as quadrant III, when $r \geq 2 m$ but $u<0$, and also quadrant IV, when $r \leq$ $2 m$ and $v<0$. Our earth of course lives in quadrant $\mathbf{I}$, where we began.

The diagram shows the Kruskal coordinates $u$ as spatial and $v$ as timelike, ignoring $\theta$ and $\varphi$. Curves of constant $r$ are hyperbolae, as is seen from equations below:

$$
u^{2}-v^{2}=(r / 2 m-1) e^{r / 2 m}=(1-2 m / r)\left(\frac{4 m}{f}\right)^{2}, \quad t=4 m\left\{\begin{array}{l}
\tanh ^{-1}(v / u), I \& I I I  \tag{1.2}\\
\tanh ^{-1}(u / v), I I \& I V
\end{array}\right.
$$

On the graph those curves of constant $r>2 m$ are the plum-colored hyperbolae in either quadrant I or quadrant III. For $0<r<2 m$ these are the blue hyperbolae, in quadrant II, or the green hyperbolae in quadrant IV. However the value $r=0$ creates the black hyperbolae in both quadrants II and IV, which are the singularities at $r=0$, beyond which no curves may pass.
One should then notice the pair of straight lines which pass the $(u, v)$ origin. These correspond to the Schwarzschild-coordinate values of $r=2 m$ and the value $t= \pm \infty$.

The Schwarzschild metric then has the following equivalent forms, in the two coordinate systems:

$$
\begin{equation*}
\mathbf{g}=\frac{d r^{2}}{1-2 m / r}+r^{2} d \Omega^{2}-(1-2 m / r) d t^{2}=\frac{32 m^{3}}{r} e^{-r / 2 m}\left(d u^{2}-d v^{2}\right)+r^{2} d \Omega^{2} \tag{1.3}
\end{equation*}
$$

where it is convenient to give the coefficient of $d u^{2}$ a name. We define

$$
\begin{equation*}
f(r) \equiv \frac{4 m}{\sqrt{r / 2 m}} e^{-r / 4 m}=4 m \sqrt{\frac{e^{-r / 2 m}}{r / 2 m}} \tag{1.4}
\end{equation*}
$$

so that the $u, v$-part of the metric is now just $f^{2}\left(d u^{2}-d v^{2}\right)$.
It is then straightforward to see that

$$
\begin{align*}
& d u=\frac{1}{4 m}\left\{\frac{r / 2 m}{\sqrt{r / 2 m-1}} e^{r / 4 m} \cosh (t / 4 m) d r+\sqrt{r / 2 m-1} e^{r / 4 m} \sinh (t / 4 m) d t\right\}, \\
& d v=\frac{1}{4 m}\left\{\frac{r / 2 m}{\sqrt{r / 2 m-1}} e^{r / 4 m} \sinh (t / 4 m) d r+\sqrt{r / 2 m-1} e^{r / 4 m} \cosh (t / 4 m) d t\right\} \tag{1.5a}
\end{align*}
$$

from which we may quickly verify that the two forms of the metric are equivalent. On the other hand, we may invert the equations, to determine $d r$ and $d t$ :

$$
\begin{equation*}
d r=\frac{f}{4 m}\left(u{\underset{\sim}{\omega}}^{\hat{u}}-v{\underset{\sim}{\omega}}^{\hat{v}}\right), \quad d t=\frac{f}{4 m}\left(\frac{r / 2 m}{r / 2 m-1}\right)\left(-v{\underset{\sim}{\omega}}^{\hat{u}}+u{\underset{\sim}{\omega}}^{\hat{v}}\right) . \tag{1.5b}
\end{equation*}
$$

A possibly useful/interesting comment is that $u_{, t}=v$ and $v_{, t}=u$, so that

$$
\begin{equation*}
\partial_{t}=v \partial_{u}+u \partial_{v}=f\left(v \widetilde{e}_{\hat{u}}+u \widetilde{e}_{\hat{v}}\right) \tag{1.5c}
\end{equation*}
$$

Since $\partial_{t}$ is a Killing vector, this suggests that this is the form of the Killing vector in these coordinates, so that the following should be a constant of the motion:

$$
\begin{equation*}
-A=u_{t}=\mathbf{g}\left(\partial_{t}, \widetilde{u}\right)=f\left(v u_{\hat{u}}+u u_{\hat{v}}\right)=f\left(v u^{\hat{u}}-u u^{\hat{v}}\right) . \tag{1.5d}
\end{equation*}
$$

Since it is difficult to resolve Eqs. (1.2) for $r$ explicitly-such explication would involve Lambert's function, as described, for instance, by Hille - we use the given form of the equation to determine $r_{, u}$ and $r_{, v}$, which will be needed. Differentiating that equation by $\partial_{u}$, or by $\partial_{v}$, and then dividing appropriately we may determine

$$
\begin{equation*}
r_{, u}=(2 m)^{2} \frac{2 u}{r} e^{-r / 2 m}=\frac{u}{4 m} f^{2}(r), \quad r_{, v}=-(2 m)^{2} \frac{2 v}{r} e^{-r / 2 m}=-\frac{v}{4 m} f^{2}(r) \tag{1.6}
\end{equation*}
$$

It is also useful to go ahead and explicitly determine derivatives of our function $f$ :

$$
\begin{equation*}
f^{\prime} \equiv \frac{d f}{d r}=-\frac{1+r / 2 m}{(r / 2 m)^{3 / 2}} e^{-r / 4 m}=-\frac{1+r / 2 m}{r / 2 m} \frac{f}{4 m}=-\frac{1+r / 2 m}{2 r} f \tag{1.7}
\end{equation*}
$$

2. Curvature and geodesics in these coordinates

We now define an orthonormal basis in our Kruskal coordinates:

$$
\begin{array}{lll}
{\underset{\omega}{u}}_{\hat{\hat{u}}}^{\equiv f d u}, & {\underset{\sim}{\omega}}_{\hat{v}}^{\equiv f d v,} \quad \stackrel{\omega^{\hat{\theta}}}{ }=r d \theta, \quad & \tilde{\sim}^{\hat{\varphi}} \equiv r \sin \theta d \varphi,  \tag{2.1}\\
\widetilde{e}_{\hat{u}}=\frac{1}{f} \partial_{u}, \quad \widetilde{e}_{\hat{v}}=\frac{1}{f} \partial_{v}, \quad \widetilde{e}_{\hat{\theta}}=\frac{1}{r} \partial_{\theta}, \quad \widetilde{e}_{\hat{\varphi}}=\frac{1}{r \sin \theta} \partial_{\varphi}
\end{array}
$$

One may then ask GRTensorII to calculate the connections and curvatures:

$$
\begin{gather*}
\Gamma_{\hat{u} \hat{\theta} \hat{\theta}}=-\frac{u}{r} \frac{f}{4 m}=\Gamma_{\hat{u} \hat{\varphi} \hat{\varphi}}, \\
\Gamma_{\hat{v} \hat{\theta} \hat{\theta}}=+\frac{v}{r} \frac{f}{4 m}=\Gamma_{\hat{v} \hat{\varphi} \hat{\varphi},},  \tag{2.2}\\
\Gamma_{\hat{u} \hat{v} \hat{u}}=+\frac{v}{2 r}(1+r / 2 m) \frac{f}{4 m}, \Gamma_{\hat{u} \hat{v} \hat{v}}=-\frac{u}{2 r}(1+r / 2 m) \frac{f}{4 m}, \quad \Gamma_{\hat{\theta} \hat{\varphi} \hat{\varphi}}=-\frac{\cot \theta}{r} .
\end{gather*}
$$

As well we determine the components of the Riemann tensor, where one needs to replace $u^{2}-v^{2}$ by its equal $(r / 2 m-1) e^{r / 2 m}$ several times:

$$
\begin{gather*}
R_{\hat{u} \hat{\theta} \hat{u} \hat{\theta}}=-\frac{m}{r^{3}}=R_{\hat{u} \hat{\varphi} \hat{u} \hat{\varphi}}=-R_{\hat{v} \hat{\theta} \hat{v} \hat{\theta}}=-R_{\hat{v} \hat{\varphi} \hat{v} \hat{\varphi}} \\
R_{\hat{\theta} \hat{\varphi} \hat{\theta} \hat{\varphi}}=2 \frac{m}{r^{3}}=-R_{\hat{u} \hat{v} \hat{u} \hat{v}} . \tag{2.3}
\end{gather*}
$$

We may then write down the form of a timelike tangent vector, $\widetilde{u}$, normalized to have length $-1=\widetilde{u}^{2}$ :

$$
\begin{gather*}
\widetilde{u}=\frac{d}{d \tau}=\frac{d u}{d \tau} \partial_{u}+\frac{d v}{d \tau} \partial_{v}+\frac{d \theta}{d \tau} \partial_{\theta}+\frac{d \varphi}{d \tau} \partial_{\varphi}=u^{\hat{u}} \widetilde{e}_{\hat{u}}+u^{\hat{v}} \widetilde{e}_{\hat{v}}+u^{\hat{\theta}} \widetilde{e}_{\hat{\theta}}+u^{\hat{\varphi}} \widetilde{e}_{\hat{\varphi}}  \tag{2.4}\\
\Longrightarrow u^{\hat{u}}=f \frac{d u}{d \tau}, \quad u^{\hat{v}}=f \frac{d v}{d \tau}, \quad u^{\hat{\theta}}=r \frac{d \theta}{d \tau}, \quad u^{\hat{\varphi}}=r \sin \theta \frac{d \varphi}{d \tau}
\end{gather*}
$$

The basic geodesic equations then say that

$$
\begin{align*}
\frac{d u^{\hat{u}}}{d \tau}= & -\Gamma_{\hat{u} \hat{\theta} \hat{\theta}}\left(u^{\hat{\theta}}\right)^{2}-\Gamma_{\hat{u} \hat{\varphi} \hat{\varphi}}\left(u^{\hat{\varphi}}\right)^{2}-\Gamma_{\hat{u} \hat{v}} u^{\hat{v}} u^{\hat{u}}-\Gamma_{\hat{u} \hat{v} \hat{v}}\left(u^{\hat{v}}\right)^{2} \\
= & \frac{u}{r} \frac{f}{4 m}\left[\left(u^{\hat{\theta}}\right)^{2}+\left(u^{\hat{\varphi}}\right)^{2}\right]-\frac{v u^{\hat{u}}-u u^{\hat{v}}}{2 r}(1+r / 2 m) \frac{f}{4 m} u^{\hat{v}}, \\
\frac{d u^{\hat{v}}}{d \tau}= & +\Gamma_{\hat{v} \hat{\theta} \hat{\theta}}\left(u^{\hat{\theta}}\right)^{2}+\Gamma_{\hat{v} \hat{\varphi} \hat{\varphi}}\left(u^{\hat{\varphi}}\right)^{2}+\Gamma_{\hat{v} \hat{u} \hat{u}}\left(u^{\hat{u}}\right)^{2}+\Gamma_{\hat{v} \hat{u} \hat{v}} u^{\hat{u}} u^{\hat{v}}  \tag{2.5}\\
= & +\frac{v}{r} \frac{f}{4 m}\left[\left(u^{\hat{\theta}}\right)^{2}+\left(u^{\hat{\varphi}}\right)^{2}\right]-\frac{v u^{\hat{u}}-u u^{\hat{v}}}{2 r}(1+r / 2 m) \frac{f}{4 m} u^{\hat{u}}, \\
\frac{d u^{\hat{\theta}}}{d \tau}= & \frac{\cot \theta}{r}\left(u^{\hat{\varphi}}\right)^{2}-\frac{u u^{\hat{u}}-v u^{\hat{v}}}{r} \frac{f}{4 m} u^{\hat{\theta}}, \\
\frac{d u^{\hat{\varphi}}}{d \tau}= & -\frac{\cot \theta}{r} u^{\hat{\theta}} u^{\hat{\varphi}}-\frac{u u^{\hat{u}}-v u^{\hat{v}}}{r} \frac{f}{4 m} u^{\hat{\varphi}} .
\end{align*}
$$

We may check that the normalization of the 4 -velocity is indeed preserved, i.e., multiplying each equation for $d u^{\alpha} / d \tau$ by $u_{\alpha}$ and summing, we may check that the sum adds up to just zero, as desired for $d(-1) / d \tau$.

Looking at the last two of these equations, we easily see that there do exist orbits that remain in the equatorial plane if they begin there; i.e., we consider $\theta_{0}=\pi / 2$ and $u^{\hat{\theta}}=0$, which tells us that $d u^{\hat{\theta}} / d \tau=0$. All single worldlines may be considered of this type, as we may orient the equatorial plane so that it contains that worldline. On the other hand, there are, in particular, radial orbits in that plane: if we set $u^{\hat{\varphi}}=0$, then we have $d u^{\hat{\varphi}} / d \tau=0$.

## Radial Orbits:

The normalization condition, already considered, now says that

$$
\begin{equation*}
\left(u^{\hat{v}}\right)^{2}-\left(u^{\hat{u}}\right)^{2}=+1=f^{2}\left[\left(v^{\prime}\right)^{2}-\left(u^{\prime}\right)^{2}\right] . \tag{2.6a}
\end{equation*}
$$

The conservation law, because of the timelike Killing vector, from Eq. (1.5d), says that

$$
\begin{equation*}
f\left(u u^{\hat{v}}-v u^{\hat{u}}\right)=A=f^{2}\left[u v^{\prime}-v u^{\prime}\right] . \tag{2.6b}
\end{equation*}
$$

To give a more direct proof that this energy-like quantity is truly conserved, we re-write it in the form

$$
\begin{align*}
\frac{d}{d \tau} A= & \frac{d}{d \tau}\left[f u u^{\hat{v}}-f v u^{\hat{u}}\right]=f u \frac{d u^{\hat{v}}}{d \tau}-f v \frac{d u^{\hat{u}}}{d \tau}+f u^{\hat{v}} u^{\prime}-f u^{\hat{u}} v^{\prime}+\left(u u^{\hat{v}}-v u^{\hat{u}}\right) \frac{d f}{d \tau} \\
= & -\left(v u^{\hat{u}}-u u^{\hat{v}}\right)(1+r / 2 m) \frac{f^{2}}{8 m r}\left(u u^{\hat{u}}-v u^{\hat{v}}\right) \\
& -\left(u u^{\hat{v}}-v u^{\hat{u}}\right)(1+r / 2 m) \frac{f^{2}}{8 m r}\left(u u^{\hat{u}}-v u^{\hat{v}}\right)=0, \tag{2.7}
\end{align*}
$$

where we have used Eqs. (1.7) and (1.5b) to calculate $d f / d \tau$, and the two central terms, among the 6 terms in the first line, have cancelled since $f u^{\prime}=u^{\hat{u}}$ and $f v^{\prime}=u^{\hat{v}}$.

It is perhaps also interesting to re-write the equations in a more coordinate-based point of view. We may introduce a name for the extra part of the equations not involving $f$, but involving $r$ directly, and first re-write the equations already given:

$$
\left.\begin{array}{rl}
\frac{d}{d \tau} u^{\hat{u}} & =-\mathcal{A} f^{3}\left(v u^{\prime}-u v^{\prime}\right) v^{\prime}  \tag{2.8}\\
\frac{d}{d \tau} u^{\hat{v}} & =-\mathcal{A} f^{3}\left(v u^{\prime}-u v^{\prime}\right) u^{\prime}, \\
\frac{d}{d \tau} f & =-\mathcal{A} f^{3}\left(u u^{\prime}-v v^{\prime}\right),
\end{array}\right\} \quad \mathcal{A} \equiv \frac{1+r / 2 m}{2 m r}
$$

But now using the fact that $u^{\hat{u}} \equiv f u^{\prime}$ and $u^{\hat{v}} \equiv f v^{\prime}$, we may obtain the following:

$$
\begin{align*}
u^{\prime \prime} & =\mathcal{A} f^{2}\left\{u\left[\left(u^{\prime}\right)^{2}+\left(v^{\prime}\right)^{2}\right]-2 v u^{\prime} v^{\prime}\right\},  \tag{2.9}\\
v^{\prime \prime} & =-\mathcal{A} f^{2}\left\{v\left[\left(u^{\prime}\right)^{2}+\left(v^{\prime}\right)^{2}\right]-2 u u^{\prime} v^{\prime}\right\} .
\end{align*}
$$

Next we may note that the factor may be re-written in many ways:

$$
\begin{equation*}
\mathcal{A} f^{2}=\frac{1+r / 2 m}{r / 2 m} 4 \frac{e^{-r / 2 m}}{r / 2 m}=\left(1-\frac{1}{\rho^{2}}\right) \frac{4}{u^{2}-v^{2}}, \quad \rho \equiv r / 2 m \tag{2.10}
\end{equation*}
$$

Given the two conserved quantities displayed in Eqs. (2.6), and noticing, from the definition of $f=f(r)$, that as $r \rightarrow 0,1 / f^{2}$ vanishes like $r$, it follows that $\left(v^{\prime}\right)^{2}$ approaches $\left(u^{\prime}\right)^{2}$, which is the same as saying that the speed of light is being approached. If we also notice that $v^{\prime}>0$ while $u^{\prime}<0$, then we may say that $v^{\prime}$ approaches $-u^{\prime}$. This then also allows us to see that $u+v$ approaches zero like $r$.

As an aside I note that the radial equations in the $\{r, t\}$ coordinates are given as follows:

$$
\begin{equation*}
\left(\frac{d r}{d \tau}\right)^{2}=A^{2}-1+\frac{2 m}{r}, \quad \frac{d t}{d \tau}=\frac{A}{1-2 m / r} \tag{2.11}
\end{equation*}
$$

and have (parametric) solution, for the case where $A \leq 1$ :

$$
r=R \cos ^{2}(\eta / 2)=\frac{1}{2} R(1+\cos \eta), \quad \tau=\frac{1}{2} R \sqrt{\frac{R}{2 m}}(\eta+\sin \eta)
$$

where $R$ is the maximum value of $r$.
On a blowup of the figure in Kruskal coordinates on the first page we can now plot an astronaut falling into the hole - with no difficulties in the equations at all as she passes $r=2 m$-and also a radio ray that passes her location exactly at the point of her being at $r=2 m$. At that point the values of $u$ and $v$ are of course equal, because they are on the $45^{\circ}$ line, with $u=0.60=v$.

$U$
Her worldline is the obvious timelike curve shown, shown in red prior to $r=2 m$ and in green afterward. The orange line is the radio message mentioned above. One can see that, in terms of the timelike coordinate $v$, the light ray arrives at the singularity prior to the astronaut's arrival at that singularity.
Since light rays must travel on $45^{\circ}$ lines, one can also notice that any radio signal that she sends out after passing $r=2 m$ has no chance of entering back into quadrant I. The brown curve trying this is shown, headed outward.

