

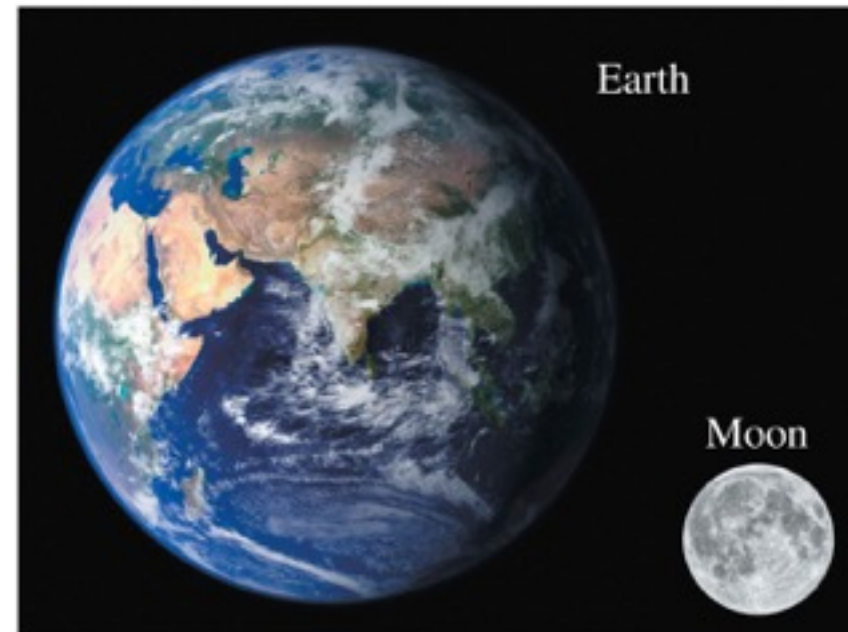
# Lecture 3 I

PHYC 161 Fall 2016

# Currents and planetary magnetism

---

- The earth's magnetic field is caused by currents circulating within its molten, conducting interior.
- These currents are stirred by our planet's relatively rapid spin (one rotation per 24 hours).
- The moon's internal currents are much weaker; it is much smaller than the earth, has a predominantly solid interior, and spins slowly (one rotation per 27.3 days).
- Hence the moon's magnetic field is only about  $10^{-4}$  as strong as that of the earth.



# Magnetic fields of current-carrying wires

---

- Computer cables, or cables for audio-video equipment, create little or no magnetic field.
- This is because within each cable, closely spaced wires carry current in both directions along the length of the cable.
- The magnetic fields from these opposing currents cancel each other.

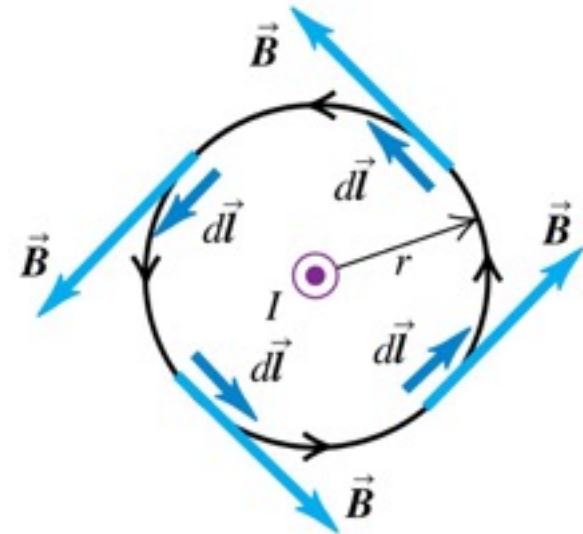


# Ampere's law (special case)

- **Ampere's law** relates electric current to the line integral around a closed path.
- Shown is the special case of a circular closed path centered on a long, straight conductor carrying current  $I$  out of the page.
- In this case the integral is simple:

Integration path is a circle centered on the conductor; integration goes around the circle counterclockwise.

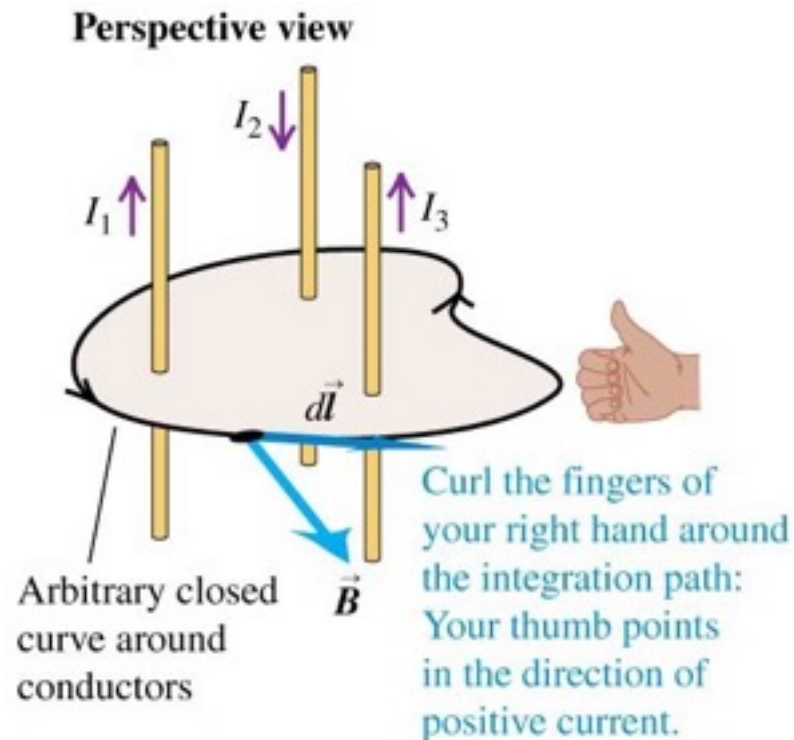
Result:  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I$



$$\oint \vec{B} \cdot d\vec{l} = \oint B_{\parallel} dl = B \oint dl = \frac{\mu_0 I}{2\pi r} (2\pi r) = \mu_0 I$$

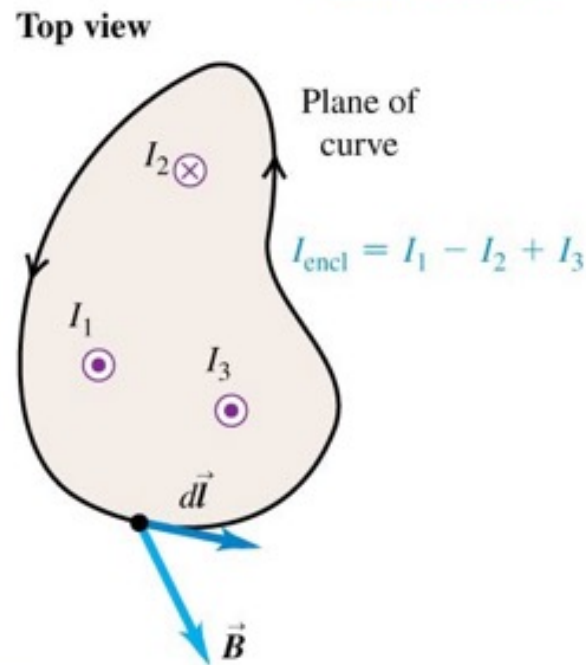
# Ampere's law (general statement)

- Suppose several long, straight conductors pass through the surface bounded by the integration path.
- Thus the line integral of the total magnetic field is proportional to the *algebraic sum* of the currents.



# Ampere's law (general statement)

- For the general statement of Ampere's law, we can replace  $I$  with  $I_{\text{encl}}$ , the algebraic sum of the currents enclosed or linked by the integration path, with the sum evaluated by using the right-hand sign rule.



# Ampere's law (general statement)

Line integral around a closed path

Ampere's law:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{encl}}$$

Scalar product of magnetic field and vector segment of path

Magnetic constant

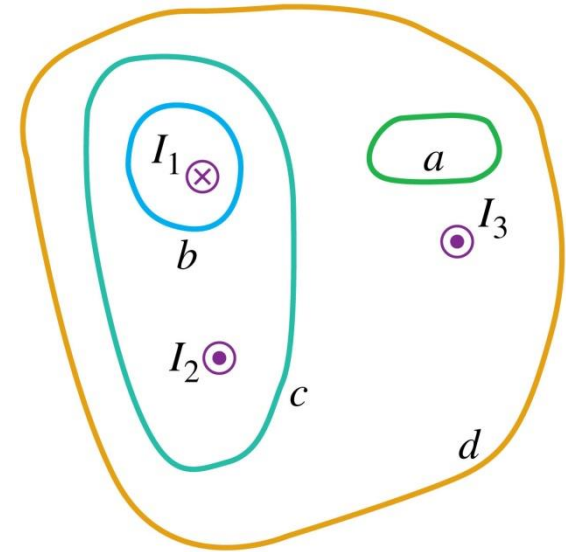
Net current enclosed by path

- This equation is valid for conductors and paths of any shape.
- If the integral around the closed path is zero, it *does not* necessarily mean that the magnetic field is everywhere along the path, only that the total current through an area bounded by the path is zero.

# CPS 31-2

The figure shows, in cross section, three conductors that carry currents perpendicular to the plane of the figure.

If the currents  $I_1$ ,  $I_2$ , and  $I_3$  all have the same magnitude, for which path(s) is the line integral of the magnetic field equal to zero?



- A. path  $a$  only
- B. paths  $a$  and  $c$
- C. paths  $b$  and  $d$
- D. paths  $a$ ,  $b$ ,  $c$ , and  $d$
- E. The answer depends on whether the integral goes clockwise or counterclockwise around the path.



# Applying Ampere's Law

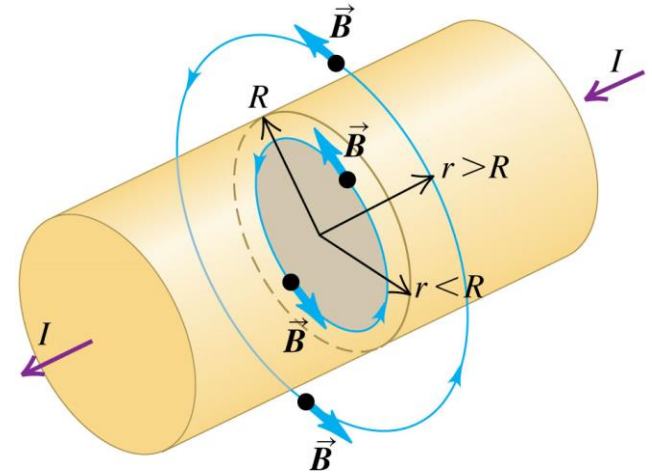
- We can look at the magnetic field inside a conducting wire with some (cylindrically symmetric) current density:

$$\int_{\text{Closed Path}} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} \Rightarrow$$

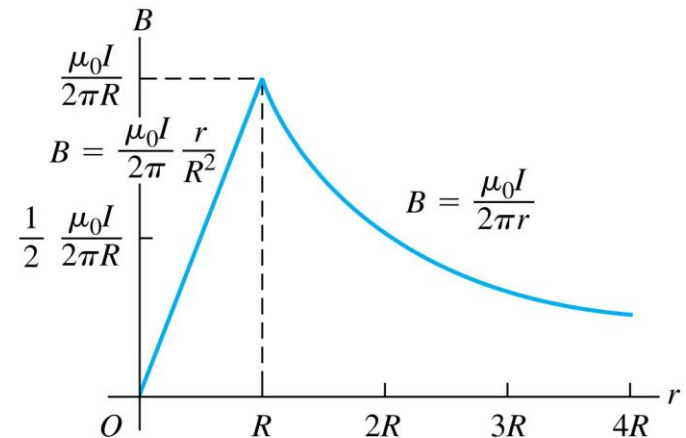
Closed Path

$$\int_{\text{Circle}} \vec{B} \cdot d\vec{l} = 2\pi r B = \mu_0 I_{\text{enc}} = \begin{cases} \mu_0 J (\pi r^2) & \text{inside wire} \\ \mu_0 I & \text{outside wire} \end{cases}$$

$$B = \begin{cases} \frac{\mu_0 J r}{2} & \text{inside wire} \\ \frac{\mu_0 I}{2\pi r} & \text{outside wire} \end{cases}$$



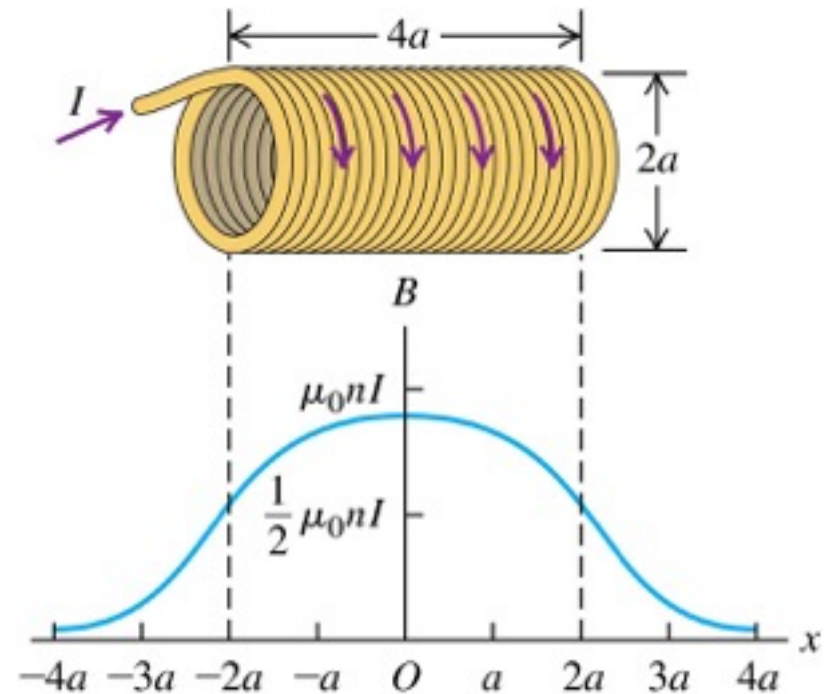
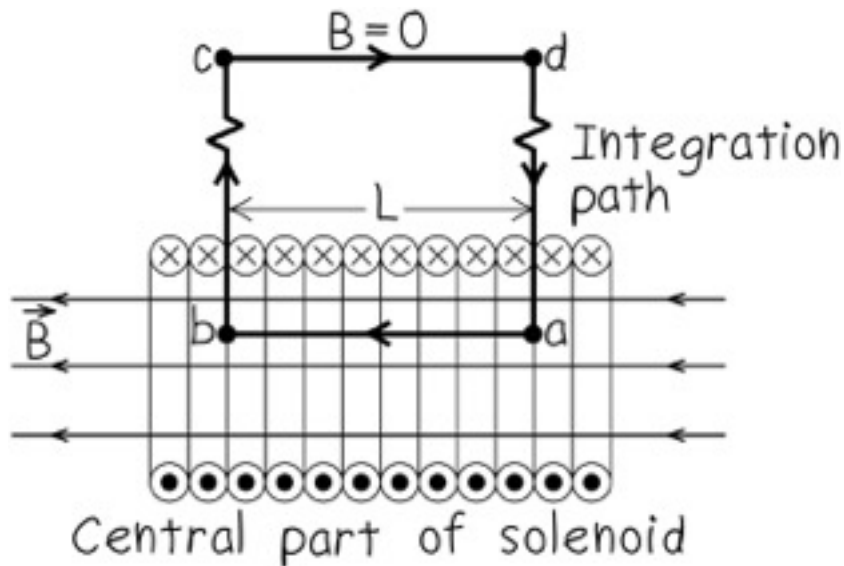
© 2012 Pearson Education, Inc.



© 2012 Pearson Education, Inc.

# Field of a solenoid

- A *solenoid* consists of a helical winding of wire on a cylinder.
- Follow Example 28.9 using the figures below.



# Applying Ampere's Law

- If we have a current,  $I$ , and  $N$  turns per unit length,  $L$ , then:

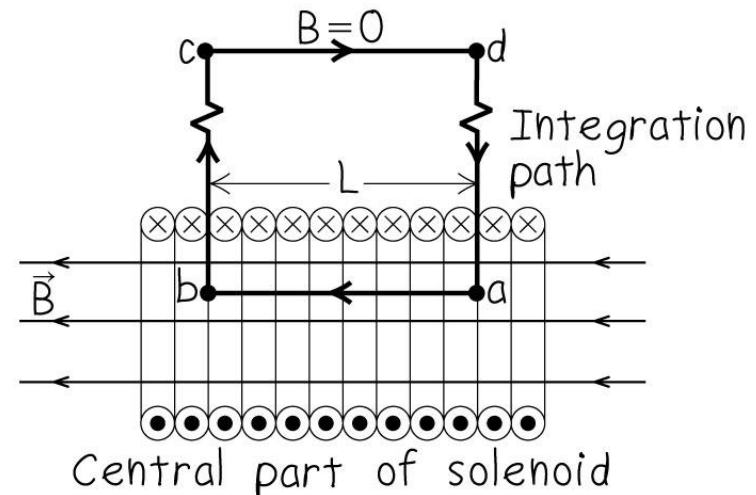
$$\int \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} \Rightarrow$$

Closed Path

$$\int_{a \rightarrow b} \vec{B} \cdot d\vec{l} + \int_{b \rightarrow c} \vec{B} \cdot d\vec{l} + \int_{c \rightarrow d} \vec{B} \cdot d\vec{l} + \int_{d \rightarrow a} \vec{B} \cdot d\vec{l} = \mu_0 NI \Rightarrow$$

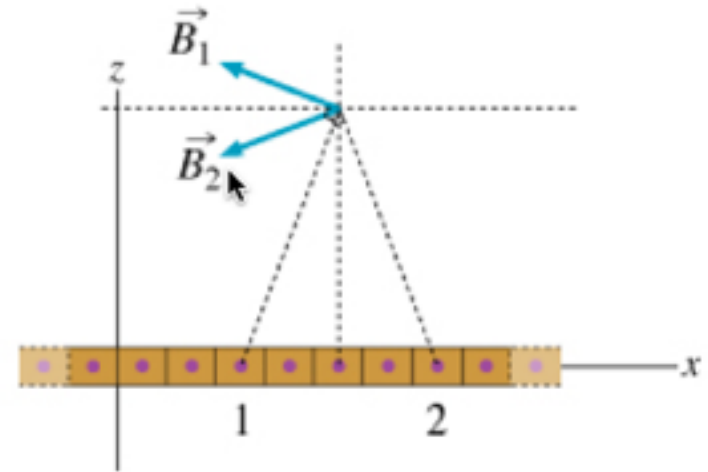
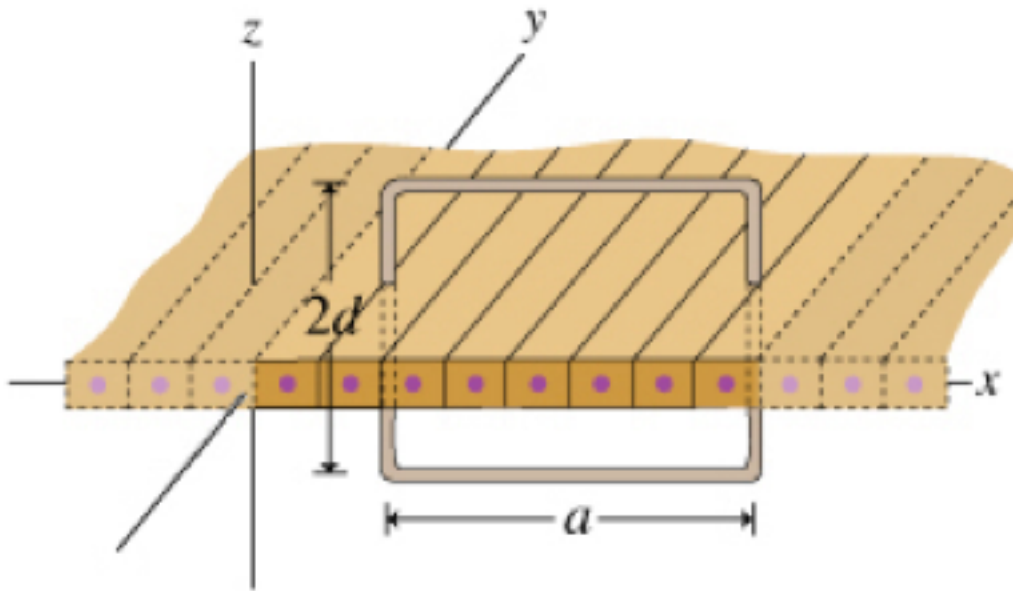
$$BL = \mu_0 NI \Rightarrow$$

$$B = \mu_0 \frac{N}{L} I$$



© 2012 Pearson Education, Inc.

# HW - Apply Amperes Law to a current sheet



Infinite sheet  $\Rightarrow$  **B is constant**  
outside the sheet

# Faraday's law of induction

---

- When the magnetic flux through a single closed loop changes with time, there is an induced emf that can drive a current around the loop:

Faraday's law:

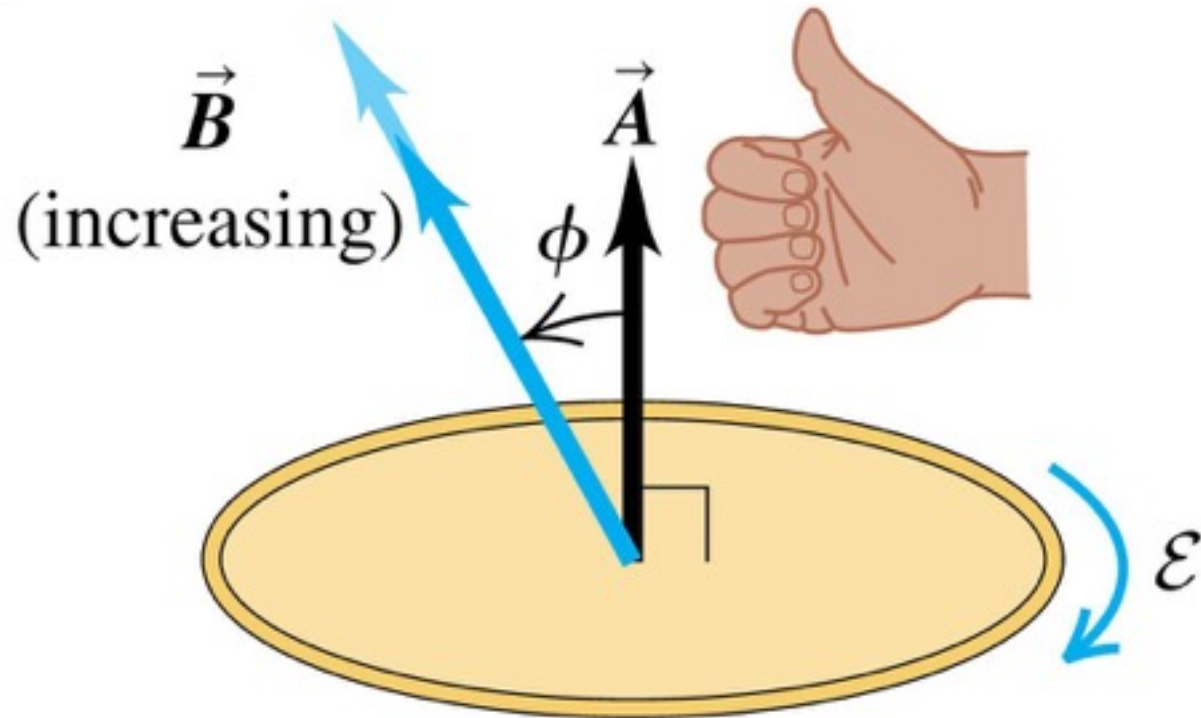
The induced emf  
in a closed loop ...

$$\mathcal{E} = -\frac{d\Phi_B}{dt}$$

... equals the negative of  
the time rate of change of  
magnetic flux through the loop.

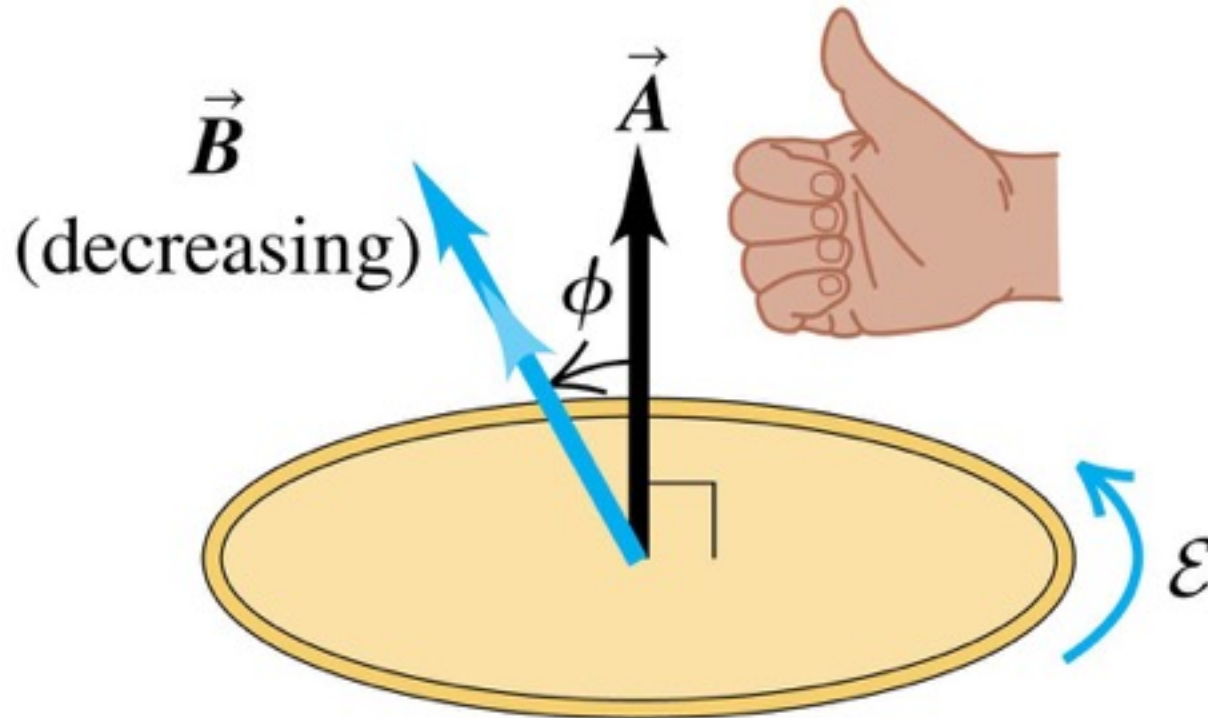
- Recall that the unit of magnetic flux is the weber (Wb).
- $1 \text{ T} \cdot \text{m}^2 = 1 \text{ Wb}$ , so  $1 \text{ V} = 1 \text{ Wb/s}$ .

# Determining the direction of the induced emf: Slide 1 of 4



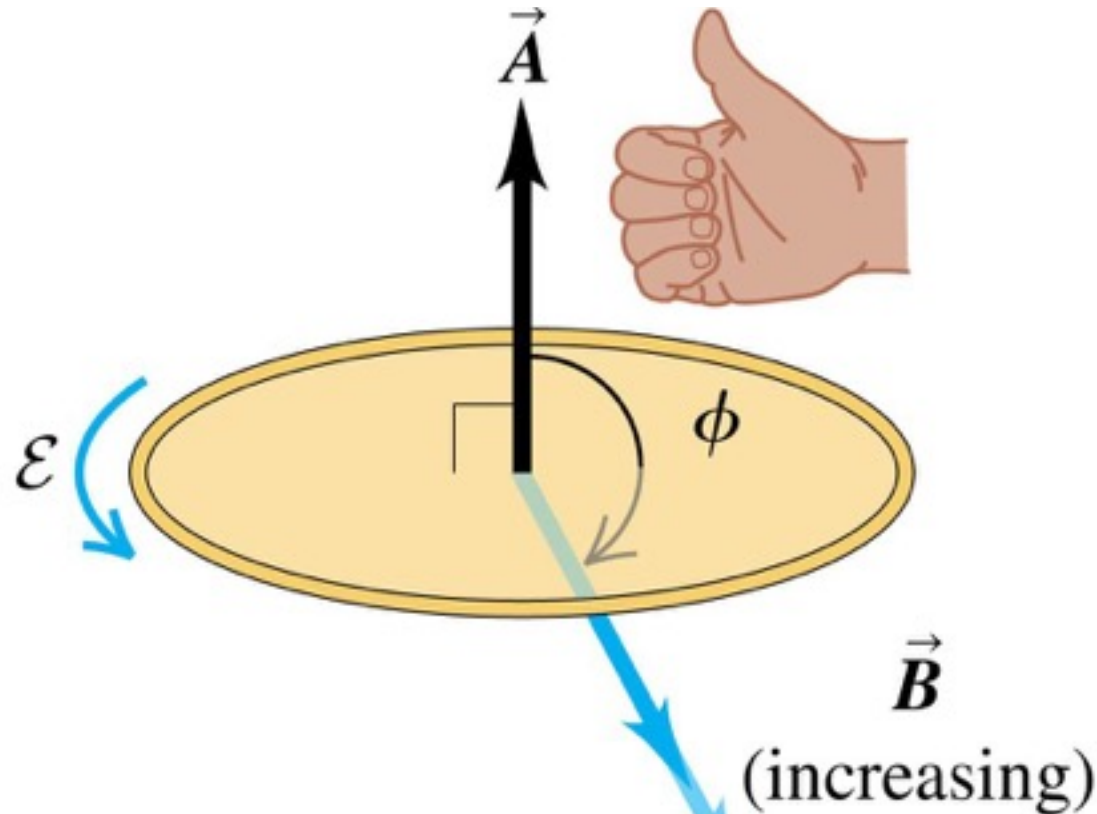
- Flux is positive ( $\Phi_B > 0$ ) ...
- ... and becoming more positive ( $d\Phi_B/dt > 0$ ).
- Induced emf is negative ( $\mathcal{E} < 0$ ).

## Determining the direction of the induced emf: Slide 2 of 4



- Flux is positive ( $\Phi_B > 0$ ) ...
- ... and becoming less positive ( $d\Phi_B/dt < 0$ ).
- Induced emf is positive ( $\mathcal{E} > 0$ ).

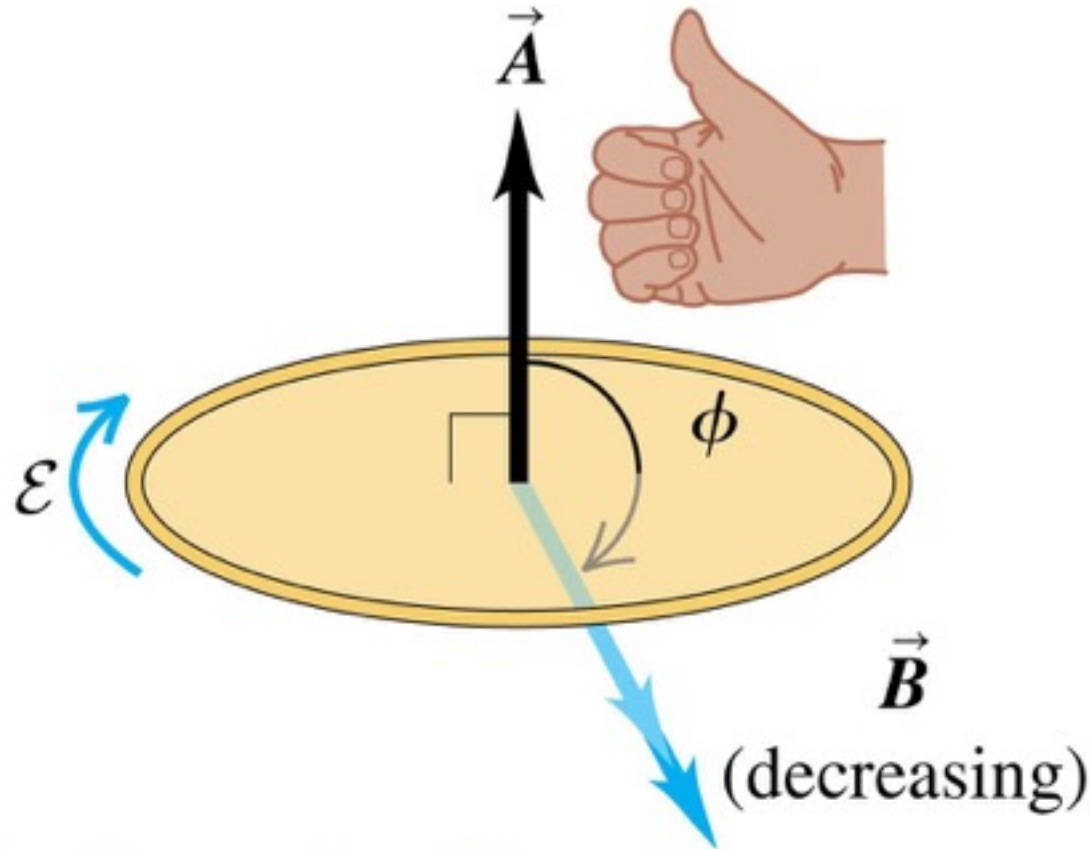
# Determining the direction of the induced emf: Slide 3 of 4



- Flux is negative ( $\Phi_B < 0$ ) ...
- ... and becoming more negative ( $d\Phi_B/dt < 0$ ).
- Induced emf is positive ( $\mathcal{E} > 0$ ).



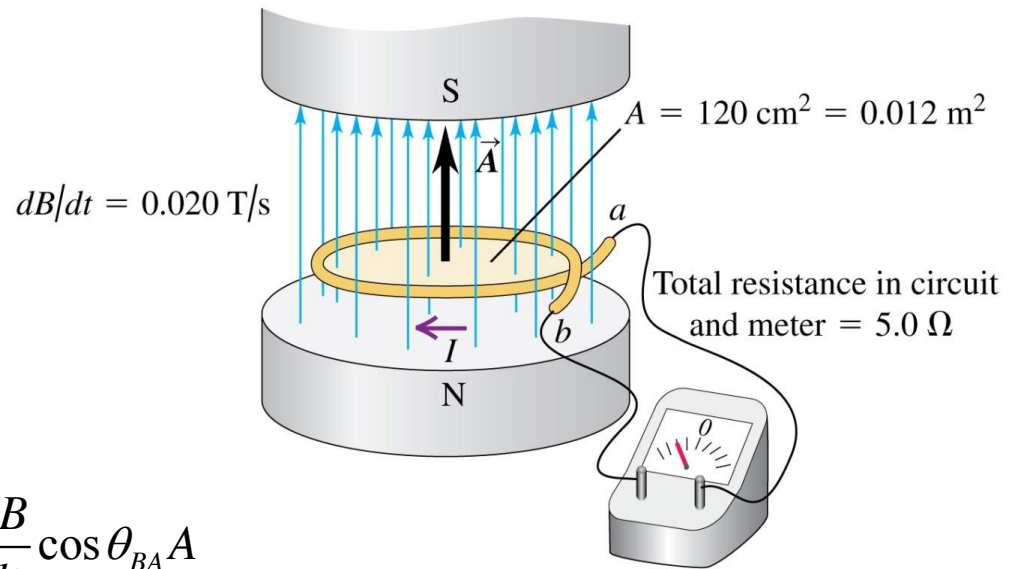
# Determining the direction of the induced emf: Slide 4 of 4



- Flux is negative ( $\Phi_B < 0$ ) ...
- ... and becoming less negative ( $d\Phi_B/dt > 0$ ).
- Induced emf is negative ( $\mathcal{E} < 0$ ).

# Example

- Let's put some numbers in to see how this might work:



$$\mathcal{E} = -\frac{d}{dt} \left[ N \int_{\text{Surface}} \vec{B} \cdot d\vec{A} \right] = -N \frac{dB}{dt} \cos \theta_{BA} A$$

$$= -(1)(0.020 \text{ T/s})(1)(0.012 \text{ m}^2) = 2.4 \times 10^{-4} \frac{\text{Tm}^2}{\text{s}}$$

$$I = \frac{\mathcal{E}}{R} = \frac{2.4 \times 10^{-4} \frac{\text{Tm}^2}{\text{s}}}{5.0 \Omega} = 4.8 \times 10^{-4} \frac{\text{Tm}^2}{\Omega \text{s}}$$

# Unit Check!!!

- Let's put some numbers in to see how this might work:

$$\begin{aligned}\mathcal{E} &= -\frac{d}{dt} \left[ N \int_{\text{Surface}} \vec{B} \cdot d\vec{A} \right] = -N \frac{dB}{dt} \cos \theta_{BA} A \\ &= -(1)(0.020 T/s)(1)(0.012 m^2) = 2.4 \times 10^{-4} \frac{Tm^2}{s} \\ I &= \frac{\mathcal{E}}{R} = \frac{2.4 \times 10^{-4} \frac{Tm^2}{s}}{5.0 \Omega} = 4.8 \times 10^{-4} \frac{Tm^2}{\Omega s}\end{aligned}$$

$$d\vec{F} = Id\vec{l} \times \vec{B} \Rightarrow$$

$$N = AmT \Rightarrow$$

$$T = \frac{N}{Am}$$

$$V = IR \Rightarrow$$

$$\frac{Nm}{C} = A\Omega \Rightarrow$$

$$\Omega = \frac{Nm}{AC}$$

$$\Rightarrow \frac{Tm^2}{\Omega s} = \frac{\frac{N}{Am} m^2}{\frac{Nm}{AC} s} = \frac{C}{s} = A$$

# Faraday's law for a coil

- A commercial alternator uses many loops of wire wound around a barrel-like structure called an armature.
- The resulting induced emf is far larger than would be possible with a single loop of wire.
- If a coil has  $N$  identical turns and if the flux varies at the same rate through each turn, total emf is:

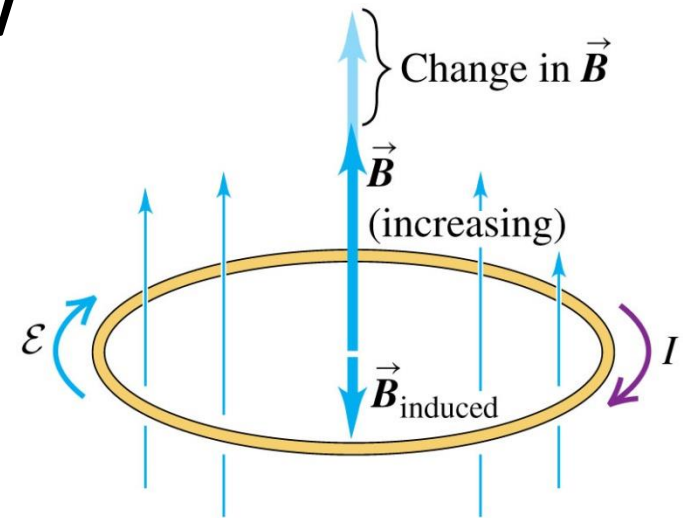


$$\mathcal{E} = -N \frac{d\Phi_B}{dt}$$

# Lenz's Law

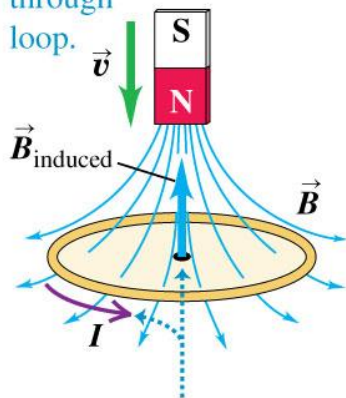
- To get the direction of the induced EMF (and thus, the current in a circuit), remember:

$$\mathcal{E} = -\frac{d}{dt}\Phi_B$$



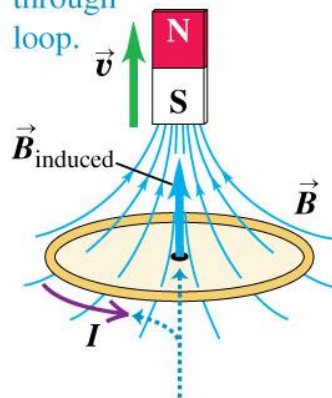
© 2012 Pearson Education, Inc.

- (a) Motion of magnet causes *increasing downward flux* through loop.

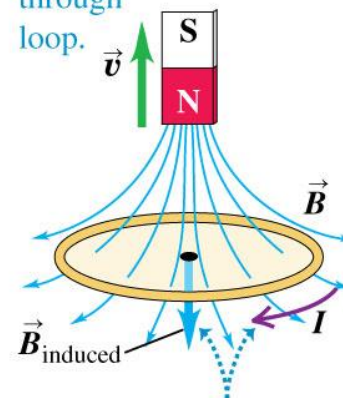


The induced magnetic field is *upward* to oppose the flux change. To produce this induced field, the induced current must be *counterclockwise* as seen from above the loop.

- (b) Motion of magnet causes *decreasing upward flux* through loop.

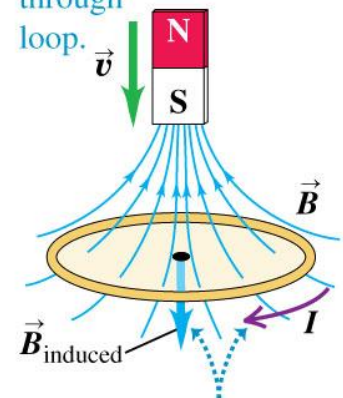


- (c) Motion of magnet causes *decreasing downward flux* through loop.



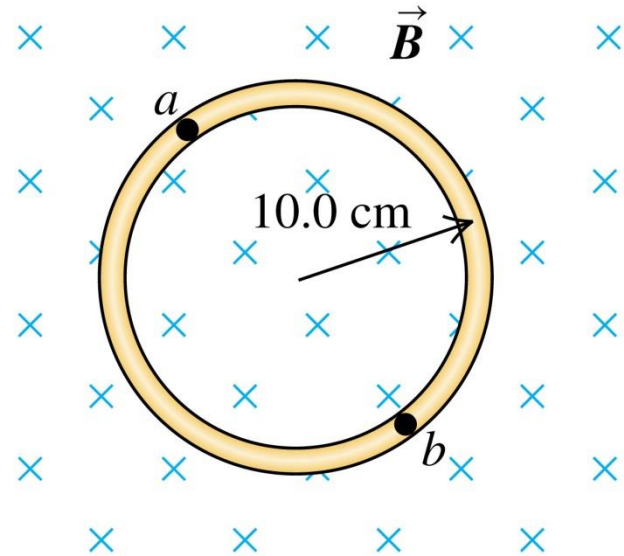
The induced magnetic field is *downward* to oppose the flux change. To produce this induced field, the induced current must be *clockwise* as seen from above the loop.

- (d) Motion of magnet causes *increasing upward flux* through loop.



# CPS 32-1

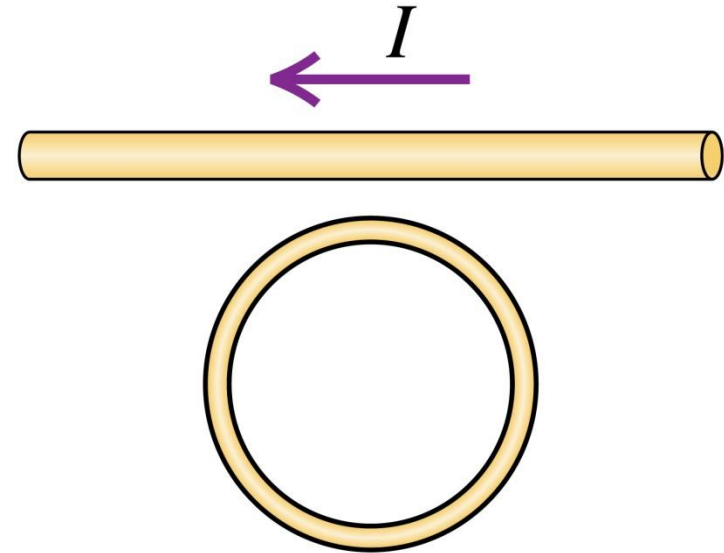
A circular loop of wire is in a region of spatially uniform magnetic field. The magnetic field is directed into the plane of the figure. If the magnetic field magnitude is *decreasing*,



- A. the induced emf is clockwise.
- B. the induced emf is counterclockwise.
- C. the induced emf is zero.
- D. The answer depends on the strength of the field.

# CPS 32-2

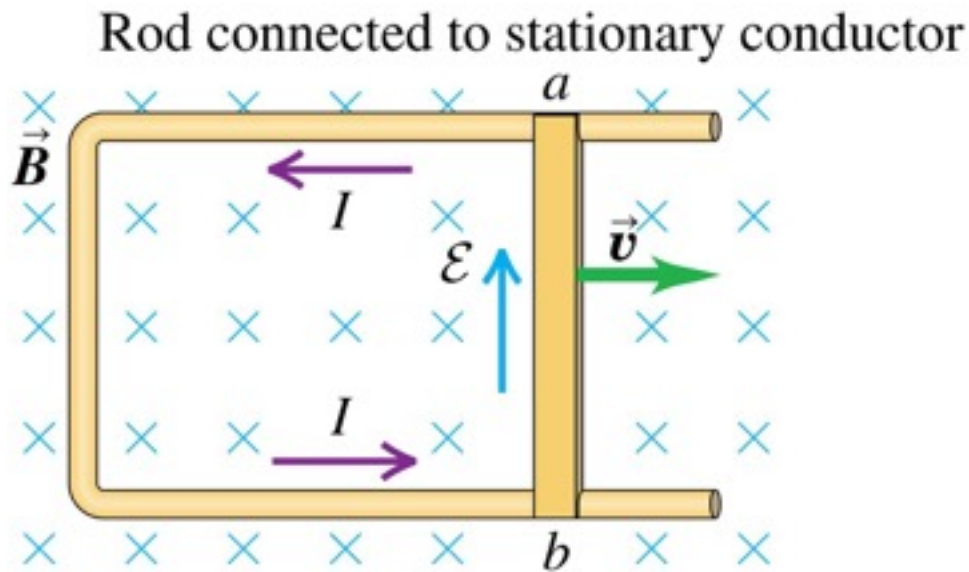
A circular loop of wire is placed next to a long straight wire. The current  $I$  in the long straight wire is increasing. What current does this induce in the circular loop?



- A. a clockwise current
- B. a counterclockwise current
- C. zero current
- D. not enough information given to decide

# Motional electromotive force

- When a conducting rod moves perpendicular to a uniform magnetic field, there is a **motional emf** induced.



The motional emf  $\mathcal{E}$  in the moving rod creates an electric field in the stationary conductor.

Motional emf,  
conductor length and velocity  
perpendicular to uniform  $\vec{B}$

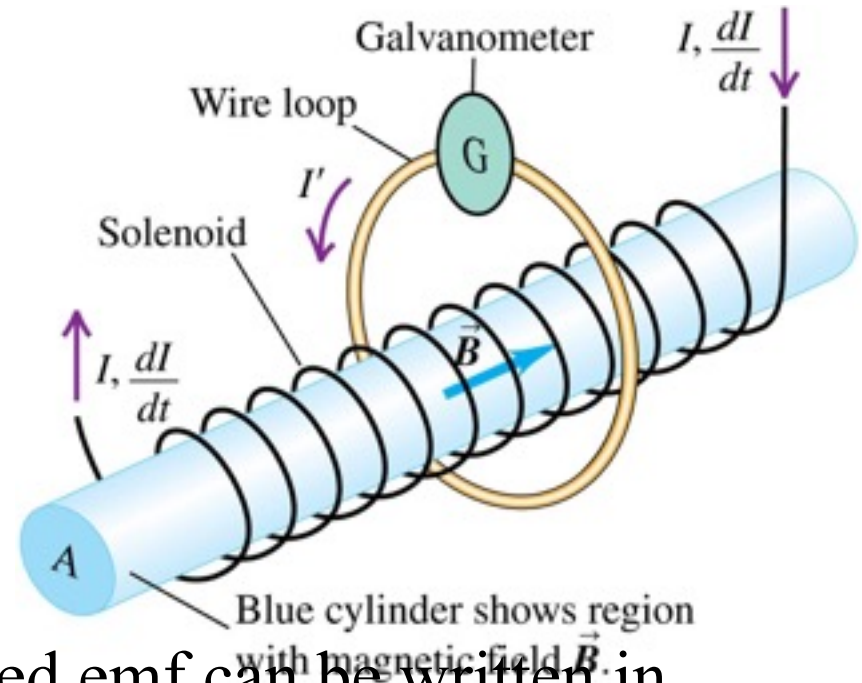
$$\mathcal{E} = vBL$$

Conductor speed  
Conductor length  
Magnitude of uniform magnetic field



# Induced electric fields

- A long, thin solenoid is encircled by a circular conducting loop.
- Electric field in the loop is what must drive the current.
- When the solenoid current  $I$  changes with time, the magnetic flux also changes, and the induced emf can be written in terms of **induced electric field**:



Faraday's law  
for a stationary  
integration path:

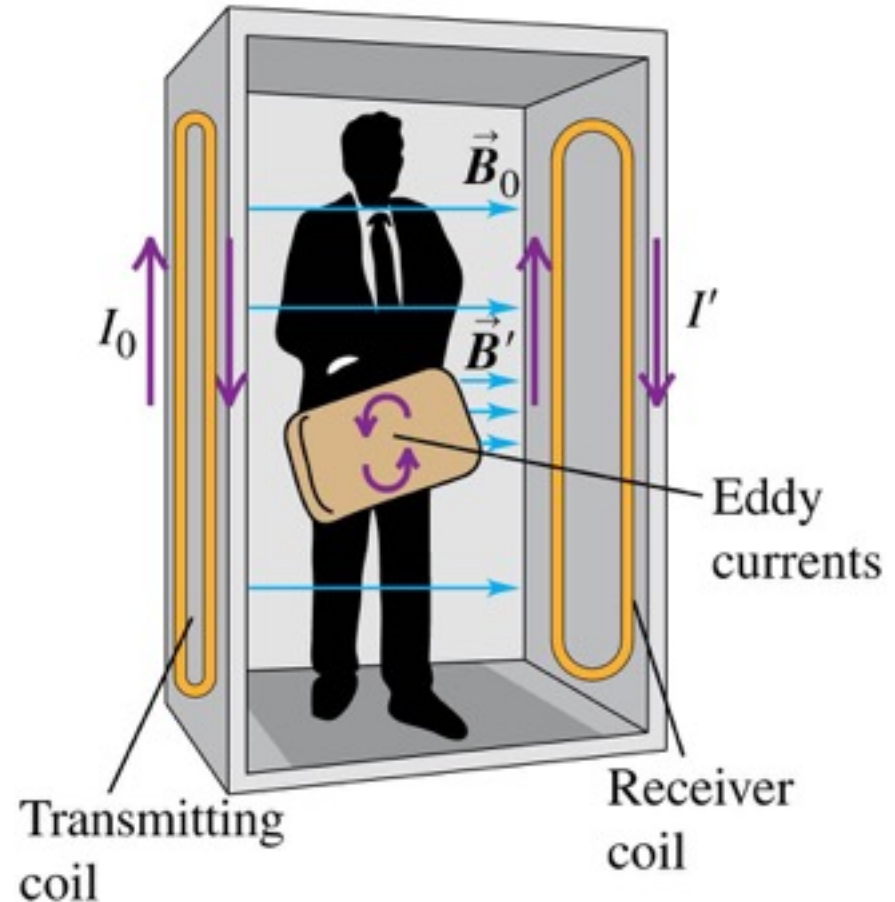
Line integral of electric field around path

$$\oint \vec{E} \cdot d\vec{l} = - \frac{d\Phi_B}{dt}$$

Negative of the time  
rate of change of  
magnetic flux through path

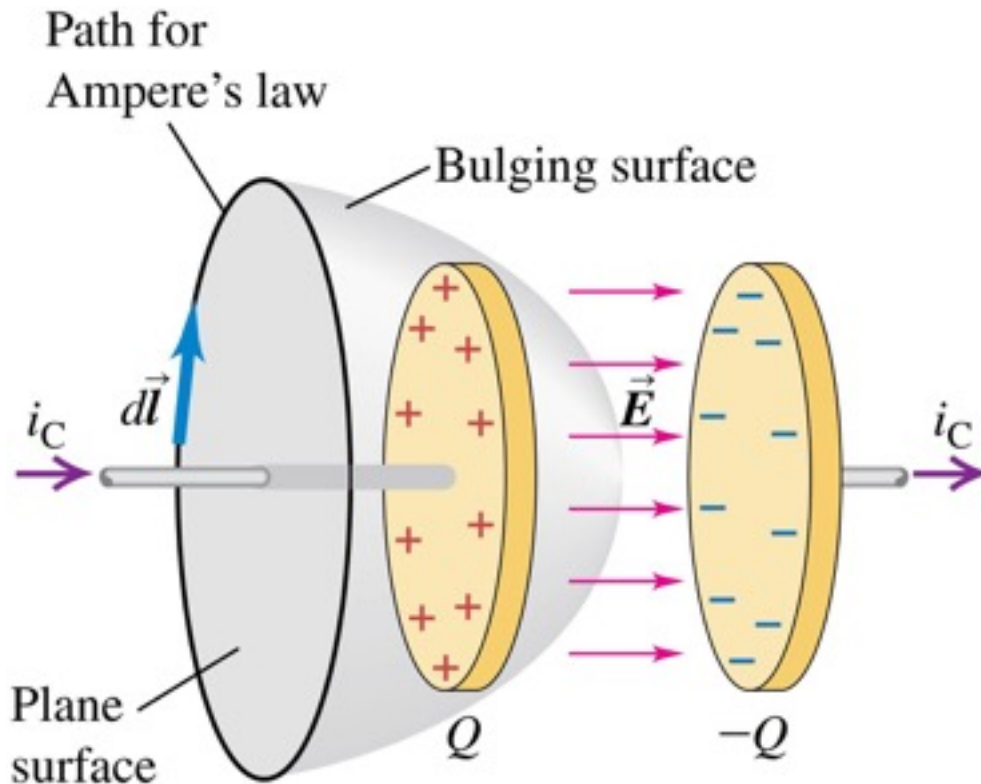
# Eddy currents

- When a piece of metal moves through a magnetic field or is located in a changing magnetic field, **eddy currents** of electric current are induced.
- The metal detectors used at airport security checkpoints operate by detecting eddy currents induced in metallic objects.



# Displacement current

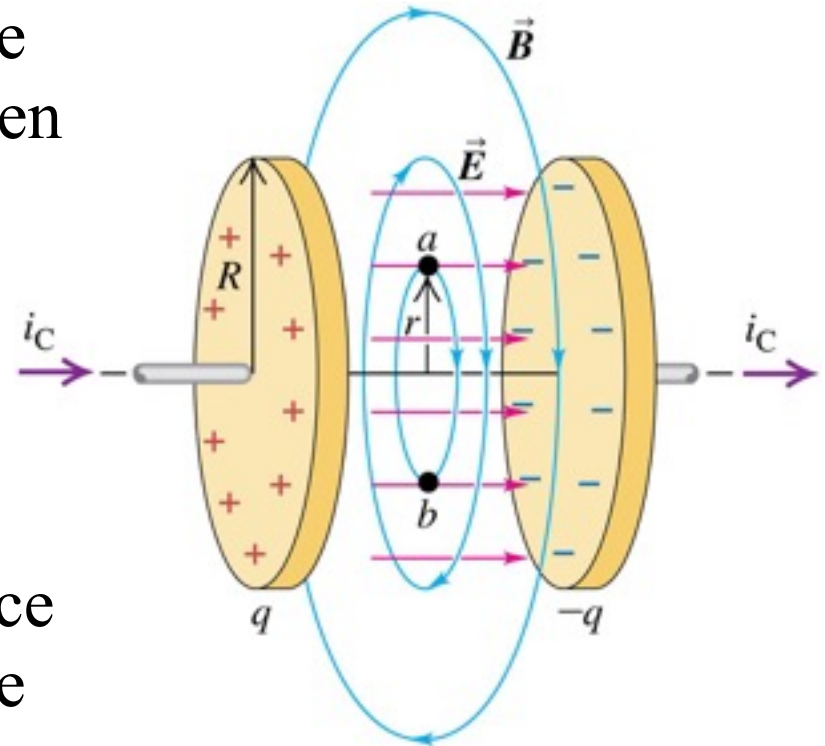
- Ampere's law is *incomplete*, as can be shown by considering the process of charging a capacitor, as shown.



- For the plane circular area bounded by the circle,  $I_{\text{encl}}$  is the current  $i_C$  in the left conductor.
- But the surface that bulges out to the right is bounded by the same circle, and the current through that surface is zero.
- This leads to a contradiction.

# Displacement current

- When a capacitor is charging, the electric field is increasing between the plates.
- We can define a fictitious **displacement current**  $i_D$  in the region between the plates.
- This can be regarded as the source of the magnetic field between the plates.



Displacement current through an area  $\dots \rightarrow i_D = \epsilon \frac{d\Phi_E}{dt}$  Time rate of change of electric flux through area

$\dots \rightarrow$  Permittivity of material in area

# Maxwell's equations of electromagnetism

- All the relationships between electric and magnetic fields and their sources are summarized by four equations, called **Maxwell's equations**.
- The first Maxwell equation is Gauss's law for electric fields from Chapter 22:

Gauss's law for  $\vec{E}$ :

Flux of electric field through a closed surface

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{\text{encl}}}{\epsilon_0}$$

Charge enclosed by surface

Electric constant

- The fields from Chapter 27:

Gauss's law for  $\vec{B}$ :

Flux of magnetic field through any closed surface ...

$$\oint \vec{B} \cdot d\vec{A} = 0$$

... equals zero.

# Maxwell's equations of electromagnetism

- The third Maxwell equation is this chapter's formulation of Faraday's law:

Faraday's law  
for a stationary  
integration path:

Line integral of electric field around path

$$\oint \vec{E} \cdot d\vec{l} = - \frac{d\Phi_B}{dt}$$

Negative of the time  
rate of change of  
magnetic flux through path

- The fourth Maxwell equation is this chapter's formulation of Ampere's law with displacement current:

Ampere's law  
for a stationary  
integration path:

Line integral of magnetic  
field around path

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \left( i_C + \epsilon_0 \frac{d\Phi_E}{dt} \right)_{\text{encl}}$$

Electric  
constant

Time rate of change of  
electric flux through path

Magnetic  
constant

Conduction current  
through path

Displacement current  
through path

# Maxwell's equations in empty space

- There is a remarkable symmetry in Maxwell's equations.
- In empty space where there is no charge, the first two equations are identical in form.
- The third equation says that a changing magnetic flux creates an electric field, and the fourth says that a changing electric flux creates a magnetic field.

In empty space there are no charges, so the fluxes of  $\vec{E}$  and  $\vec{B}$  through any closed surface are equal to zero.

$$\oint \vec{E} \cdot d\vec{A} = 0$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

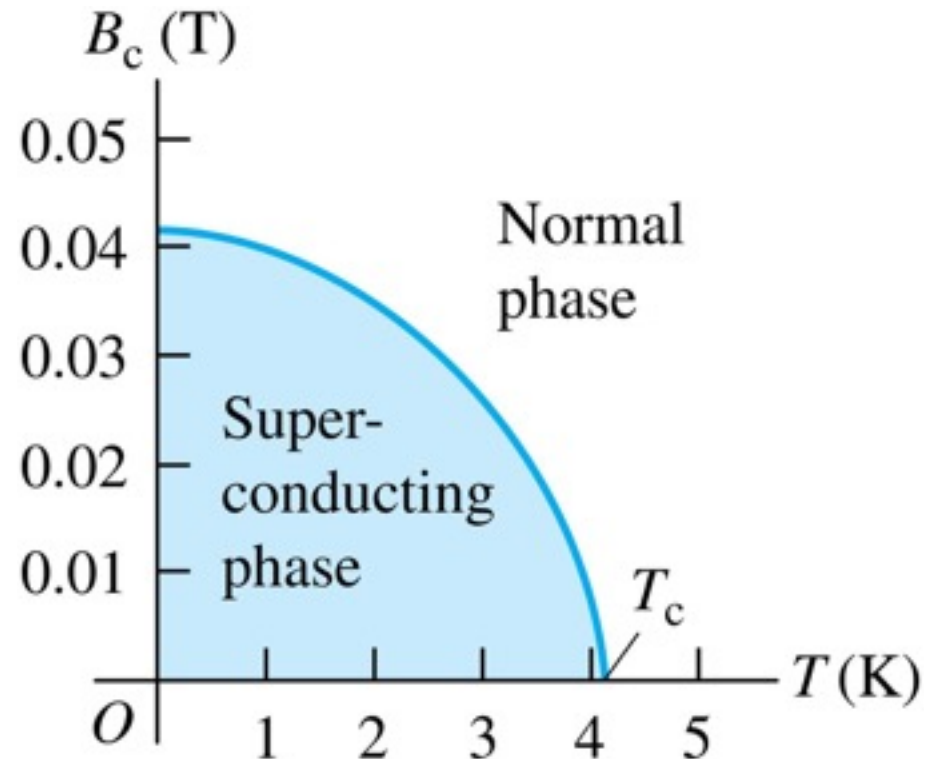
$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0\epsilon_0 \frac{d\Phi_E}{dt}$$

In empty space there are no conduction currents, so the line integrals of  $\vec{E}$  and  $\vec{B}$  around any closed path are related to the rate of change of flux of the other field.

# Superconductivity in a magnetic field

- When a superconductor is cooled below its critical temperature  $T_c$ , it loses all electrical resistance.
- For any superconducting material the critical temperature  $T_c$  changes when the material is placed in an externally produced magnetic field.
- Shown is this dependence for mercury.
- As the external field magnitude increases, the superconducting transition occurs at a lower and lower temperature.

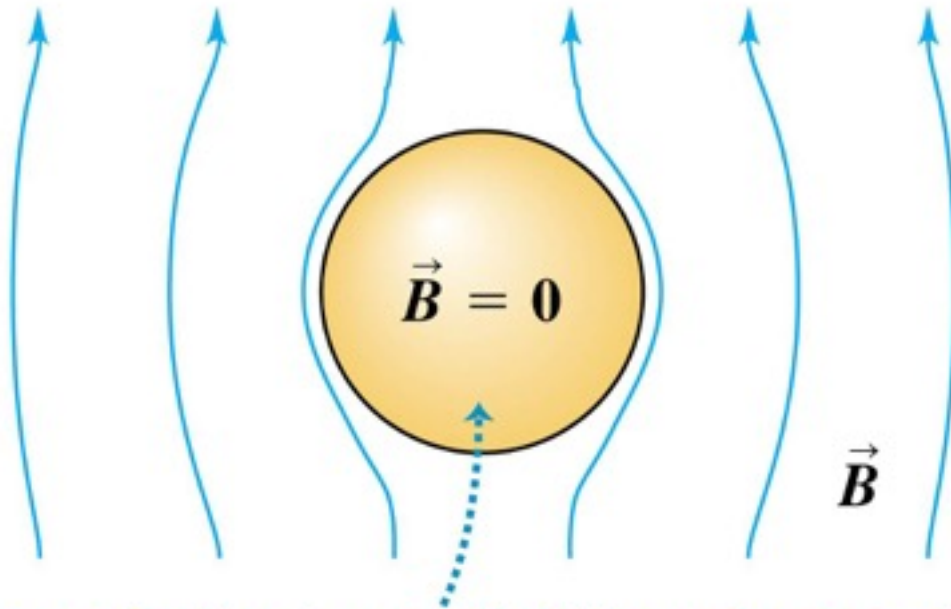




# The Meissner effect

---

- If we place a superconducting material in a uniform applied magnetic field, and then lower the temperature until the superconducting transition occurs, then all of the magnetic flux is expelled from the superconductor.
- The expulsion of magnetic flux is called the **Meissner effect**.



Magnetic flux is expelled from the material, and the field inside it is zero (Meissner effect).