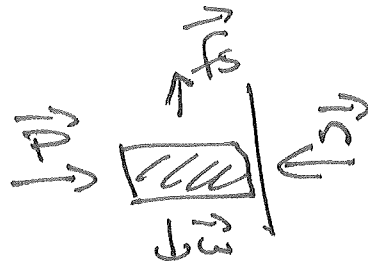


Physics 160

Extra Credit #14

NORMAL & FRICTIONAL Forces

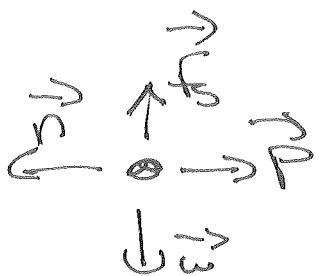
FOR A BOX AGAINST A
WALL:



NORMAL force to left since vertical wall

Also w DOWN. ~~so~~ WITH NO FRICTION BOX would slide

DOWN \Rightarrow friction is upward



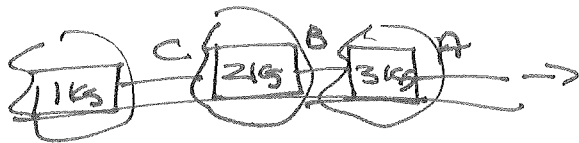
NO MOTION $\Rightarrow \Sigma F_x = 0, \Sigma F_y = 0$

$$\Sigma F_x = 0 \Rightarrow P - n = 0 \Rightarrow n = P$$

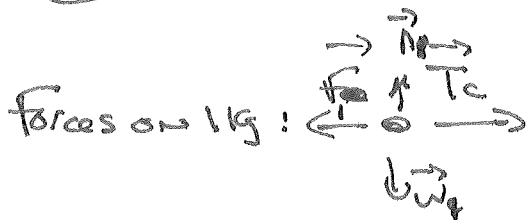
$$\Sigma F_y = 0 \Rightarrow f_s - w = 0 \Rightarrow f_s = w$$

- RANK BASED ON P SINCE $n = P$
- $f_s = w \Rightarrow$ RANK BASED ON MASS VALUES ($w = mg$)

Kinetic Friction Ranking Task



Constant speed $\Rightarrow \Sigma F_x = 0$
 No motion in $y \Rightarrow \Sigma F_y = 0$

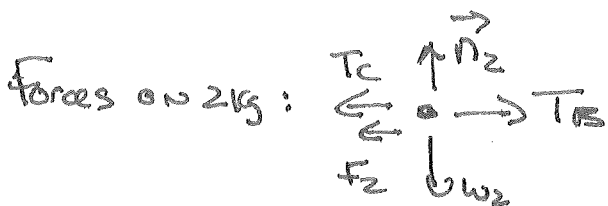


T_c = Tension in Rope C
 \vec{f}_1 = Kinetic friction on 1

$$\Sigma F_y = 0 \Rightarrow N_1 - W_1 = 0 \Rightarrow N_1 = W_1 = (1\text{kg})g$$

$$* f_1 = \mu_k N_1 = \mu_k (1\text{kg})g$$

$$\Sigma F_x = 0 \Rightarrow T_c - f_1 = 0 \Rightarrow T_c = f_1 = \mu_k (1\text{kg})g$$

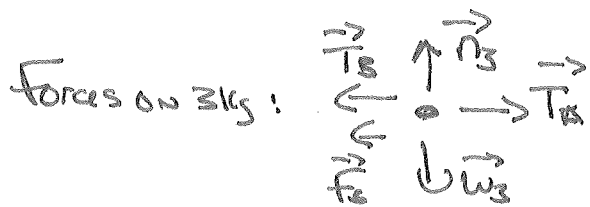


$$\Sigma F_y = 0 \Rightarrow N_2 = W_2 = (2\text{kg})g$$

so $f_2 = \mu_k (2\text{kg})g$

$$\Sigma F_x = 0 \Rightarrow T_B - T_c - f_2 = 0$$

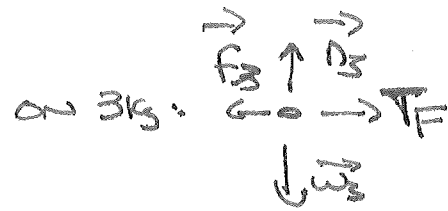
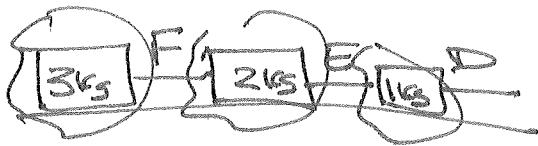
$$\Rightarrow T_B = T_c + f_2 = \mu_k (1\text{kg})g + \mu_k (2\text{kg})g = \mu_k (3\text{kg})g$$



$$\Sigma F_y = 0 \Rightarrow N_3 = W_3 = (3\text{kg})g \Rightarrow f_3 = \mu_k (3\text{kg})g$$

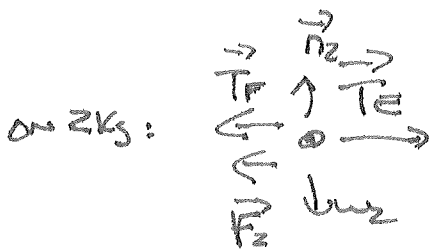
$$\Sigma F_x = 0 \Rightarrow T_A - T_B - f_3 = 0$$

$$\Rightarrow T_A = T_B + f_3 = \mu_k (3\text{kg})g + \mu_k (3\text{kg})g = \mu_k (6\text{kg})g$$



From previous work: $f_3 = \mu_k(3kg)g$

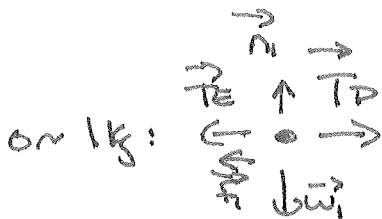
$$\sum F_x = 0 \Rightarrow T_F - f_3 = 0 \Rightarrow T_F = f_3 = \mu_k(3kg)g$$



From previous: $f_2 = \mu_k(2kg)g$

$$\sum F_x = 0 \Rightarrow T_E - T_F - f_2 = 0$$

$$\Rightarrow T_E = T_F + f_2 = \mu_k(3kg)g + \mu_k(2kg)g = \mu_k(5kg)g$$



$$f_1 = \mu_k(1kg)g$$

$$\sum F_x = 0 \Rightarrow T_D - T_E - f_1 = 0 \Rightarrow T_D = T_E + f_1$$

$$\Rightarrow T_D = \mu_k(5kg)g + \mu_k(1kg)g = \mu_k(6kg)g$$



From previous $T_G = \mu_k(3kg)g$



$$T_H = \mu_k(5kg)g$$

So All together :

$$T_C = \mu_k (1\text{kg})g \quad T_F = \mu_k (3\text{kg})g$$

$$T_B = \mu_k (3\text{kg})g \quad T_E = \mu_k (5\text{kg})g$$

$$T_A = \mu_k (6\text{kg})g \quad T_D = \mu_k (6\text{kg})g$$

$$T_G = \mu_k (3\text{kg})g \quad T_H = \mu_k (5\text{kg})g$$

largest

smallest

$$\begin{array}{c} T_A \\ T_D \end{array} \left\{ \begin{array}{c} T_E \\ T_H \end{array} \right\} \left\{ \begin{array}{c} T_B \\ T_F \\ T_G \end{array} \right\} T_C$$

5.27

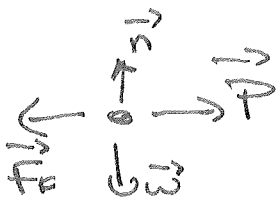


Crate:

$m = 11.7 \text{ kg}$, Constant speed $v_0 = 3 \text{ m/s}$

$\mu_k = 0.18$

To maintain motion?



Constant speed $\Rightarrow a_x = 0$

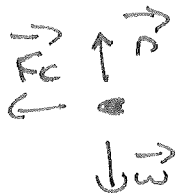
No motion in $y \Rightarrow a_y = 0$

$$\sum F_y = 0 \Rightarrow n - w = 0 \Rightarrow n = w = mg = (11.7 \text{ kg})(9.8 \text{ m/s}^2) = 114.66 \text{ N}$$

$$f_k = \mu_k n = 0.18(114.66 \text{ N}) = 20.6388 \text{ N}$$

$$\sum F_x = 0 \Rightarrow P - f_k = 0 \Rightarrow P = f_k = 20.6388 \text{ N}$$

b) Without P , How far to stop?



$$\text{Now } \sum F_x = m a_x \Rightarrow -f_k = m a_x$$

$$\Rightarrow -\mu_k n = m a_x, \quad n = w = mg \Rightarrow -\mu_k mg = m a_x$$

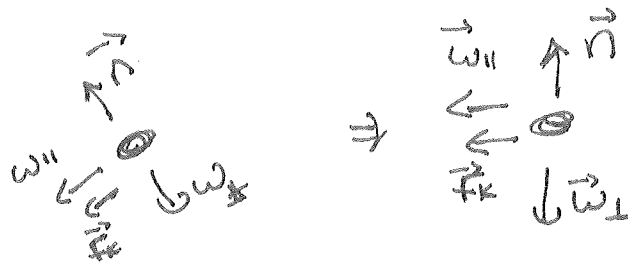
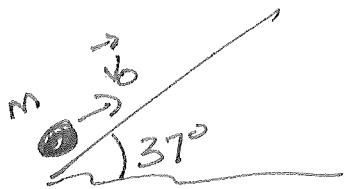
$$\Rightarrow a_x = -\mu_k g \quad (\text{DIDN'T NEED MASS TO DO THIS PART!})$$

$$a_x = -0.18(9.8 \text{ m/s}^2) = -1.764 \text{ m/s}^2 \leftarrow \text{constant so } v^2 = v_0^2 + 2a_x(x - x_0)$$

$$\Rightarrow 0 = (3 \text{ m/s})^2 + 2(-1.764 \text{ m/s}^2)(x - 0) \Rightarrow x = \frac{-(3 \text{ m/s})^2}{2(-1.764 \text{ m/s}^2)} = 2.551 \text{ m}$$

5.30

$v_0 = 14 \text{ m/s}, \mu_k = 0.35, \mu_s = 0.59$



NO ACCELERATION perpendicular to incline $\Rightarrow \Sigma F_{\perp} = 0$

$\Rightarrow n - w_{\perp} = 0 \Rightarrow n = w_{\perp} = mg \cos \alpha$

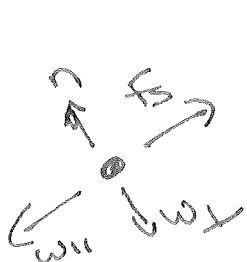
so $f_k = \mu_k n = \mu_k mg \cos \alpha$

$\Sigma F_{\parallel} = ma_{\parallel}, a_{\parallel} = a = ?$

$\Rightarrow -w_{\parallel} - f_k = ma \Rightarrow -mg \sin \alpha - \mu_k mg \cos \alpha = ma$

$\Rightarrow a = -g(\sin \alpha + \mu_k \cos \alpha) = -9.8 \text{ m/s}^2 (\sin 37^\circ + 0.35 \cos 37^\circ) = -8.637 \text{ m/s}^2$

b) will it stay at top. AT TOP, static friction tries to prevent motion BACK DOWN.



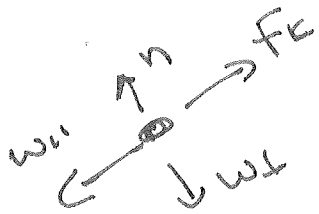
so if $f_{s, \text{MAX}} \geq w_{\parallel}$, it will stay

$f_{s, \text{MAX}} = \mu_s n \geq w_{\parallel}, n = w_{\perp} = mg \cos \alpha$

$\Rightarrow \mu_s mg \cos \alpha \geq mg \sin \alpha \Rightarrow 0.59 \cos 37^\circ \geq \sin 37^\circ$

$\Rightarrow 0.471 \geq 0.602$ so $f_{s, \text{MAX}}$ Not big enough

c) BACK DOWN: \vec{f}_k opposite to $w_{||}$



$$n = w_{\perp} = mg \cos \alpha \text{ still}$$

$$\sum F_{||} = ma_{||} \Rightarrow \cancel{w_{||}} f_k - w_{||} = ma$$

$$\Rightarrow \mu_k mg \cos \alpha - mg \sin \alpha = ma$$

$$\begin{aligned} \Rightarrow a &= (\mu_k \cos \alpha - \sin \alpha) g = (0.35 \cos 37^\circ - \sin 37^\circ)(9.8 \text{ m/s}^2) \\ &= -3.1584 \text{ m/s}^2 \end{aligned}$$