March 30, Week 10

Today: Chapter 8, Collisions

Homework #8: Mastering Physics: 8 problems from chapter 8 Written Question: 8.101 Due April 2 at 11:59pm

Exam #4: Friday, April 6

Review Session: Thursday, April 5, 7:30PM

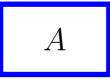
Practice Problems for chapters 5, 6, and 7 available on Mastering Physics

 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.

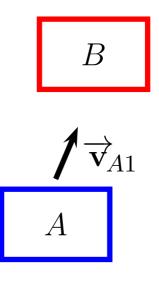


 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.

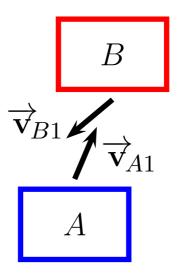




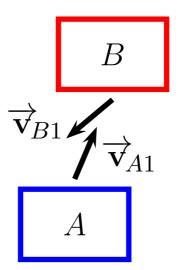
 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.



 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.

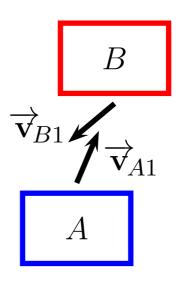


 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.



$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1}$$

 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.

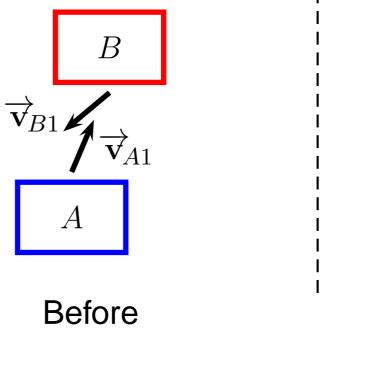


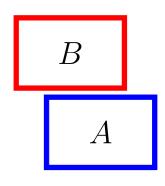
Before

After

$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1}$$

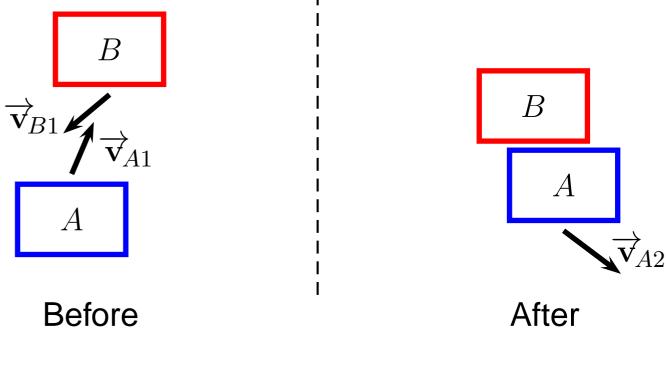
 $\Delta \left(\overrightarrow{\mathbf{p}}_A + \overrightarrow{\mathbf{p}}_B \right) = 0 \Rightarrow$ the total momentum of the system can't change.



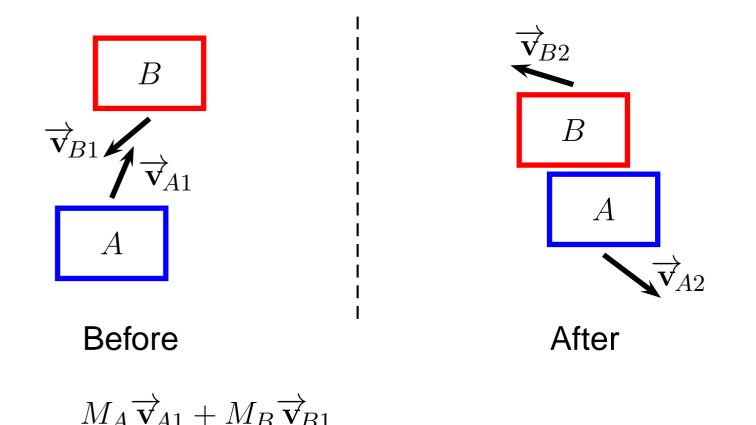


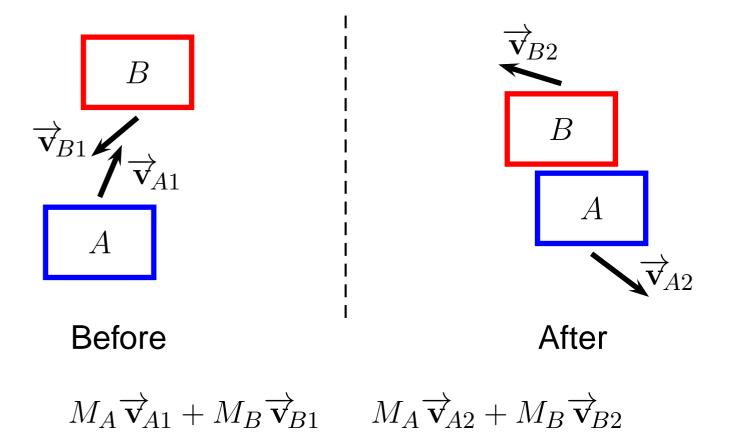
After

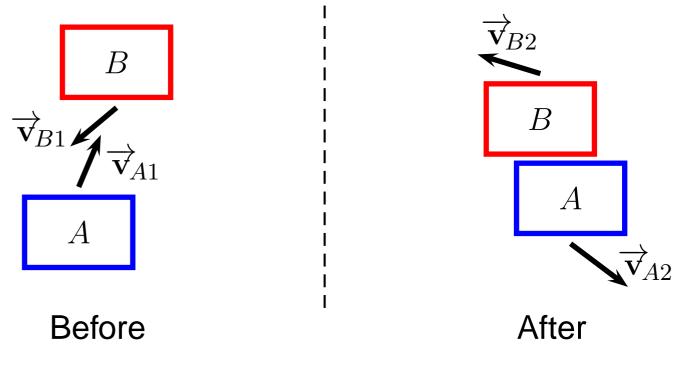
$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1}$$



$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1}$$

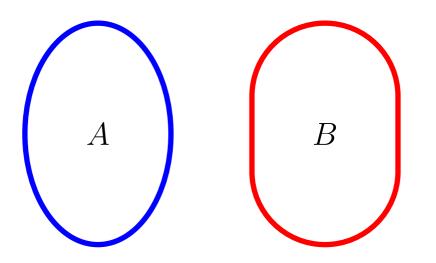




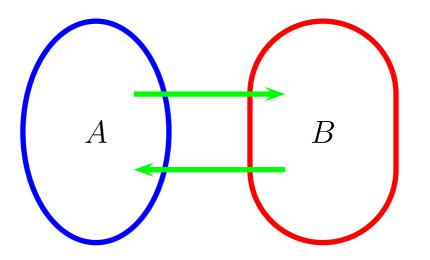


$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1} = M_A \overrightarrow{\mathbf{v}}_{A2} + M_B \overrightarrow{\mathbf{v}}_{B2}$$

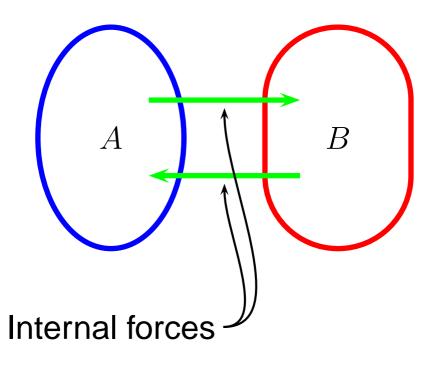
If there are external force acting on a system then momentum will not be conserved.



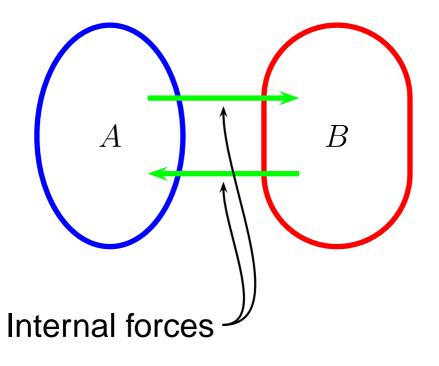
If there are external force acting on a system then momentum will not be conserved.



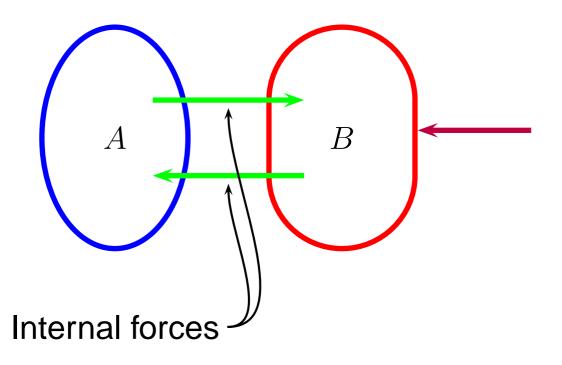
If there are external force acting on a system then momentum will not be conserved.



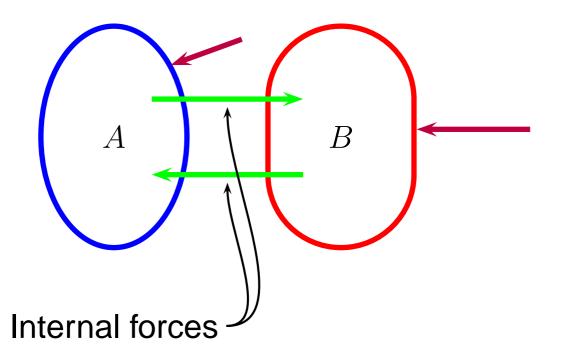
If there are external force acting on a system then momentum will not be conserved.



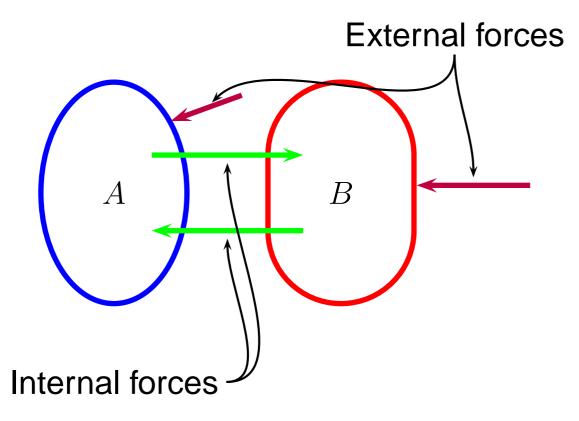
If there are external force acting on a system then momentum will not be conserved.



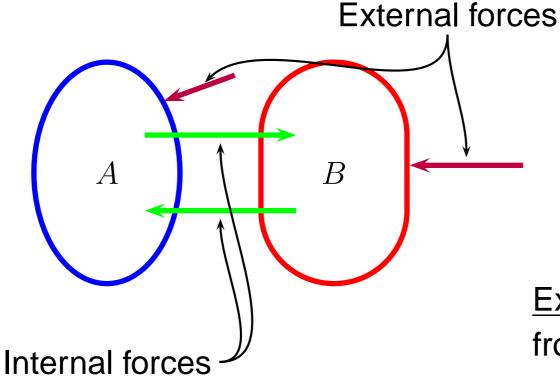
If there are external force acting on a system then momentum will not be conserved.



If there are external force acting on a system then momentum will not be conserved.



If there are external force acting on a system then momentum will not be conserved.



Internal Forces - Forces inside the system. Always come in action/reaction pairs

External Forces - Forces from outside the system



<u>Collision</u> - Any strong interaction that lasts a short period of time.

<u>Collision</u> - Any strong interaction that lasts a short period of time.

Collisions are always assumed to conserve momentum since even if there are external forces, the collision's short duration makes their effect on the motion negligible.

<u>Collision</u> - Any strong interaction that lasts a short period of time.

Collisions are always assumed to conserve momentum since even if there are external forces, the collision's short duration makes their effect on the motion negligible.

Collisions are classified as to whether they also conserve kinetic energy.

<u>Collision</u> - Any strong interaction that lasts a short period of time.

Collisions are always assumed to conserve momentum since even if there are external forces, the collision's short duration makes their effect on the motion negligible.

Collisions are classified as to whether they also conserve kinetic energy.

Elastic Collision - Conserves Momentum and Kinetic Energy.

<u>Collision</u> - Any strong interaction that lasts a short period of time.

Collisions are always assumed to conserve momentum since even if there are external forces, the collision's short duration makes their effect on the motion negligible.

Collisions are classified as to whether they also conserve kinetic energy.

Elastic Collision - Conserves Momentum and Kinetic Energy.

Inelastic Collision - Conserves Momentum only.

<u>Collision</u> - Any strong interaction that lasts a short period of time.

Collisions are always assumed to conserve momentum since even if there are external forces, the collision's short duration makes their effect on the motion negligible.

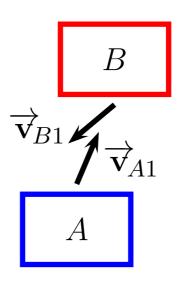
Collisions are classified as to whether they also conserve kinetic energy.

Elastic Collision - Conserves Momentum and Kinetic Energy.

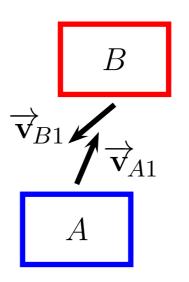
Inelastic Collision - Conserves Momentum only.

Example: Are the collisions from the previous lecture elastic?

When the colliding objects stick together, the collision can *never* be elastic. This collision is called completely inelastic or a plastic collision.

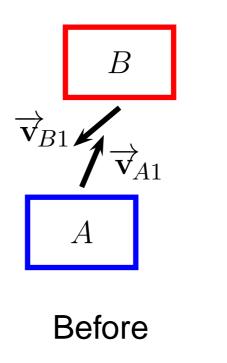


When the colliding objects stick together, the collision can *never* be elastic. This collision is called completely inelastic or a plastic collision.



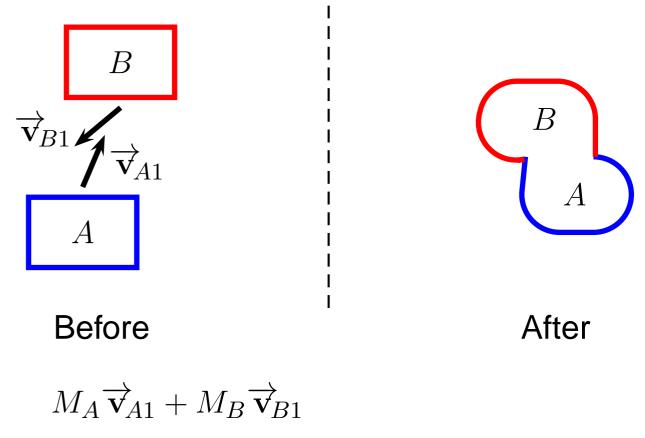
$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1}$$

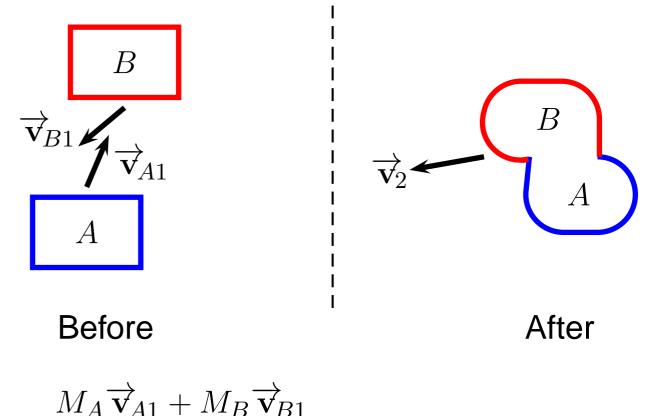
When the colliding objects stick together, the collision can *never* be elastic. This collision is called completely inelastic or a plastic collision.

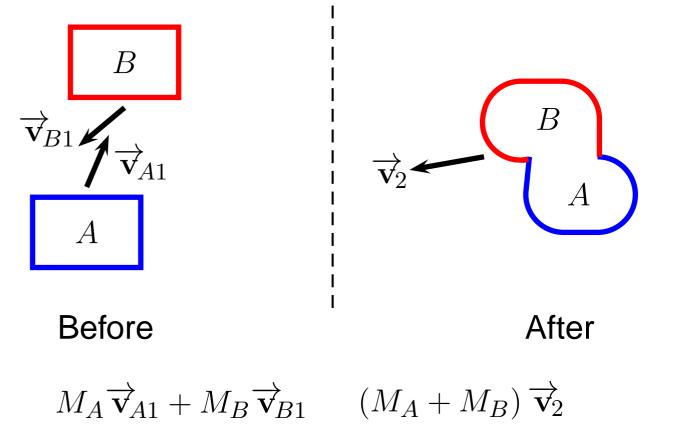


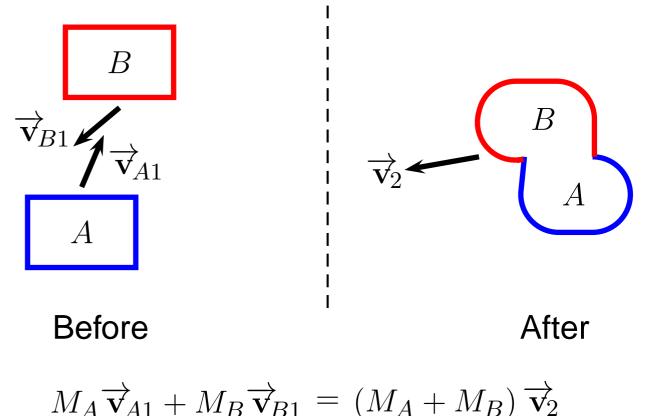
After

$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1}$$





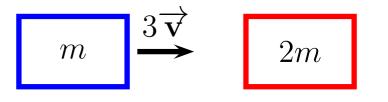




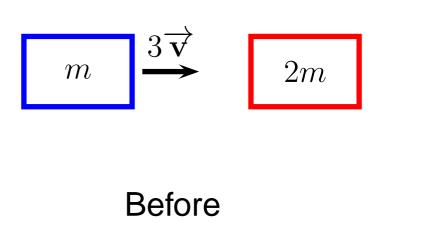
Clicker Quiz

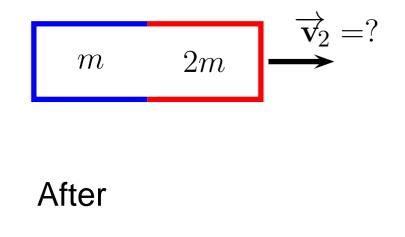
A block with $M_A = m$ and velocity $3\vec{v}$ to the right has a completely inelastic collision with $M_B = 2m$ that is initially at rest. How fast must the masses be going the instant after their collision?

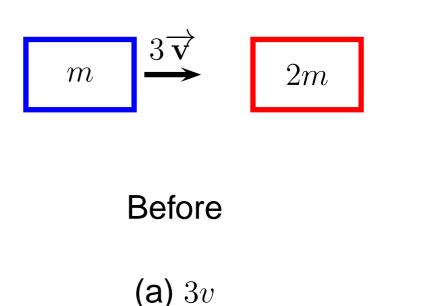
A block with $M_A = m$ and velocity $3\vec{v}$ to the right has a completely inelastic collision with $M_B = 2m$ that is initially at rest. How fast must the masses be going the instant after their collision?

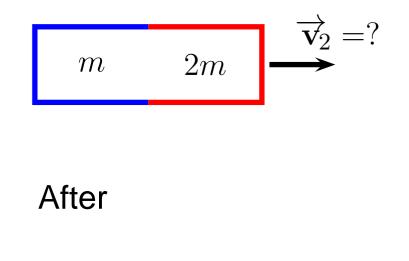


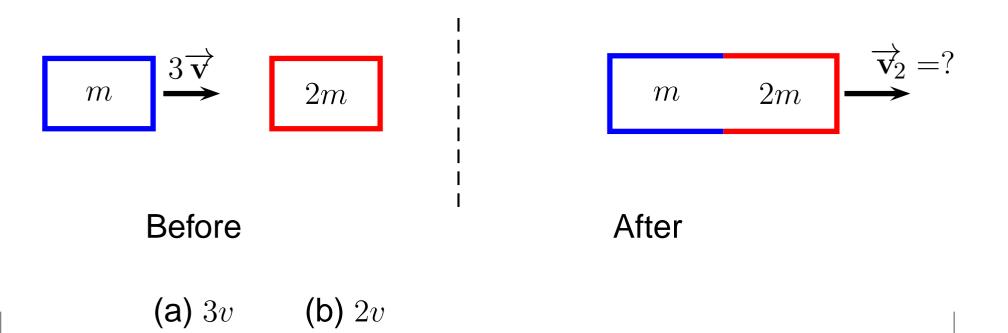
Before

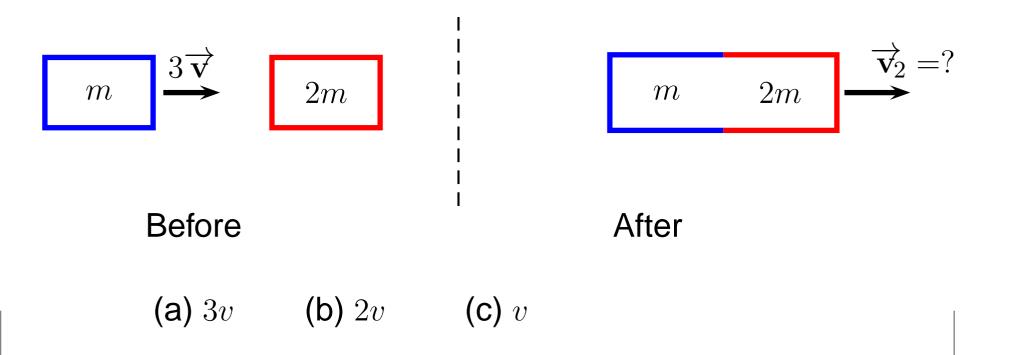


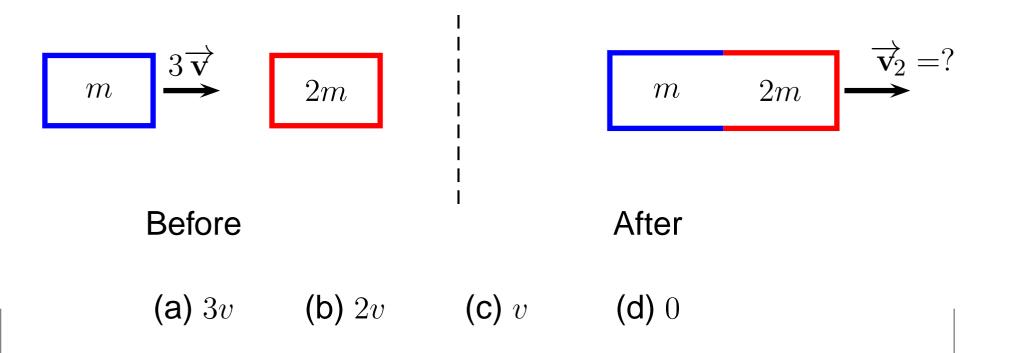


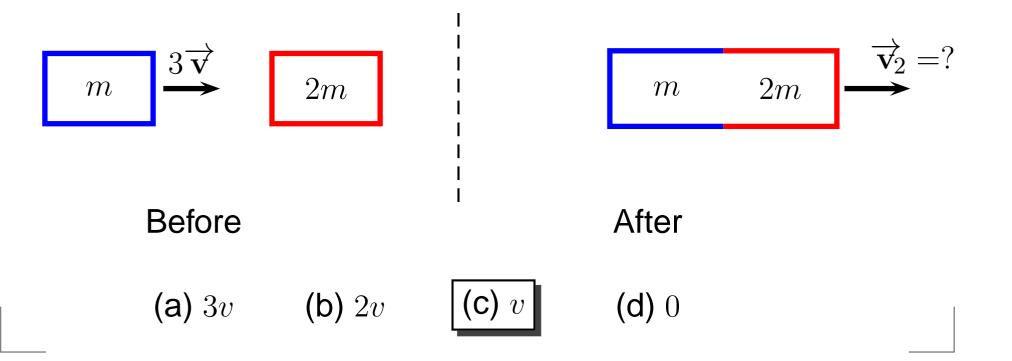












Example

 $M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1} = (M_A + M_B) \overrightarrow{\mathbf{v}}_2$

Example

$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1} = (M_A + M_B) \overrightarrow{\mathbf{v}}_2$$

Example: A 2900-kg Hummer H_2 going East on Lomas Boulevard at 11 m/s has a completely inelastic collision with a 730-kg smart-car going 25° East-of-North at 30 m/s on Monte-Vista Boulevard. What is the speed and direction of the combination the instant after the collision?

Elastic Collisions occur when there is no friction between the colliding objects and a perfect reformation of shape of both objects.

Elastic Collisions occur when there is no friction between the colliding objects and a perfect reformation of shape of both objects.

Billiard Collisions are almost perfectly elastic.

- Elastic Collisions occur when there is no friction between the colliding objects and a perfect reformation of shape of both objects.
- Billiard Collisions are almost perfectly elastic.
- For an elastic collision, we must have:

- Elastic Collisions occur when there is no friction between the colliding objects and a perfect reformation of shape of both objects.
- Billiard Collisions are almost perfectly elastic.
- For an elastic collision, we must have:

$$M_A \overrightarrow{\mathbf{v}}_{A1} + M_B \overrightarrow{\mathbf{v}}_{B1} = M_A \overrightarrow{\mathbf{v}}_{A2} + M_B \overrightarrow{\mathbf{v}}_{B2}$$

- Elastic Collisions occur when there is no friction between the colliding objects and a perfect reformation of shape of both objects.
- Billiard Collisions are almost perfectly elastic.
- For an elastic collision, we must have:

$$M_{A} \overrightarrow{\mathbf{v}}_{A1} + M_{B} \overrightarrow{\mathbf{v}}_{B1} = M_{A} \overrightarrow{\mathbf{v}}_{A2} + M_{B} \overrightarrow{\mathbf{v}}_{B2} \text{ and}$$
$$\frac{1}{2} M_{A} v_{A1}^{2} + \frac{1}{2} M_{B} v_{B1}^{2} = \frac{1}{2} M_{A} v_{A2}^{2} + \frac{1}{2} M_{B} v_{B2}^{2}$$

In 1D, the velocities have just one component $\Rightarrow \overrightarrow{\mathbf{v}}_{A1} = v_{A1}$, *etc.*

In 1D, the velocities have just one component $\Rightarrow \overrightarrow{\mathbf{v}}_{A1} = v_{A1}$, *etc.*

$$M_A v_{A1} + M_B v_{B1} = M_A v_{A2} + M_B v_{B2} \text{ and}$$

$$\frac{1}{2} M_A v_{A1}^2 + \frac{1}{2} M_B v_{B1}^2 = \frac{1}{2} M_A v_{A2}^2 + \frac{1}{2} M_B v_{B2}^2$$

In 1D, the velocities have just one component $\Rightarrow \overrightarrow{\mathbf{v}}_{A1} = v_{A1}$, *etc.*

$$M_A v_{A1} + M_B v_{B1} = M_A v_{A2} + M_B v_{B2} \text{ and}$$
$$\frac{1}{2} M_A v_{A1}^2 + \frac{1}{2} M_B v_{B1}^2 = \frac{1}{2} M_A v_{A2}^2 + \frac{1}{2} M_B v_{B2}^2$$

Given M_A , M_B , v_{A1} , $v_{B1} \Rightarrow$ there are two unknowns (v_{A2} and v_{B2}) and two equations.

In 1D, the velocities have just one component $\Rightarrow \overrightarrow{\mathbf{v}}_{A1} = v_{A1}$, *etc.*

$$M_A v_{A1} + M_B v_{B1} = M_A v_{A2} + M_B v_{B2} \text{ and}$$

$$\frac{1}{2} M_A v_{A1}^2 + \frac{1}{2} M_B v_{B1}^2 = \frac{1}{2} M_A v_{A2}^2 + \frac{1}{2} M_B v_{B2}^2$$

Given M_A , M_B , v_{A1} , $v_{B1} \Rightarrow$ there are two unknowns (v_{A2} and v_{B2}) and two equations.

Only one way to have an elastic collision in 1D!

It can be shown (see textbook or lecture notes) that if a collision is elastic, the relative velocity, $v_A - v_B$, changes sign after the collision.

It can be shown (see textbook or lecture notes) that if a collision is elastic, the relative velocity, $v_A - v_B$, changes sign after the collision.

$$(v_{A2} - v_{B2}) = -(v_{A1} - v_{B1})$$

It can be shown (see textbook or lecture notes) that if a collision is elastic, the relative velocity, $v_A - v_B$, changes sign after the collision.

$$(v_{A2} - v_{B2}) = -(v_{A1} - v_{B1})$$

Substituting into the momentum equation gives (see lecture notes):

It can be shown (see textbook or lecture notes) that if a collision is elastic, the relative velocity, $v_A - v_B$, changes sign after the collision.

$$(v_{A2} - v_{B2}) = -(v_{A1} - v_{B1})$$

Substituting into the momentum equation gives (see lecture notes):

$$v_{A2} = \frac{V_{A1} \left(M_A - M_B\right) + 2M_B V_{B1}}{\left(M_A + M_B\right)}$$

It can be shown (see textbook or lecture notes) that if a collision is elastic, the relative velocity, $v_A - v_B$, changes sign after the collision.

$$(v_{A2} - v_{B2}) = -(v_{A1} - v_{B1})$$

Substituting into the momentum equation gives (see lecture notes):

$$v_{A2} = \frac{V_{A1} \left(M_A - M_B \right) + 2M_B V_{B1}}{\left(M_A + M_B \right)}$$

$$v_{B2} = \frac{-V_{B1} \left(M_A - M_B\right) + 2M_A V_{A1}}{\left(M_A + M_B\right)}$$

1D Elastic Collisions Example

$$v_{A2} = \frac{V_{A1} \left(M_A - M_B \right) + 2M_B V_{B1}}{\left(M_A + M_B \right)}$$

$$v_{B2} = \frac{-V_{B1} \left(M_A - M_B\right) + 2M_A V_{A1}}{\left(M_A + M_B\right)}$$

1D Elastic Collisions Example

$$v_{A2} = \frac{V_{A1} \left(M_A - M_B \right) + 2M_B V_{B1}}{\left(M_A + M_B \right)}$$

$$v_{B2} = \frac{-V_{B1} \left(M_A - M_B\right) + 2M_A V_{A1}}{\left(M_A + M_B\right)}$$

Example: A 5-kg mass going 6 m/s to the right has a one-dimensional elastic collision with a 30 kg mass initially at rest. What are the speeds and direction of both afterwards?

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

 $M_A v_{A1,x} + M_B v_{B1,x} = M_A v_{A2,x} + M_B v_{B2,x}$

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

$$M_A v_{A1,x} + M_B v_{B1,x} = M_A v_{A2,x} + M_B v_{B2,x}$$

$$M_A v_{A1,y} + M_B v_{B1,y} = M_A v_{A2,y} + M_B v_{B2,y}$$

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

$$M_A v_{A1,x} + M_B v_{B1,x} = M_A v_{A2,x} + M_B v_{B2,x}$$

$$M_A v_{A1,y} + M_B v_{B1,y} = M_A v_{A2,y} + M_B v_{B2,y}$$

$$\frac{1}{2}M_A\left(v_{A1,x}^2 + v_{A1,y}^2\right) + \frac{1}{2}M_B\left(v_{B1,x}^2 + v_{B1,y}^2\right) = \frac{1}{2}M_A\left(v_{A2,x}^2 + v_{A2,y}^2\right) + \frac{1}{2}M_A\left(v_{B2,x}^2 + v_{B2,y}^2\right)$$

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

Given the masses and initial velocities, there are four unknowns:

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

Given the masses and initial velocities, there are four unknowns:

 $v_{A2,x}$ $v_{A2,y}$ $v_{B2,x}$ $v_{B2,y}$

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

Given the masses and initial velocities, there are four unknowns:

 $v_{A2,x}$ $v_{A2,y}$ $v_{B2,x}$ $v_{B2,y}$

But only three equations!

In two-dimensions, there are two momentum equations (one for each component), but still only a single energy equation (energy is a scalar).

Given the masses and initial velocities, there are four unknowns:

 $v_{A2,x} \quad v_{A2,y} \quad v_{B2,x} \quad v_{B2,y}$

But only three equations!

Infinitely many ways to have a 2D elastic collision

2D Example

We must restrict the problem in some way for there to be a single solution.

2D Example

We must restrict the problem in some way for there to be a single solution.

Example: A 2900-kg Hummer H_2 going East on Lomas Boulevard at 11 m/s has an elastic collision with a 730-kg smart-car going 25° East-of-North at 30 m/s on Monte-Vista Boulevard. If the Hummer has a speed of 9 m/s afterwards, what is the speed of the smart-car and direction for both, the instant after the collision?