## April 18, Week 13

Today: Chapter 10, Angular Momentum<br>Homework \#10-Due April 26 at 11:59pm Mastering Physics: 7 questions from chapter 10. Written Question: 10.86

Exam \#5, Friday, April 27
On Chapters 9 and 10

## Angular Momentum

Angular Momentum, $\overrightarrow{\mathrm{L}}$ - the rotational counterpart to linear momentum, $\overrightarrow{\mathrm{p}}$.

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\sum \overrightarrow{\mathbf{F}}=\frac{\overrightarrow{d \mathbf{p}}}{d t}
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$$

How much torque must be applied to cause a change in rotation.

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$$

How much torque must be applied to cause a change in rotation.

For a point particle (an object with a single value of $\overrightarrow{\mathrm{v}}$ ), the angular momentum is:

$$
\overrightarrow{\mathrm{L}}=\overrightarrow{\mathrm{r}} \times \overrightarrow{\mathrm{p}}
$$

## Angular Momentum II

$\overrightarrow{\mathrm{L}}=\overrightarrow{\mathrm{r}} \times \overrightarrow{\mathrm{p}}$ can be shown by taking a derivative.

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\vec{\tau}=\frac{\vec{d} \mathbf{L}}{d t} \quad \vec{\tau}=\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{F}}
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\vec{\tau}=\frac{\overrightarrow{\mathrm{L}}}{d t} \quad \vec{\tau}=\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{F}} \quad \overrightarrow{\mathbf{F}}=\frac{\vec{d} \mathbf{p}}{d t}
$$

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$\overrightarrow{\mathrm{L}}=\overrightarrow{\mathrm{r}} \times \overrightarrow{\mathrm{p}}$ can be shown by taking a derivative.

$$
\begin{aligned}
\vec{\tau} & =\frac{\vec{d} \mathbf{L}}{d t} \quad \vec{\tau}=\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{F}} \quad \overrightarrow{\mathbf{F}}=\frac{\overrightarrow{d \mathbf{p}}}{d t} \\
\vec{\tau} & =\frac{\overrightarrow{d \mathbf{L}}}{d t}
\end{aligned}
$$

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$$
\begin{aligned}
& \overrightarrow{\boldsymbol{\tau}}=\frac{\overrightarrow{d \overrightarrow{\mathbf{L}}}}{d t} \quad \overrightarrow{\boldsymbol{\tau}}=\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{F}} \quad \overrightarrow{\mathbf{F}}=\frac{\overrightarrow{d \mathbf{p}}}{d t} \\
& \overrightarrow{\boldsymbol{\tau}}=\frac{\overrightarrow{d \mathbf{L}}}{d t}=\frac{d}{d t}(\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{p}})
\end{aligned}
$$

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\begin{gathered}
\overrightarrow{\boldsymbol{\tau}}=\frac{\overrightarrow{\mathrm{d}}}{d t} \quad \vec{\tau}=\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{F}} \quad \overrightarrow{\mathbf{F}}=\frac{\overrightarrow{d \mathbf{p}}}{d t} \\
\vec{\tau}=\frac{\overrightarrow{d \mathbf{L}}}{d t}=\frac{d}{d t}(\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{p}})=\left(\frac{\overrightarrow{d \mathbf{r}}}{d t} \times \overrightarrow{\mathbf{p}}\right)+\left(\overrightarrow{\mathbf{r}} \times \frac{\overrightarrow{d \mathbf{p}}}{d t}\right)
\end{gathered}
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=(\overrightarrow{\mathbf{v}} \times \overrightarrow{\mathbf{p}})+(\overrightarrow{\mathbf{r}} \times \overrightarrow{\mathbf{F}})=(\overrightarrow{\mathbf{v}} \times M \overrightarrow{\mathbf{v}})+\vec{\tau}
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\overrightarrow{\mathbf{v}} \times \overrightarrow{\mathbf{v}}=0 \text { since } \phi=0^{\circ}
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For rigid bodies (objects with infinitely many values of $\vec{v}$ ), we have to imagine splitting the object into many small pieces.

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$$
\overrightarrow{\mathbf{L}}_{i}=\overrightarrow{\mathbf{r}}_{i} \times \overrightarrow{\mathbf{p}}_{i}=\overrightarrow{\mathbf{r}}_{i} \times M_{i} \overrightarrow{\mathbf{v}}_{i}
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Each piece going on circle $\Rightarrow \overrightarrow{\mathbf{r}}_{i}$ is $90^{\circ}$ to $\overrightarrow{\mathrm{v}}_{i}$

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$$
L_{i}=r_{i} M_{i} v_{i}
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$$
v_{i}=r_{i} \omega
$$

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## Clicker Quiz

A solid disk with moment of Inertia $I=2 \mathrm{~kg} \cdot \mathrm{~m}^{2}$ is rotating clockwise with angular speed $3 \mathrm{rad} / \mathrm{s}$. What average torque must be exerted over $2 s$ in order to make the disk spin counter-clockwise with angular speed $5 \mathrm{rad} / \mathrm{s}$ ?

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(a) $2 N \cdot m$

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(b) $4 N \cdot m$

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(c) $5 N \cdot m$

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(c) $5 N \cdot m$
(d) $8 N \cdot m$

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## Example

## Point Particle: $\overrightarrow{\mathrm{L}}=\overrightarrow{\mathrm{r}} \times \overrightarrow{\mathrm{p}}$

Rigid Body: $\overrightarrow{\mathrm{L}}=I \vec{\omega}$

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Example: Find the angular momentum of the earth for its orbital motion around the sun. Assume the $5.97 \times 10^{24}-\mathrm{kg}$ earth is following a circular orbit of radius $1.5 \times 10^{11} \mathrm{~m}$.

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Example: Find the angular momentum of the earth for its orbital motion around the sun. Assume the $5.97 \times 10^{24}-\mathrm{kg}$ earth is following a circular orbit of radius $1.5 \times 10^{11} \mathrm{~m}$.

Example: Find the angular momentum of the earth for its 24 -hour daily motion. Treat the earth as a solid sphere of radius of $6.38 \times 10^{6} \mathrm{~m}$.

## Conservation of Angular Momentum

In the absence of external torques, the total angular momentum of a system cannot change.

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3rd Law for rotation: $\vec{\tau}_{A}=-\vec{\tau}_{B}$

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$$
\vec{\tau}_{A}+\vec{\tau}_{B}=0
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\begin{aligned}
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$$
\vec{\tau}_{A}=\frac{\vec{d}_{A}}{d t} \vec{\tau}_{A}=\begin{aligned}
& \vec{\tau}_{B}=\text { Torque on } B \text { due to } A \\
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& \text { 3rd Law for rotation: } \vec{\tau}_{A}=-\vec{\tau}_{B} \\
& \vec{\tau}_{A}+\overrightarrow{\mathbf{I}}_{B}=0 \\
& \frac{d \mathbf{L}_{A}}{d t}+\frac{\overrightarrow{\mathbf{L}_{A}}}{d t}=0
\end{aligned}
$$

